

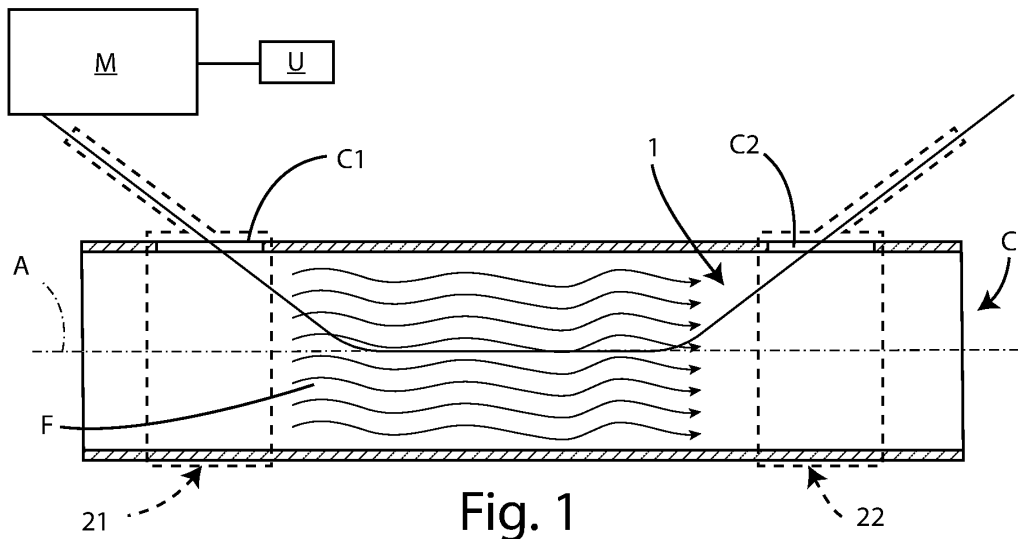


Fig. 1

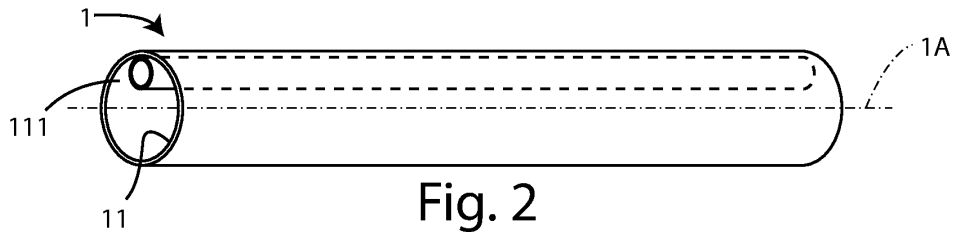


Fig. 2

Tempo	Deformazione in predeterminati punti del cavo			
t_1	$(D_1)_1$	$(D_2)_1$	...	$(D_N)_1$
t_2	$(D_1)_2$	$(D_2)_2$	...	$(D_N)_2$
...	...	...	...	...
t_M	$(D_1)_M$	$(D_2)_M$	...	$(D_N)_M$

Fig. 3

Tempo	Deformazione in predeterminati punti del cavo rispetto a predeterminati valori di riferimento			
t_1	$(\Delta D_1)_1 = (D_1)_1 - D_{10}$	$(\Delta D_2)_1 = (D_2)_1 - D_{20}$	...	$(\Delta D_N)_1 = (D_N)_1 - D_{N0}$
t_2	$(\Delta D_1)_2 = (D_1)_2 - D_{10}$	$(\Delta D_2)_2 = (D_2)_2 - D_{20}$	...	$(\Delta D_N)_2 = (D_N)_2 - D_{N0}$
...	...	...	...	...
t_M	$(\Delta D_1)_M = (D_1)_M - D_{10}$	$(\Delta D_2)_M = (D_2)_M - D_{20}$	...	$(\Delta D_N)_M = (D_N)_M - D_{N0}$

