Claims

1. An ultrasonic microscope for inspecting an object,
wherein the ultrasonic microscope comprises:
an object holder configured to hold the object in an object region;
a scan head movable relative to the object region;
a first transducer supported by the scan head,
wherein the first transducer is configured to emit first acoustic pulses along an emission direction and to focus the first acoustic pulses in a focal point, and
wherein the first transducer is further configured to detect second acoustic pulses emerging from the object and to output a first detection signal representing the second acoustic pulses detected by the first transducer;
a first actuator configured to move the first transducer relative to the scan head along a vertical direction which is essentially parallel to the emission direction; and
a controller configured to:
- control vertical movement of the first transducer relative to the scan head provided by the first actuator based on the first detection signal– control emission of the first acoustic pulses by the first transducer,
– determine a distance value representing a distance between the first transducer and the object based on the first detection signal, and
– control the vertical movement of the first transducer relative to the scan head provided by the first actuator based on the determined distance value.

2. The ultrasonic microscope according to claim 1,
wherein the controller is further configured to:
– control the vertical movement of the first transducer relative to the scan head provided by the first actuator so that the distance between the first transducer and the object approaches a predefined working distance.

3. The ultrasonic microscope according to claim 1,
wherein the controller is further configured to:
– determine a defocusing value representing a distance between the focal point and a location of interest of the object based on the determined distance value, and
– control the vertical movement of the first transducer relative to the scan head provided by the first actuator based on the defocusing value.

4. The ultrasonic microscope according to any one of claims 1 to 3, further comprising:
a scan-head positioning device configured to move the scan head relative to the object holder in a lateral plane which is essentially orthogonal to the vertical direction.

5. The ultrasonic microscope according to claim 4,
wherein the controller is further configured to:
– control the scan-head positioning device so that the scan head is positioned at a plurality of positions,
– perform, each time the scan head is positioned at one of the plurality of positions, causing the first transducer to emit at least one of the first acoustic pulses, detecting at least one of the second acoustic pulses and outputting the first detection signal,
– store the first detection signals or values derived from the first detection signals in association with the plurality of positions, and
– control the vertical movement of the first transducer relative to the scan head provided by the first actuator based on a set of the stored first detection signals or derived values.

6. The ultrasonic microscope according to claim 4, further comprising:
a second actuator configured to move the first transducer relative to the scan head along a lateral direction which is essentially orthogonal to the vertical direction;
wherein the scan-head positioning device is configured to displace the scan head at most by a first displacement value;

wherein the second actuator is configured to displace the first transducer relative to the scan head at most by a second displacement value; and

wherein a ratio of the first displacement value to the second displacement value is at least 10.

7. An ultrasonic microscope for inspecting an object,

wherein the ultrasonic microscope comprises:

an object holder configured to hold the object in an object region;

a scan head movable relative to the object region;

a first transducer supported by the scan head,

wherein the first transducer is configured to emit first acoustic pulses along an emission direction and to focus the first acoustic pulses in a focal point, and

wherein the first transducer is further configured to detect second acoustic pulses emerging from the object and to output a first detection signal representing the second acoustic pulses detected by the first transducer;

a first actuator configured to move the first transducer relative to the scan head along a vertical direction which is essentially parallel to the emission direction;

a controller configured to control vertical movement of the first transducer relative to the scan head provided by the first actuator based on the first detection signal; and

a second transducer supported by the scan head so that the object region is located between the first transducer and the second transducer;

wherein the second transducer is configured to detect the second acoustic pulses emerging from the object and to output a second detection signal representing the second acoustic pulses detected by the second transducer.

8. The ultrasonic microscope according to claim 7, further comprising:

a second actuator configured to move the first transducer relative to the scan head along a lateral direction which is essentially orthogonal to the vertical direction; and

wherein the controller is further configured to control lateral movement of the first transducer relative to the scan head provided by the second actuator based on the second detection signal.

9. The ultrasonic microscope according to claim 8, wherein the controller is configured to control the lateral movement of the first transducer relative to the scan head provided by the second actuator so that the first transducer is aligned with the second transducer along the lateral direction.

10. The ultrasonic microscope according to claim 9, wherein the controller is configured to control the lateral movement of the first transducer relative to the scan head provided by the second actuator so that an intensity of the second detection signal is maximized.

11. The ultrasonic microscope according to claim 9 or 10, wherein the controller is configured to calculate a frequency-domain representation of the second detection signal and to control the lateral movement of the first transducer relative to the scan head provided by the second actuator based on the frequency-domain representation of the second detection signal.

12. The ultrasonic microscope according to any one of claims 7 to 11, further comprising:
a third actuator configured to move the second transducer relative to the scan head along the vertical direction.

13. The ultrasonic microscope according to claim 12, wherein the controller is further configured to control vertical movement of the second transducer relative to the scan head provided by the third actuator based on the first detection signal.

14. The ultrasonic microscope according to claim 13, wherein the controller is configured to calculate a control signal for controlling the vertical movement of the first transducer relative to the scan head provided by the first actuator based the first detection signal,
wherein the controller is further configured to control vertical movement of the second transducer relative to the scan head provided by the third actuator based on the control signal.

15. The ultrasonic microscope according to any one of claims 12 to 14, wherein the controller is further configured to control vertical movement of the second transducer relative to the scan head provided by the third actuator based on the second detection signal.

16. The ultrasonic microscope according to claim 15, wherein the controller is configured to control the vertical movement of the second transducer relative to the scan head provided by the third actuator so that an intensity of the second detection signal is maximized.

17. The ultrasonic microscope according to claim 15 or 16, wherein the controller is configured to calculate a frequency-domain representation of the second detection signal and to control the vertical movement of the second transducer relative to the scan head provided by the third actuator based on the frequency-domain representation of the second detection signal.

18. The ultrasonic microscope according to any one of claims 1 to 17, further comprising:
a fourth actuator configured to move the object holder relative to the scan head along the vertical direction; and
wherein the controller is further configured to control the fourth actuator so that the object can be variably positioned relative to the focal point in the vertical direction.

19. The ultrasonic microscope according to any one of claims 1 to 18,
wherein the first transducer is disposed above the object region.

20. The ultrasonic microscope according to any one of claims 1 to 19,
wherein the first transducer is configured to emit the first acoustic pulses so that the first acoustic pulses have an acoustic frequency above a threshold frequency,
wherein the threshold frequency is selected from a group of threshold frequencies and the group of threshold frequencies comprises 10 MHz and 15 MHz.