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(71) Applicant: **BRIGHT MACHINES, INC.** [US/US]; 2445
16th Street, San Francisco, California 94103 (US).

(72) Inventors: **GALLO, Emmanuel**; 2445 16th Street, San
Francisco, California 94103 (US). **SHAFIEKHANI, Ali**;
2445 16th Street, San Francisco, California 94103 (US).
PANSODTEE, Pattawong; 2445 16th Street, San Francis-
co, California 94103 (US). **CLARK, Barrett Christopher**;

2445 16th Street, San Francisco, California 94103 (US).
PAPPOPPULA, Murali; 2445 16th Street, San Francisco,
California 94103 (US).

(74) Agent: **SZEPESI, Judith**; 99 Almaden Boulevard, Suite
575, San Jose, California 95113 (US).

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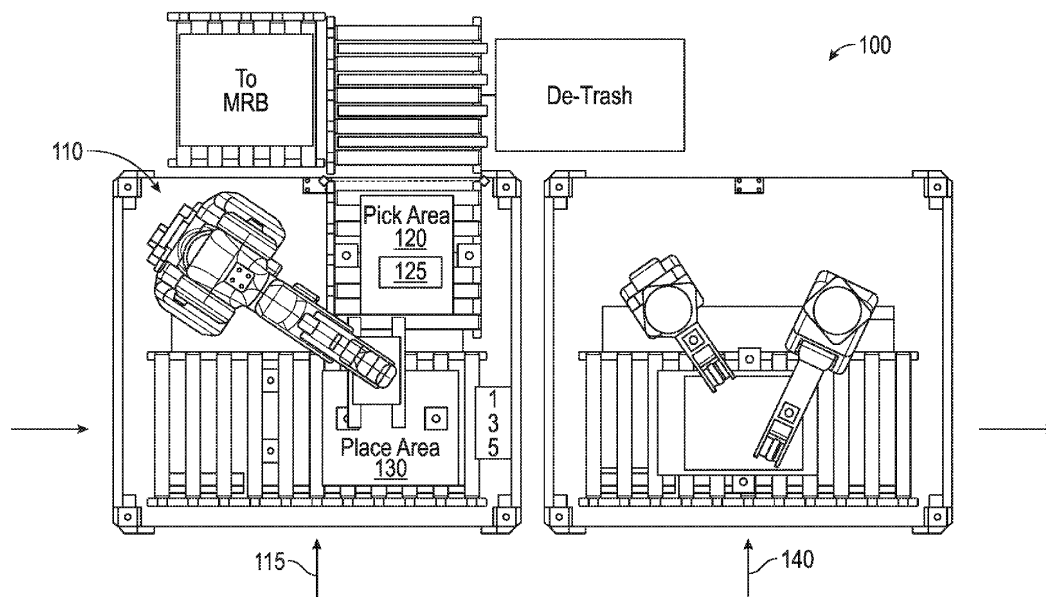


FIG. 1A

(57) Abstract: An assembly operation and a robotic cell for inserting a part into a chassis comprising calculating a first part pose estimation for the part in the pick area, picking up the part, and moving the part above the chassis, calculating a second part pose estimation for the part being held by the robot arm above the chassis, and correcting the second part pose estimation using a chassis pose estimation. The operation further comprising inserting the part into the chassis, wherein the multi-stage verification ensures that a high value part is not damaged in the assembly.

[Continued on next page]

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