Fig. 4

Tempo	Differenza tra valori di deformazione associati a due predeterminati punti del cavo successivi			
t_1	$\{\Delta(\Delta D_1)_1\} = (\Delta D_1)_1 - (\Delta D_2)_1$	$\{\Delta(\Delta D_2)_1\} = (\Delta D_2)_1 - (\Delta D_3)_1$	...	$\{\Delta(\Delta D_N)_1\} = (\Delta D_{N-1})_1 - (\Delta D_N)_1$
t_2	$\{\Delta(\Delta D_1)_2\} = (\Delta D_1)_2 - (\Delta D_2)_2$	$\{\Delta(\Delta D_2)_2\} = (\Delta D_2)_2 - (\Delta D_3)_2$	...	$\{\Delta(\Delta D_N)_2\} = (\Delta D_{N-1})_2 - (\Delta D_N)_2$
...	...	...	...	...
t_M	$\{\Delta(\Delta D_1)_M\} = (\Delta D_1)_M - (\Delta D_2)_M$	$\{\Delta(\Delta D_2)_M\} = (\Delta D_2)_M - (\Delta D_3)_M$	...	$\{\Delta(\Delta D_N)_M\} = (\Delta D_{N-1})_M - (\Delta D_N)_M$

Fig. 5

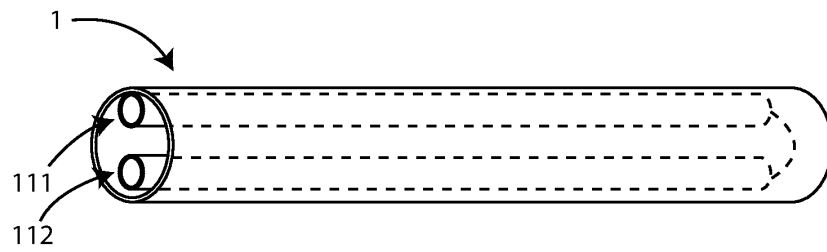


Fig. 6

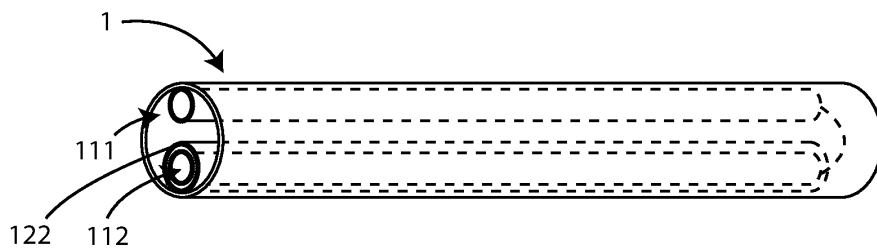


Fig. 7

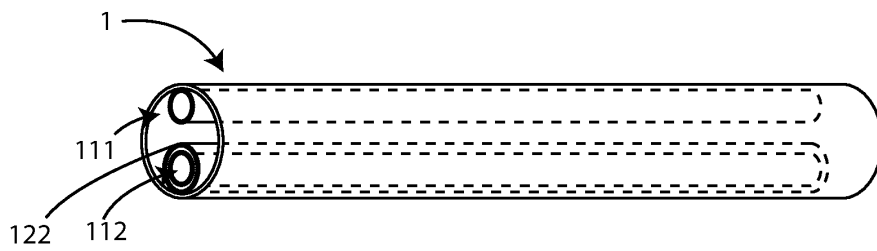
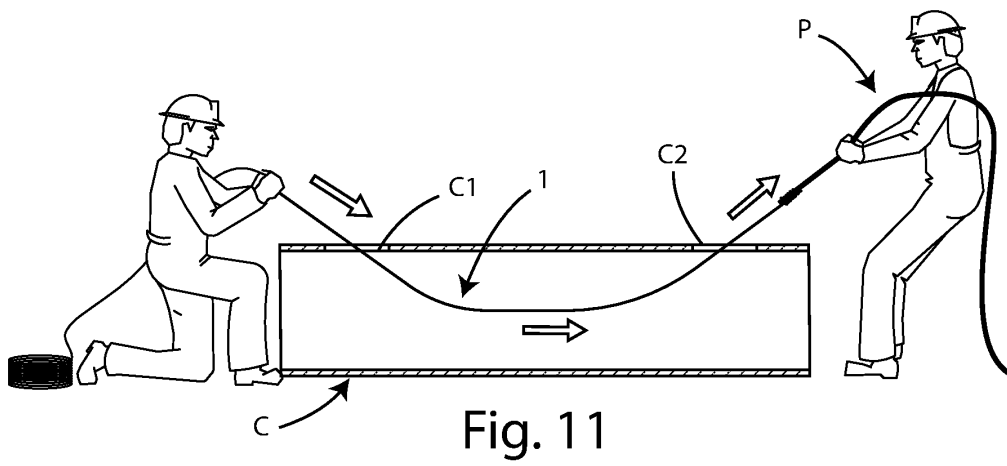
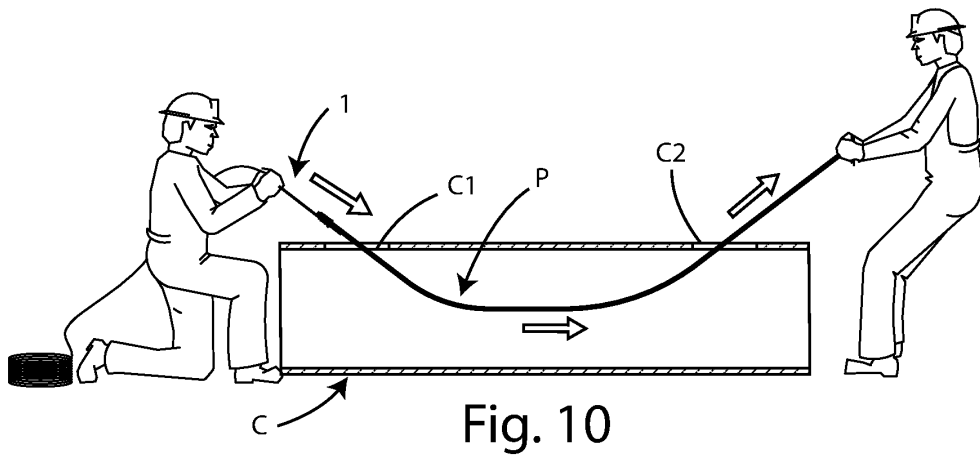
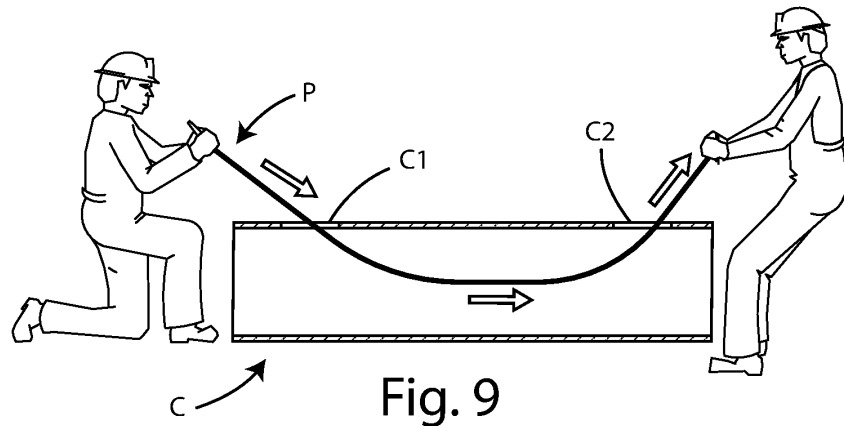


