

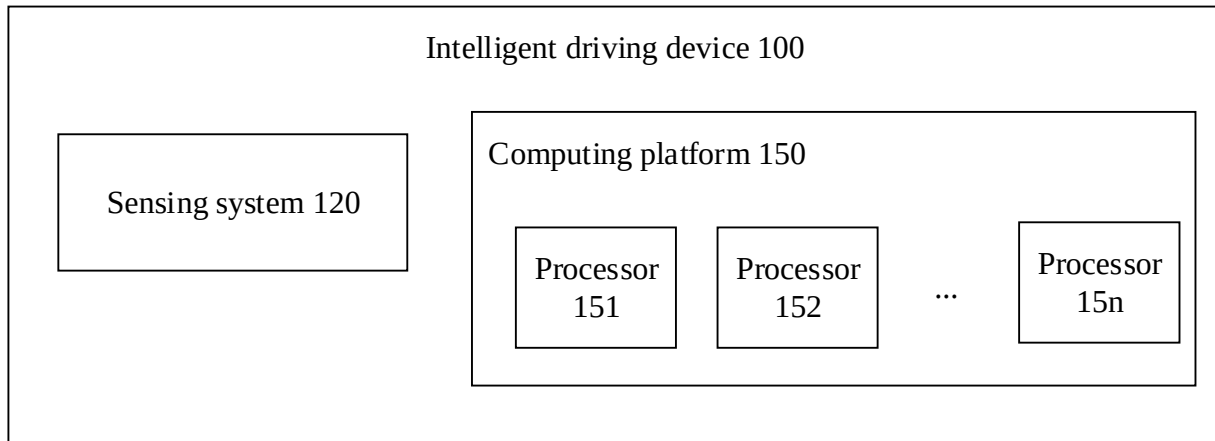


FIG. 1

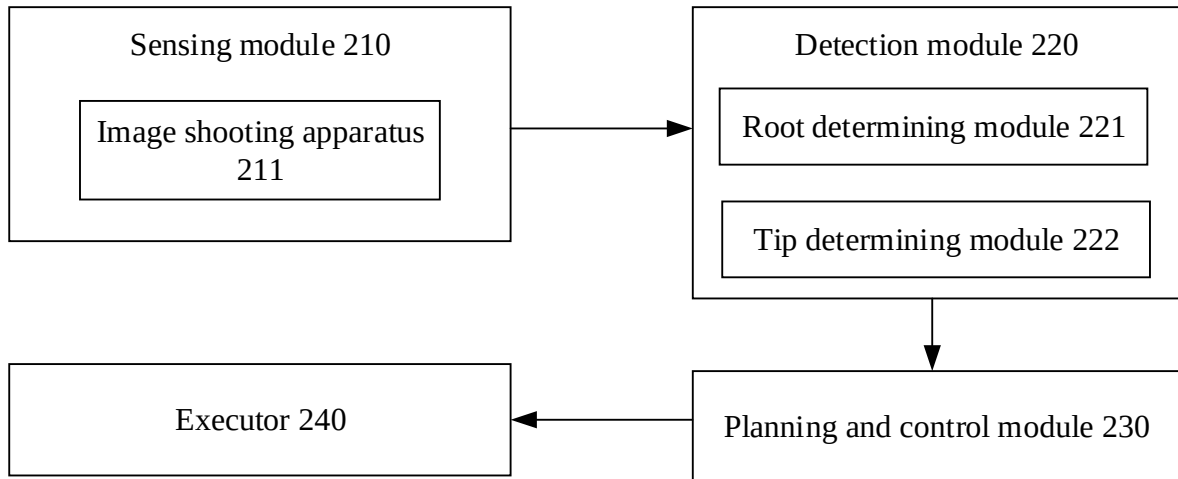


FIG. 2

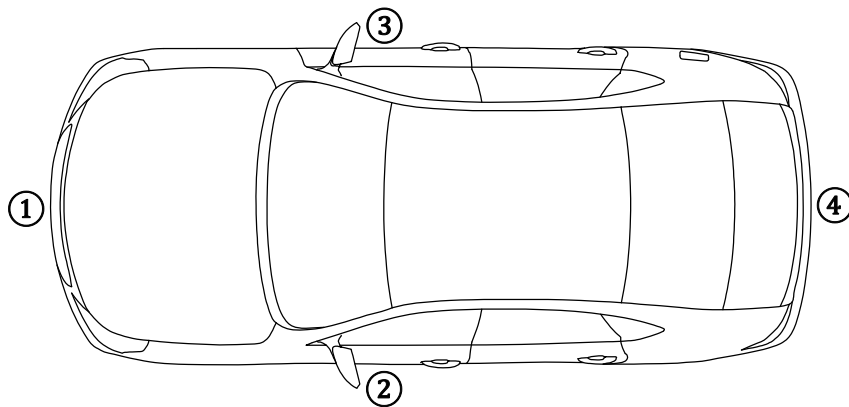


FIG. 3

400

S410: Obtain a first image and a second image, where the first image and the second image are images that are captured at different angles and that include a first rear-view mirror on a target vehicle



S420: Determine a location of the first rear-view mirror on the target vehicle based on the first image and the second image



S430: Control an intelligent driving device based on the location of the first rear-view mirror on the target vehicle

