

METHOD AND SYSTEM FOR DETECTING SIGNAL SOURCES IN A SURVEILLANCE SPACE

FIELD OF THE INVENTION

This invention relates to surveillance systems, and more specifically to methods for determining parameters of a source of electromagnetic radiation.

BACKGROUND OF THE INVENTION

5 Surveillance systems are used for continuous detection and tracking of signals emitted by a signal source in a region of space under surveillance. The signals are received by an antenna array directed towards the space under surveillance and processed to determine signal parameters such as frequency and azimuth direction. The signal source may be an active stationary or moving transmitter that transmits EM
10 radiation, such as radio transmitter, wireless telephone and so on. It may also be a passive source corresponding to a reflected signal, such as a signal that originates from an active transmitter and is picked up and subsequently reflected by a radar antenna or any other radiation source. So far as the present invention is concerned, it is immaterial whether the signal source is active or passive. The signals received by the receiving
15 antenna array are processed so as to distinguish genuine signals from noise and to determine the frequency, amplitude and direction of each detected signal.

A problem with hitherto proposed detection systems is that detection of weak signals is difficult, thus imposing severe restrictions on the maximum distance from the antenna array for which signal detection is possible. Moreover, known systems are
20 unable to distinguish between signals of identical frequency originating from signal sources that are spatially disposed in different directions.

SUMMARY OF THE INVENTION

The present invention provides a method and system for determining electromagnetic properties of a signal source such as frequency and azimuth angle detected in a space under surveillance. The method and system according to the invention may be used when neither the number of signal sources, nor the frequency and direction of the signal sources are known *a priori* to the system.

In accordance with a first aspect of the invention there is provided a method for determining a respective electromagnetic parameter and spatial disposition of one or more signal sources in a surveillance space simultaneously bombarded by multiple signals, the method comprising:

receiving said multiple signals at each of a plurality of widebeam, wideband antennas that are spaced apart in a linear array by equal mutual spacings;

simultaneously sampling the respective signals $A_{i,n}$ of each of the antennas at a sampling rate to generate a two-dimensional array of sampled values $S_{i,n}$, where $S_{i,n}$ is the n -th sample of the signal $A_{i,n}$ received at an antenna i ;

calculating a two-dimensional Fourier transform F_{jk} of the array $S_{i,n}$; and

identifying peaks in the Fourier transform satisfying one or more predetermined criteria, a peak satisfying the predetermined criteria being indicative of a signal source in the surveillance space, whereby the location of the peak in said two-dimensional Fourier transform F_{jk} indicates the frequency and the azimuth of the respective signal source and the amplitude of the peak indicates the amplitude of the signal source.

In accordance with a second aspect of the invention there is provided a system for determining a respective electromagnetic parameter and spatial disposition of one or more signal sources in a surveillance space simultaneously bombarded by multiple signals, the system comprising:

an antenna array having a plurality of spaced apart widebeam, wideband antennas that are spaced apart in a linear array by equal mutual spacings and are configured to receive said multiple signals; and

a processor coupled to the antenna array and being configured to:

sample the respective signals $S_{i,n}$ received by each of the antennas at a sampling rate to generate a two-dimensional array of sampled values $S_{i,n}$, where $S_{i,n}$ is the n -th sample of the signal received at a detector i ;

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calculate a two-dimensional Fourier transform F_{jk} of the array $S_{i,n}$; and

identify peaks in the Fourier transform satisfying one or more predetermined criteria, a peak satisfying the predetermined criteria being indicative of a signal source in the surveillance space, whereby the location of the peak in said two-dimensional
5 Fourier transform F_{jk} indicates the frequency and the azimuth of the respective signal source and the amplitude of the peak indicates the amplitude of the signal source.

The system of the invention comprises an array of antenna elements. Signal sources in the surveillance space radiate electromagnetic (EM) signals towards the receiving antenna array which collects the radiated signals. The frequency f of the EM
10 radiation may or may not be known to the system. The antenna array must, of course, be capable of receiving the signals and to this end must be tuned to a frequency band in which the signal sources are located and must be adapted to receive a signal over a wide angle of view that contains all the signal sources. The distance traveled by the EM radiation from the object to the antenna array is in general different for each receiving
15 antenna in the array. The signals arriving at each of the receiving antennas are thus out of phase from each other, the phase difference being a function of the incremental distance that each signal travels before being received. The signals are sampled to yield a two dimensional array of sampled values that is input to an azimuth determination processing stage. The azimuth determination processing involves calculating a two
20 dimensional Fourier transform of the input array. The Fourier transform, has one index (or "bin number") j that is a function of the frequency f of the EM radiation, and various parameters of the system. The other bin number of the Fourier transform, k , is a function of the frequency f , the azimuth angle θ and parameters of the system.