Fig. 8



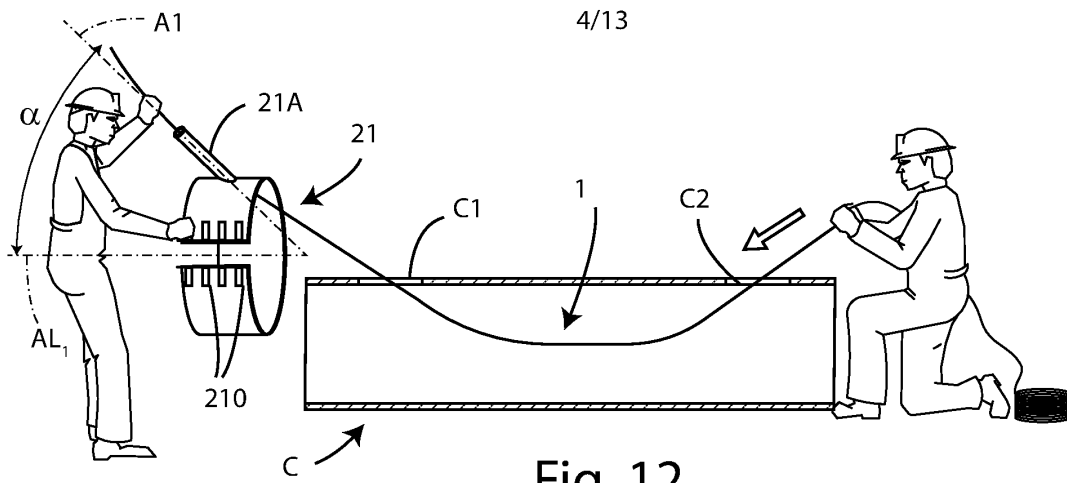


Fig. 12

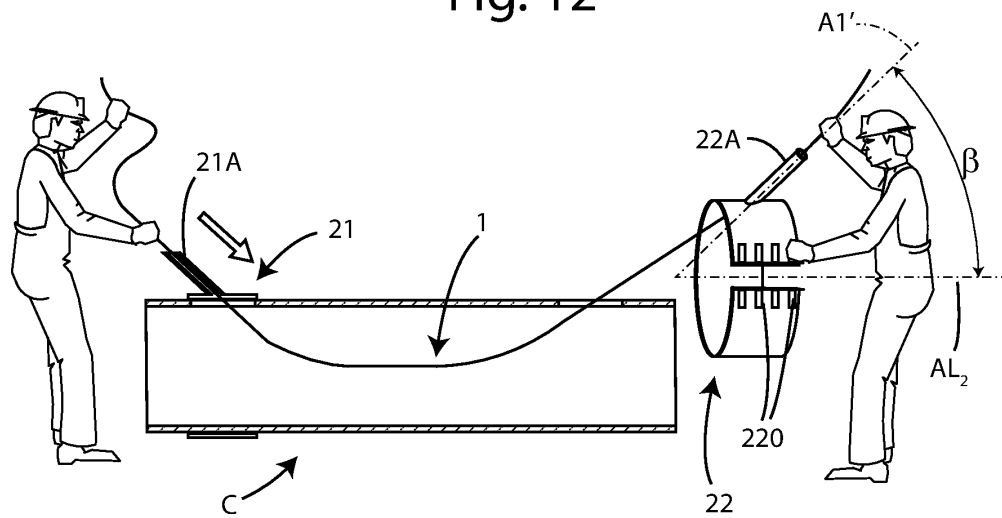


Fig. 13