FIG. 4

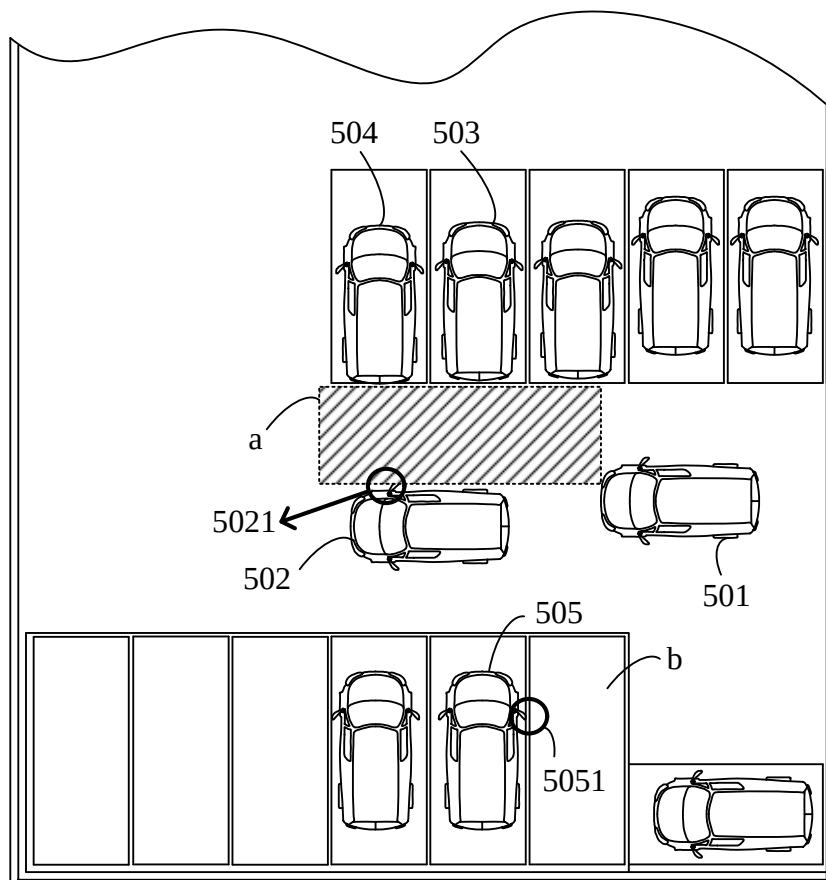
