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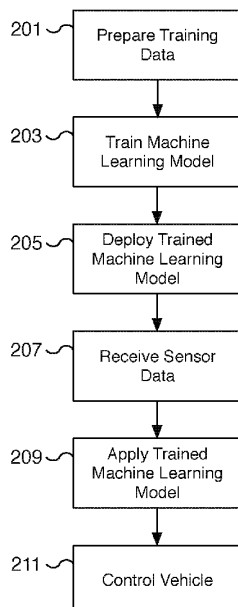


FIG. 2

(57) Abstract: A processor coupled to memory is configured to receive image data based on an image captured by a camera of a vehicle. The image data is used as a basis of an input to a trained machine learning model trained to predict a three-dimensional trajectory of a machine learning feature. The three-dimensional trajectory of the machine learning feature is provided for automatically controlling the vehicle.

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