The Fourier transform is scanned for peaks satisfying predetermined criteria in
25 order to identify signals in the surveillance space and to segregate these signals from clutter. For each received signal, if the frequency f of its EM radiation is unknown to the system, the frequency f is determined from the bin number j of the peak. The azimuth angle θ of the received signal is then determined from the bin number k of the peak and the frequency f .

BRIEF DESCRIPTION OF THE DRAWINGS

In order to understand the invention and to see how it may be carried out in practice, some embodiments will now be described, by way of non-limiting example only, with reference to the accompanying drawings, in which:

5 **Fig. 1** shows a block diagram of a surveillance system configured to determine the azimuth angle and frequency of a signal source in accordance with an embodiment of the invention;

Fig. 2 shows a method for determining the azimuth angle and frequency of a signal source in accordance with an embodiment of the invention;

10 **Fig. 3** shows a two-dimensional time-distance plot obtained by one embodiment of the method of the invention; and

Fig. 4 is a flow diagram showing the principal operations carried out by a surveillance system for determining the azimuth angle and frequency of a signal source in accordance with an embodiment of the invention.

15 DETAILED DESCRIPTION OF EMBODIMENTS

The present invention provides a system and method for determining the azimuth angle and signal frequency of a signal source that emits a signal, which is detected in a space under surveillance. Fig. 1 is a block diagram schematically showing the hardware components and signal processing stages of a detection system **20** in
20 accordance with one embodiment of the invention. The system **20** comprises an antenna array **21** consisting of a plurality of wideband antenna elements **A**. Four antenna elements **A₀** to **A₃** are shown in Fig.1. This is by way of example only, and although the invention may be carried out using any number of receiving antennas greater than 1, the greater the number of receiving antennas in the array **21**, the greater is the accuracy and
25 sensitivity of the detection and consequently of the azimuth determination. Signal sources in the surveillance space, such as transmitters **22** to **25** (shown in Fig. 2) radiate electromagnetic (EM) pulses towards the receiving antenna array **21** which collects the received data.

 Fig. 2 shows schematically an arrangement of the antenna array **21** in which
30 adjacent receiving antennas are aligned along an axis **30** and separated by a fixed distance **d**. The distance from the array **21** to a signal source detected in the surveillance

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space, such as the transmitters **22** to **25** is sufficiently large, in comparison to the length of the array **21** that the respective rays R from each antenna in the array to the transmitters are essentially parallel, and thus determine the same azimuth angle θ with the axis **30**.

5 The signal that is collected in the i -th receiver A_i of the receiving antenna array **21** during the n -th sample may be modeled as:

$$S_{i,n} = A \cos[2\pi f(ndt + i\Delta t) + \varphi] + N_{i,n} \quad (1)$$

where:

- t = time,
- 10 A = amplitude,
- f = frequency of the EM radiation,
- dt = time delay of the signal between samples,
- Δt = time delay of signals from adjacent antennas in the array, and
- $N_{i,n}$ = noise in i -th antenna during the n -th sample.

15 The signals $S_{i,n}$ have respective time delays $i\Delta t$ owing to the fact that the distance that each signal $S_{i,n}$ travels along the respective ray **32** from the transmitter to the antenna A_i is different for each signal. In Fig. 2 it is seen that the distance traveled by the signal S_i along the ray R_i exceeds the distance traveled by the signal S_0 along the ray R_0 by an amount Δt given by:

$$20 \quad \Delta t = \frac{d}{c} \cos(\theta) \quad (2)$$

where c is the velocity of the propagation of the signals and d is the fixed distance between antennas.

Referring again to Fig. 1, each antenna **A** receives its respective signal **S** that is provided to its respective receiver channel **RC**. The signals $S_{i,n}$ are sampled by the
25 receivers **RC** at a known sampling rate, to yield a two dimensional array of sampled values:

$$S = A \cos 2\pi f[(ndt + i\Delta t) + \varphi] + N_i \quad (3)$$

where n is the sample number obtained using the sampling rate. For a fixed value of n , the sequence $S_{i,n}$ is a sampling of the signal emitted by the respective signal source **22**
30 to **25** at a sampling rate equal to $1/dt$.

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For m simultaneous signals, this gives:

$$S_{i,n} = \sum_m \left[A_m \cos[2\pi f_m (ndt + i\Delta t_m) + \varphi_m] + N_{i,n} \right] \quad (4)$$

In one embodiment, the values of $S_{i,n}$ are binarized by setting $S_{i,n}=1$ when $S_{i,n}>0$ and $S_{i,n}=-1$ when $S_{i,n}\leq 0$. Binarizing the signals simplifies the hardware and software since a particular benefit of the invention over hitherto proposed approaches is that the invention is able to detect weak signals, which individually are indistinguishable from noise. Any benefit in attempting to assign a multibit value to a signal that is of such small magnitude that it is indistinguishable from noise is insignificant and generally offset by the greater simplicity in the hardware and processing that can be achieved by binarizing the signals. On the other hand, when the dynamic range of simultaneous multi-signals is required, multibit processing may be preferable using fewer antennas so as to reduce processing complexity.

