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(54) Title: FLYING LEAD WORKOVER INTERFACE SYSTEM

(57) Abstract

Flying lead hydraulic (60) and electrical (62) umbilical arrangements are disclosed for control of a subsea christmas tree (400) for production and workover operations. Alternative arrangements for deep water ROV arrangements for a conventional christmas tree (400) are illustrated in Figures 2A, 2B and in Figures 3A, 3B, and 3C. Alternative arrangements for a horizontal christmas tree (500) are illustrated in Figures 5, 6, and 7.