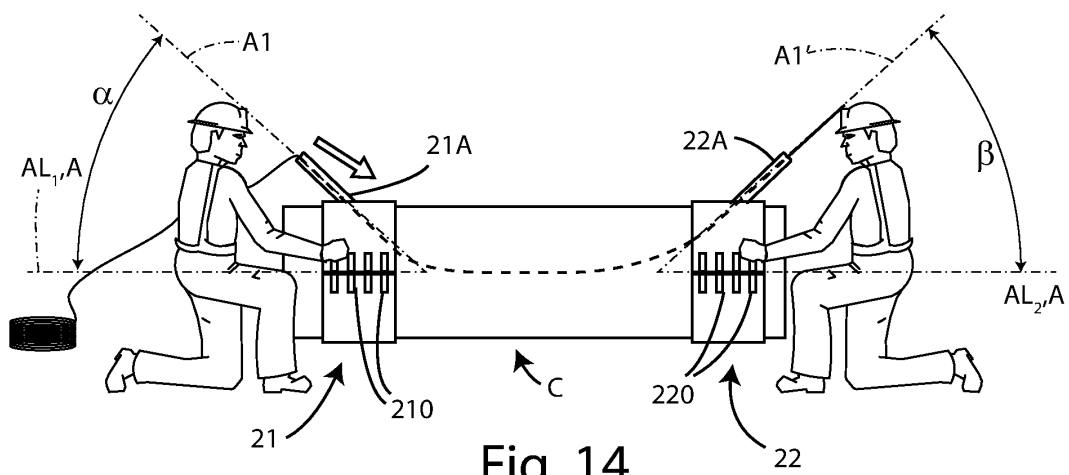


Fig. 14

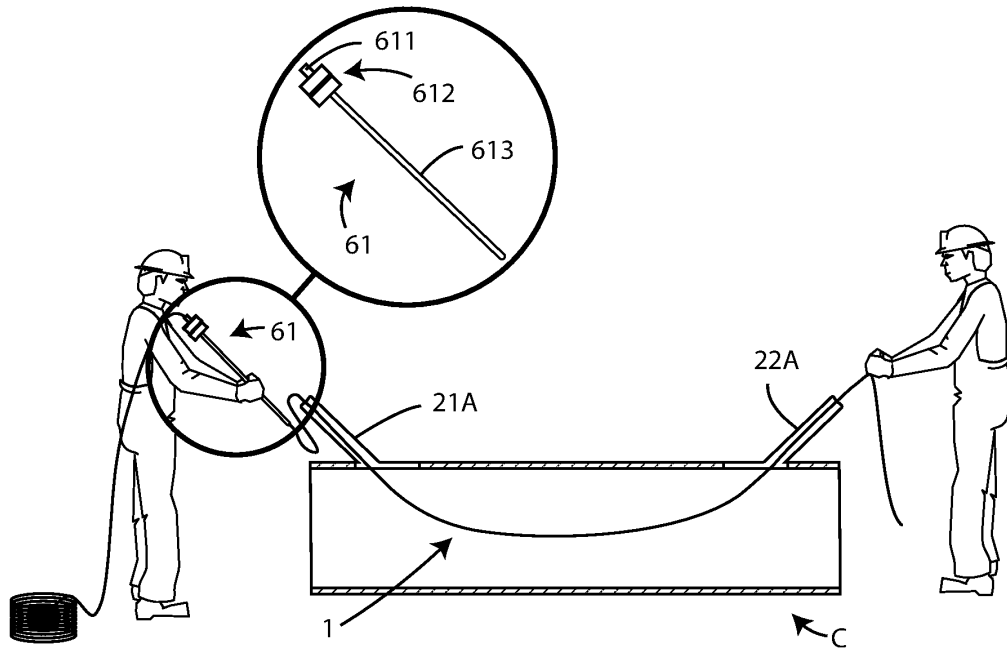


Fig. 15

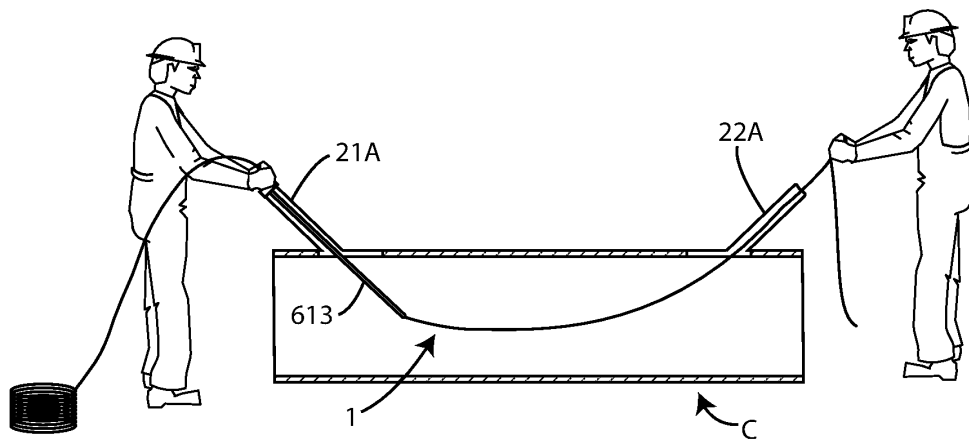