The two dimensional array $S_{i,n}$ is input to an azimuth determination processing stage 11. The azimuth determination processing involves calculating a two dimensional Fourier transform of the array $S_{i,n}$. The Fourier transform, referred to herein as a “frequency-azimuth plot”, is a two-dimensional array F_{jk} . j is a bin number satisfying:

$$f = \frac{j \cdot \text{clock}}{N} \quad (5)$$

where f is the possibly unknown frequency of the EM radiation and N is the number of bins of this dimension. k is a bin number satisfying:

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$$f = \frac{k \cdot (1/dt)}{N'} \quad (6)$$

where N' is the number of bins of this dimension.

Substituting Equation (2) into Equation (6) yields:

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$$f = \frac{k \cdot c}{N' \cdot d \cos \theta} \quad (7)$$

or equivalently,

$$\theta = \text{Arc cos} \left(\frac{k \cdot c}{N' \cdot d \cdot f} \right) \quad (8)$$

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The array F_{jk} is scanned in the azimuth determination processing stage **11** for peaks satisfying one or more predetermined criteria in order to identify signals emitted by the signal sources **22** to **25** in the surveillance space and to segregate these signals from clutter. The predetermined criteria may include, for example, peak amplitude above a predetermined threshold. The frequency f of each identified signal source is determined from the bin number j of the peak using Equation (5). This produces a value of f whose accuracy is determined by the number of bins N . The accuracy of the frequency determination can often be improved by using phase data, as is known in the art of Fourier analysis. In order to deal with the problem of frequency ambiguity, the method of the invention may be performed at least twice using different values of "clock" and/or by using an RF filter. Once the frequency is known, the azimuth angle θ of the signal source is then determined from the bin number k of the peak using Equation (7). The output **26** of the processing stage **11** includes the azimuth angle for each detected signal and optionally the frequency of each detected signal.

Fig. 3 shows a two-dimensional frequency-azimuth plot **35** obtained on real data by the method of the invention. The data were collected using a linear array of 128 receivers. The plot was obtained using 512 signal samples. The plot **35** has two peaks **36** and **37** corresponding to two different signal sources in the surveillance area. The peak **36** reveals a signal having a frequency of f_1 and an azimuth angle of 30° . This signal was detected with a signal to noise ratio of -18 db. The peak **37** reveals a signal having a frequency of f_2 and an azimuth angle of 50° . This signal was detected with a signal to noise ratio of -20db. Increasing the number of detectors in the array enhances sensitivity.

Fig 4 is a flow diagram summarizing the principal operations carried out in accordance with an embodiment of the invention for determining the azimuth angle and frequency of a signal source as described above with particular reference to Figs. 1 to 3.

It should be noted that the system of the invention may be implemented using more than one array of receiving antennas. For example, the invention may be implemented using two mutually perpendicular arrays of receiving antennas. An additional Fourier transform of the two-dimensional Fourier transform F_{jk} then generates, for each identified emitter, two independent angles (azimuth and elevation) that together define a position vector of the signal source.

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It will also be appreciated that the signal source need not be an active transmitter but could, for example, be a reflected signal.

It will also be appreciated that since the signals detected by the detector array according to the invention are spatially separated in two-dimensional space, signals
5 having identical frequencies but spaced apart in two-dimensional space will be discretely detected.

Also, once the frequency and direction of a transmitter have been determined using FFT, Discrete Fourier Transform may be employed to track the detected transmitter thus saving processing time.

10 It will also be understood that the system according to the invention may be a suitably programmed computer. Likewise, the invention contemplates a computer program being readable by a computer for executing the method of the invention. The invention further contemplates a machine-readable memory tangibly embodying a program of instructions executable by the machine for executing the method of the
15 invention.

CLAIMS:

