

ABSTRACT

SIMULATION ARRANGEMENT

5 A vehicle simulator is provided with a control device (10) for actuation
by an operator which device's input is digitised (12) and fed to a vehicle
model (14). The model (14) maintains an objective position and direction for
the simulated vehicle which are fed to a lag means (16). The lag means
operates to delay the rate of change of objective direction of the simulated
vehicle to provide a subjective direction to a display generator (18). The
10 display generator (18) provides a subjective view based on the objective
position and subjective direction of the simulated vehicle on a display (22).

(Figure 1)

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