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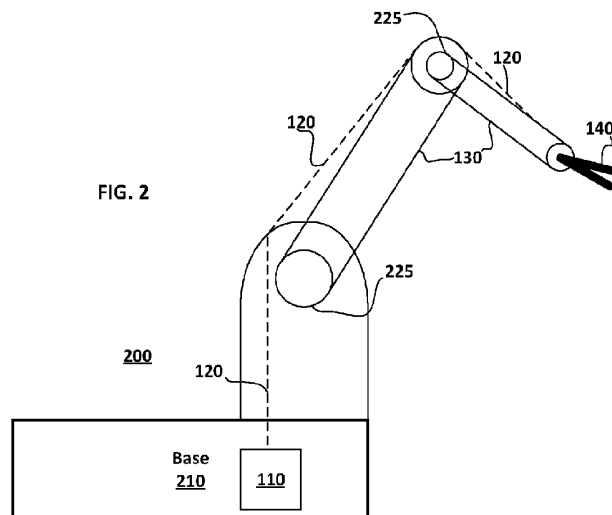
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(54) Title: SOFTWARE COMPENSATED ROBOTICS



(57) Abstract: A software compensated robotic system makes use of neural networks and image processing to control operation and/or movement of an end effector. Images are used to compensate for variations in the response of the robotic system to command signals. This compensation allows for the use of components having lower reproducibility, precision and/or accuracy that would otherwise be practical.

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