

ABSTRACT

Disclosed are a method and a device for virtually controlling a logistics robot, the method comprising the steps of: collecting logistics robot information and load information; configuring a first virtual area corresponding to an actual occupied space of a logistics robot; determining whether an operation control condition of the logistics robot is satisfied, on the basis of a positional relationship between the first virtual area and a second virtual area configured to correspond to an actual occupied space of another object; and outputting a control signal for controlling an operation of the logistics robot.

Fig.4