1. A method for determining a respective electromagnetic parameter and spatial disposition of one or more signal sources in a surveillance space simultaneously bombarded by multiple signals, the method comprising:
 - 5 receiving said multiple signals at each of a plurality of widebeam, wideband antennas that are spaced apart in a linear array by equal mutual spacings;
simultaneously sampling the respective signals $S_{i,n}$ of each of the antennas at a sampling rate to generate a two-dimensional array of sampled values $S_{i,n}$, where $S_{i,n}$ is the n -th sample of the signal received at an antenna i ;
 - 10 calculating a two-dimensional Fourier transform F_{jk} of the array $S_{i,n}$; and
identifying peaks in the Fourier transform satisfying one or more predetermined criteria, a peak satisfying the predetermined criteria being indicative of a signal source in the surveillance space, whereby the location of the peak in said two-dimensional Fourier transform F_{jk} indicates the frequency and the azimuth of the respective signal
15 source and the amplitude of the peak indicates the amplitude of the signal source.
2. The method according to claim 1, including calculating the frequency of the radiation emitted by the signal source indicated by an identified peak satisfying the one or more predetermined criteria, using an algebraic involving the sampling rate.
3. The method according to claim 2, including calculating the frequency of the
20 radiation emitted by the signal source indicated by the identified peak using the algebraic expression $f = \frac{j \cdot \text{clock}}{N}$, where f is the frequency of the radiation, j is a bin number of the peak and N is a number of bins.
4. The method according to any one of claims 1 to 3, including calculating an azimuth angle of the signal source indicated by an identified peak satisfying the one or
25 more predetermined criteria.
5. The method according to claim 4, wherein the azimuth angle of the signal source is calculated using an algebraic expression involving the frequency f of the radiation emitted by the signal source.

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6. The method according to claim 5, wherein and wherein the azimuth angle θ of the signal source indicated by the peak is calculated using the algebraic expression $\theta = \text{Arc cos}\left(\frac{k \cdot c}{N' \cdot d \cdot f}\right)$, where c is the velocity of the radiation, k is a bin number of the peak and N' is a number of bins.
- 5 7. The method according to any one of claims 1 to 6, wherein the values of $S_{i,n}$ are binarized by setting $S_{i,n} = 1$ when $S_{i,n} > 0$ and $S_{i,n} = -1$ when $S_{i,n} \leq 0$.
8. The method according to any one of claims 1 to 7, wherein the multiple signals are received by a two-dimensional array of antennas such that along each of two mutually perpendicular axes respective ones of said antennas are spaced apart in a linear
10 array by equal mutual spacings; the method further including:
 computing an additional Fourier transform of said two-dimensional Fourier transform F_{jk} so as to compute a three-dimensional Fourier transform that also provides elevation of each respective signal source.
9. A system for determining a respective electromagnetic parameter and spatial
15 disposition of one or more signal sources in a surveillance space simultaneously bombarded by multiple signals, the system comprising:
 an antenna array having a plurality of spaced apart widebeam, wideband antennas that are spaced apart in a linear array by equal mutual spacings and are configured to receive said multiple signals; and
20 a processor coupled to the antenna array and being configured to:
 sample the respective signals $S_{i,n}$ received by each of the antennas at a sampling rate to generate a two-dimensional array of sampled values $S_{i,n}$, where $S_{i,n}$ is the n -th sample of the signal received at a detector i ;
 calculate a two-dimensional Fourier transform F_{jk} of the array $S_{i,n}$; and
25 identify peaks in the Fourier transform satisfying one or more predetermined criteria, a peak satisfying the predetermined criteria being indicative of a signal source in the surveillance space, whereby the location of the peak in said two-dimensional Fourier transform F_{jk} indicates the frequency and the azimuth of the respective signal source and the amplitude of the peak indicates the amplitude of the signal source.

10. The system according to claim 9, wherein, wherein the processor is further configured to calculate, for an identified peak satisfying the one or more predetermined criteria, the frequency of the radiation emitted by the antennas indicated by the peak using an algebraic involving the sampling rate.
- 5 11. The system according to claim 10, wherein the antennas are arranged in a linear array having a uniform spacing d between adjacent detectors, and wherein the processor is configured to calculate the frequency of the radiation emitted by the signal source indicated by the peak using the algebraic expression $f = \frac{j \cdot \text{clock}}{N}$, where f is the frequency of the radiation, j is a bin number of the peak and N is a number of bins.
- 10 12. The system according to any one of claims 9 to 11, wherein the processor is further configured to calculate, for an identified peak satisfying the one or more predetermined criteria, an azimuth angle of the signal source indicated by the peak.
13. The system according to claim 12, wherein the processor is configured to calculate the azimuth angle of the signal source using an algebraic expression involving
- 15 the frequency f of the radiation emitted by the signal source.
14. The system according to claim 13, wherein the processor is configured to calculate the azimuth angle θ of the signal source indicated by the peak using the algebraic expression $\theta = \text{Arc cos} \left(\frac{k \cdot c}{N' \cdot d \cdot f} \right)$, wherein c is the velocity of the radiation, k is a bin number of the peak and N' is a number of bins.
- 20 15. The system according to any one of claims 9 to 14, wherein the values of $S_{i,n}$ are binarized by setting $S_{i,n} = 1$ when $S_{i,n} > 0$ and $S_{i,n} = -1$ when $S_{i,n} \leq 0$.
16. A computer program comprising computer program code means for performing the method of any one of claims 1 to 8 when said program is run on a computer.
17. A computer program as claimed in claim 16 embodied on a computer readable
- 25 medium.