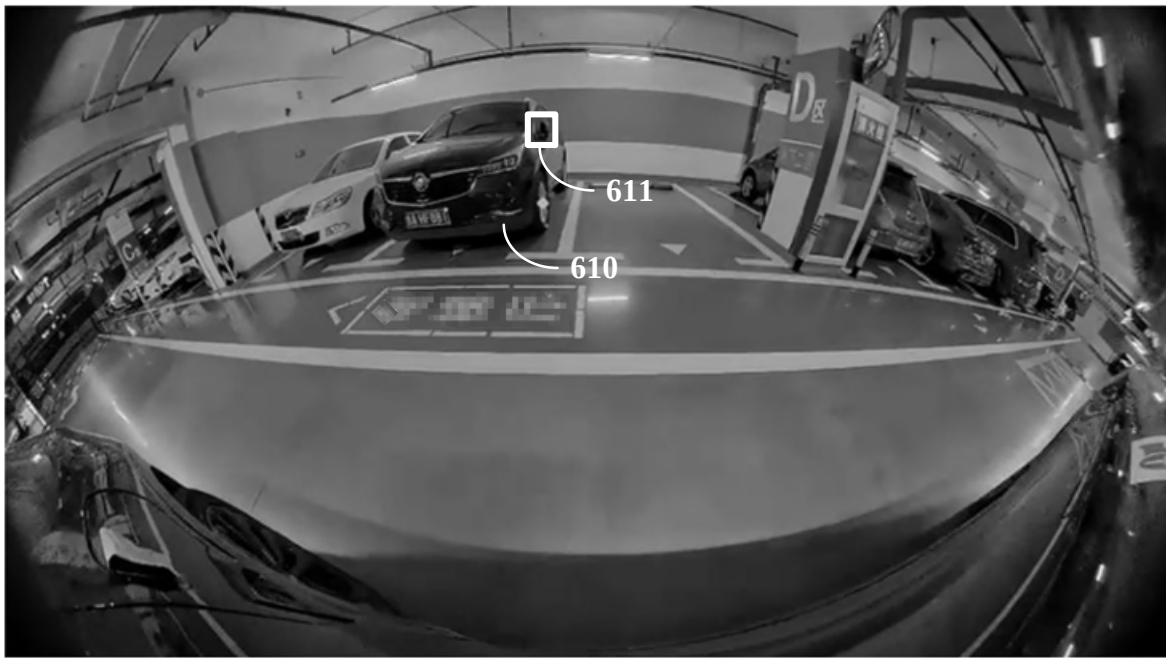
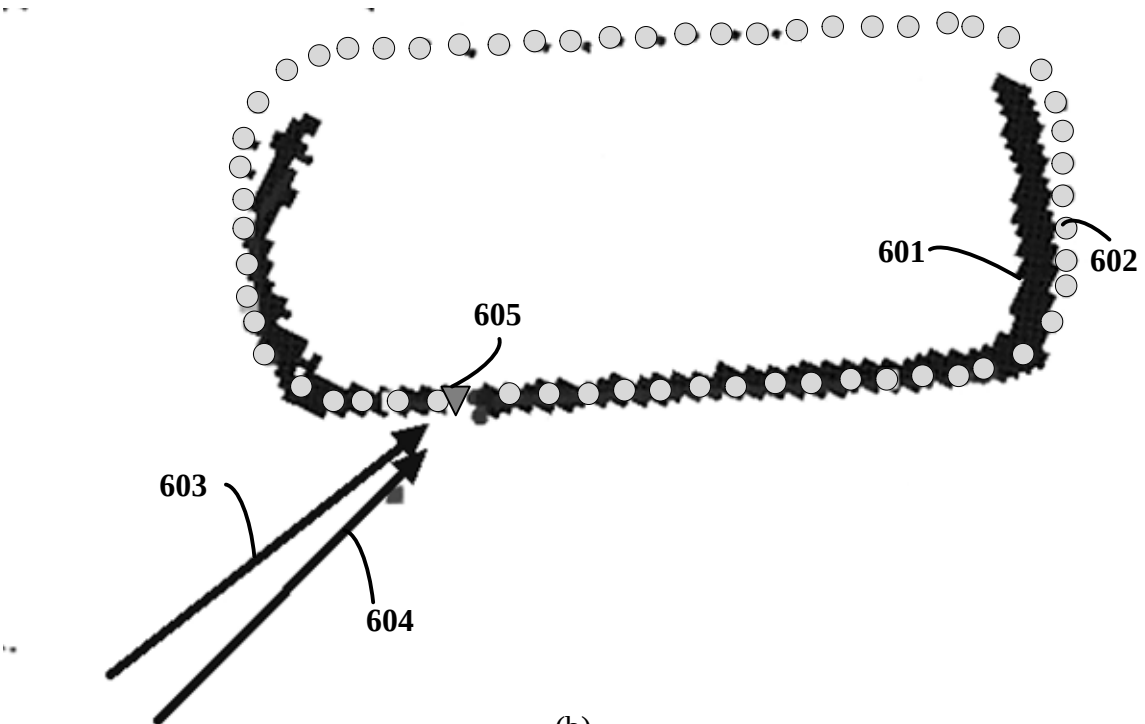


