

AbstractMETHOD FOR THE CONTROL, BY A SUPERVISING SERVER, OF THE
MOVEMENT OF A FLEET OF AUTONOMOUSLY GUIDED VEHICLES

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The invention concerns a method for the control, by a supervising server, of the movement of a fleet of autonomously guided vehicles in a movement area equipped with a plurality of wireless Wi-Fi access points each comprising at least one geolocation means and a Wi-Fi communication module, said method comprising a

10 step of recording coordinates of these access points and steps of changing access point, which are executed by each of the autonomously guided vehicles, said steps consisting of controlling the disconnection of the Wi-Fi communication module from the active access point and reconnection to the SSID_i access point for which the coordinates recorded in the database are the closest of the coordinates determined

15 by the geolocation means.