FIG. 5

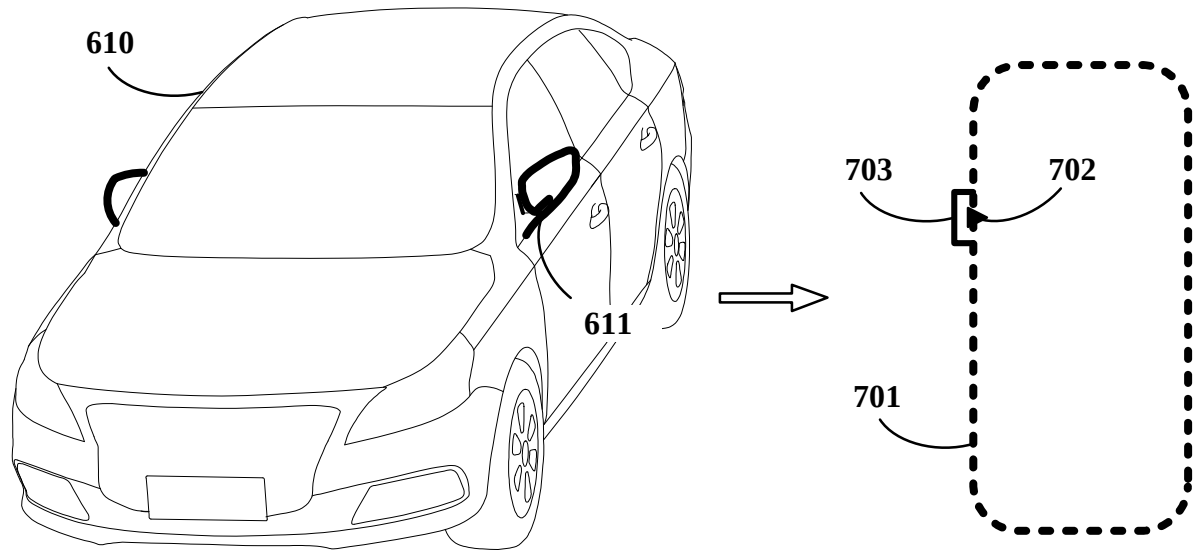


(a)

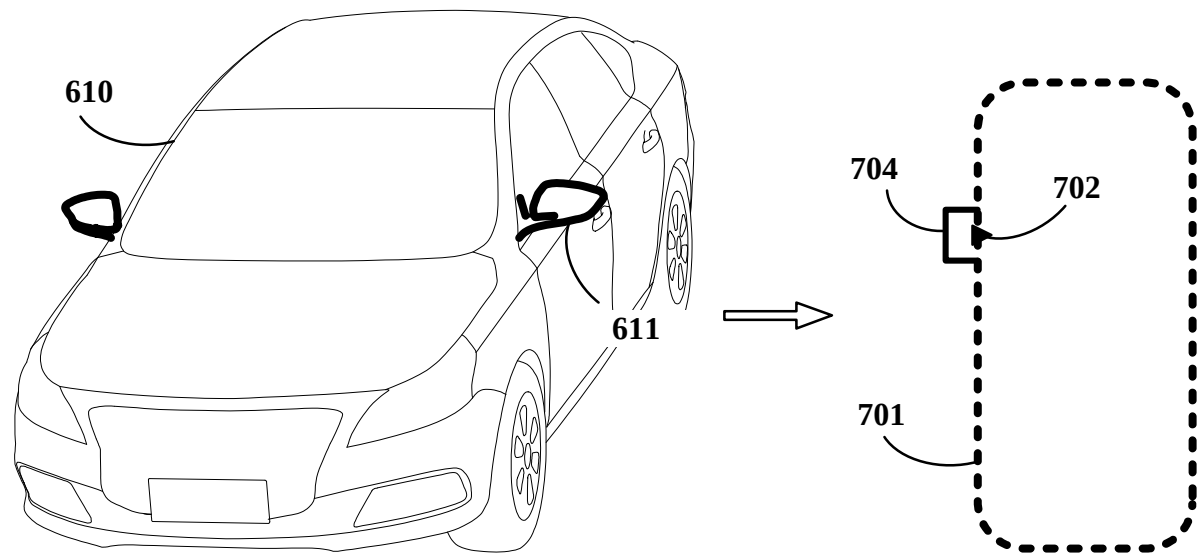


(b)

FIG. 6

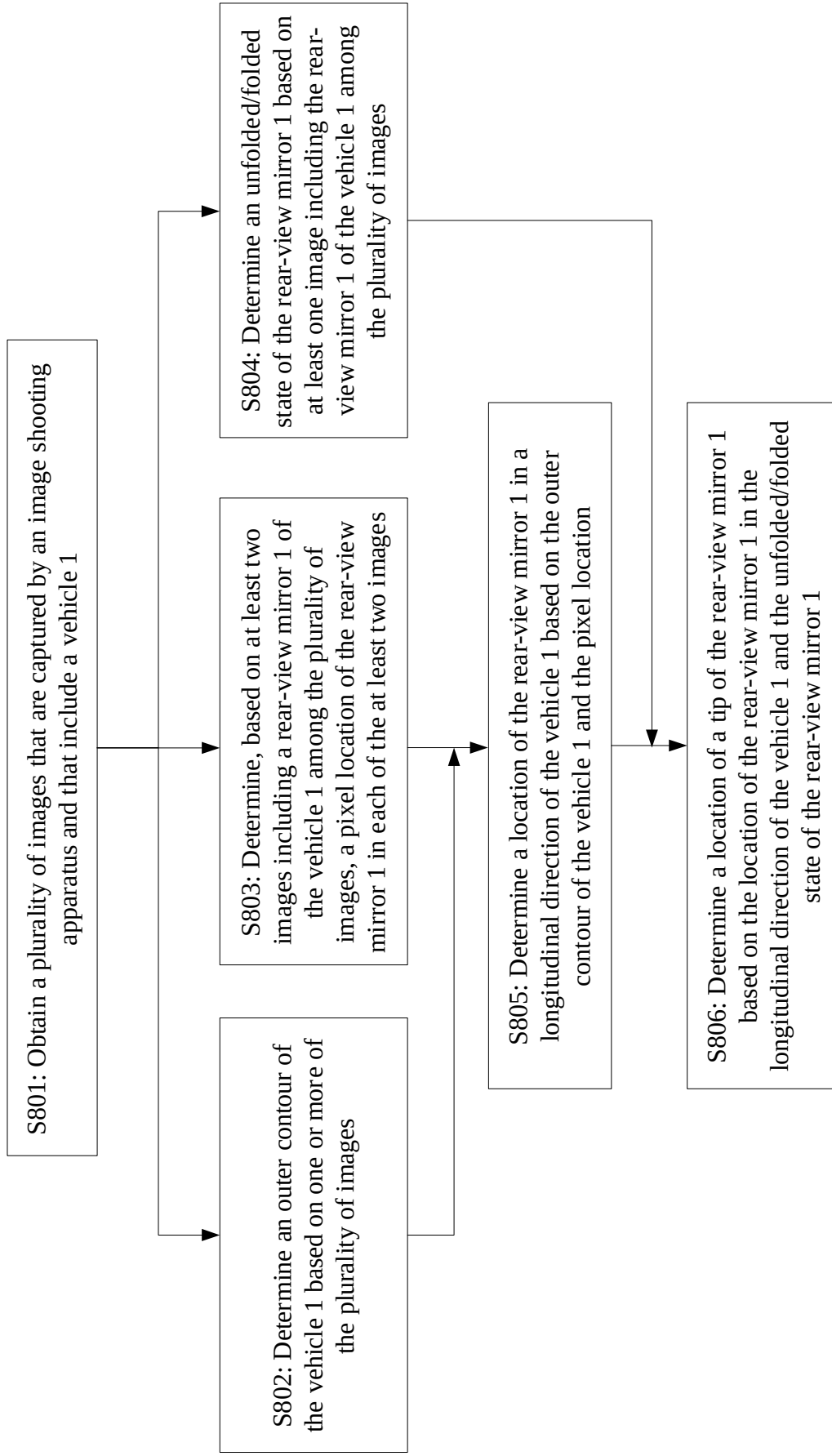


(a)



(b)

FIG. 7

800**FIG. 8**

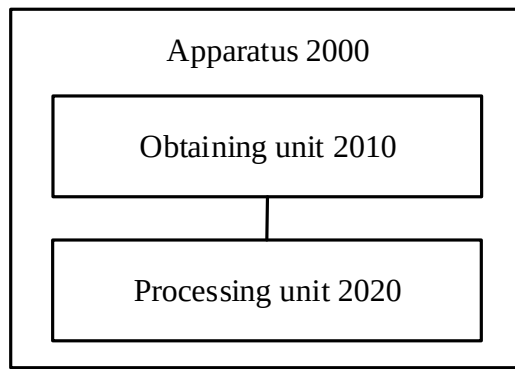


FIG. 9

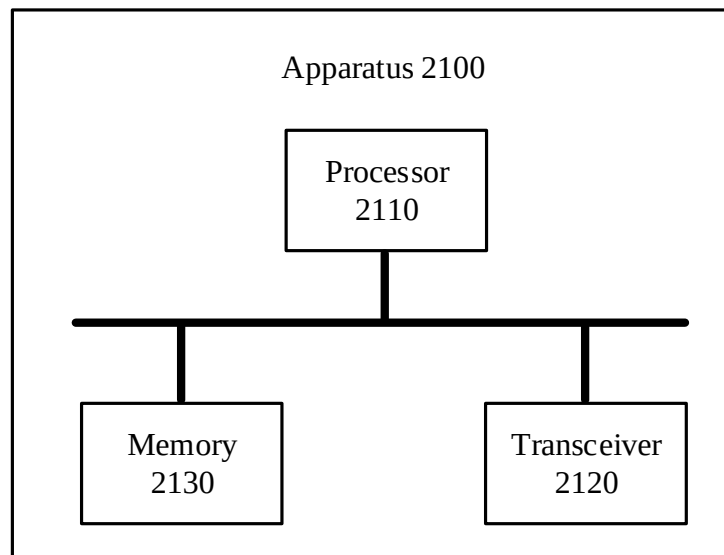


FIG. 10