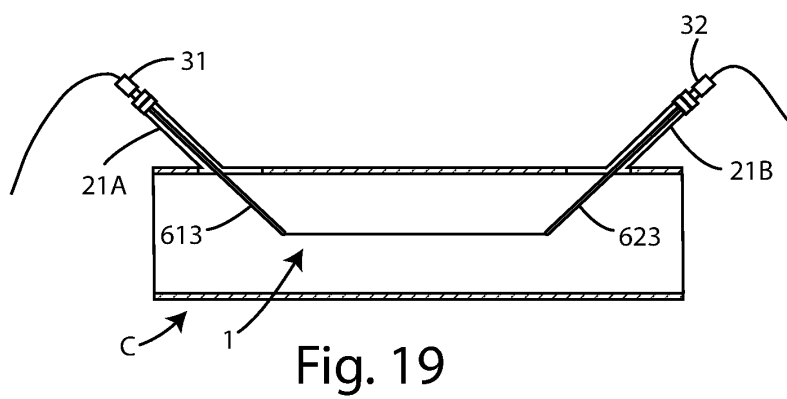
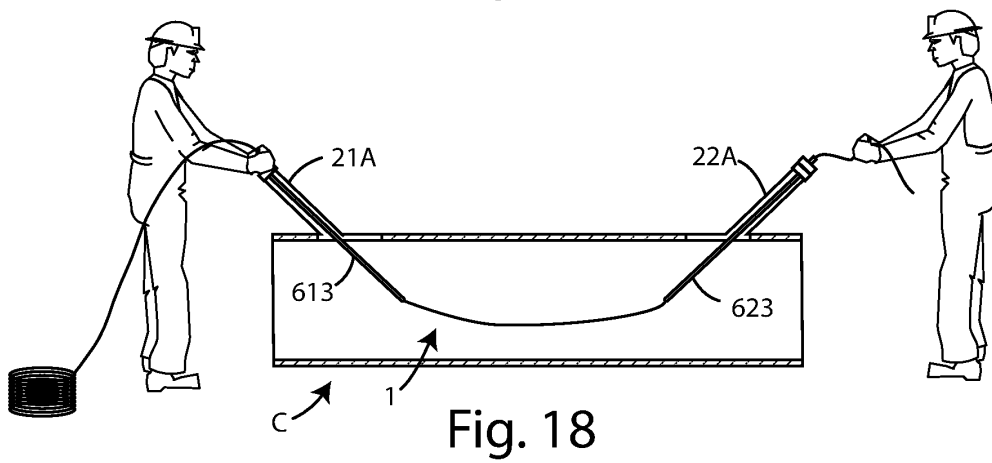
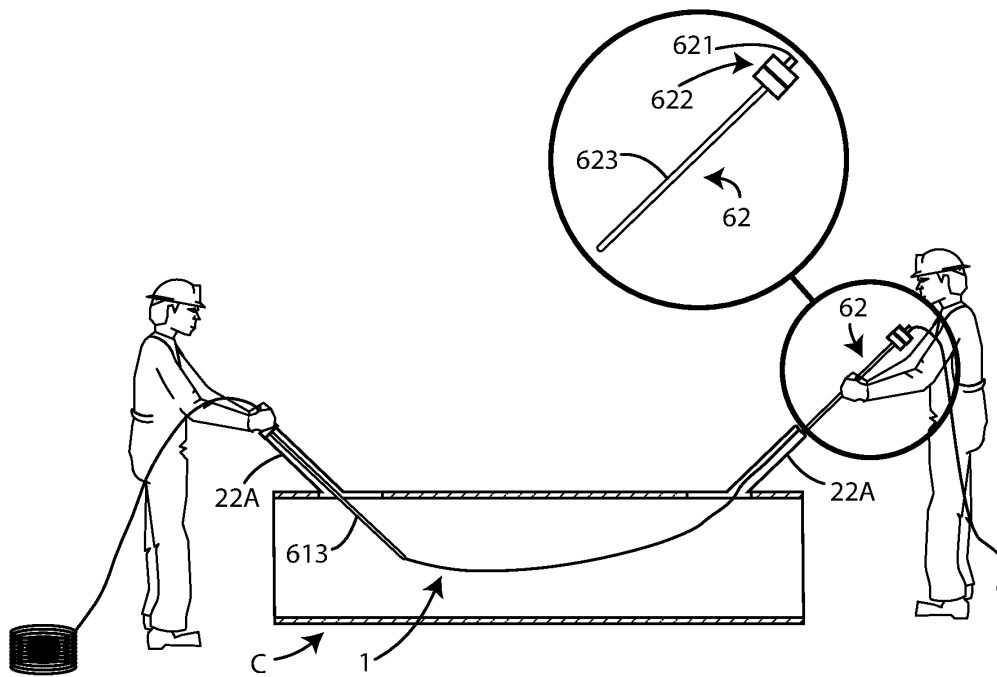
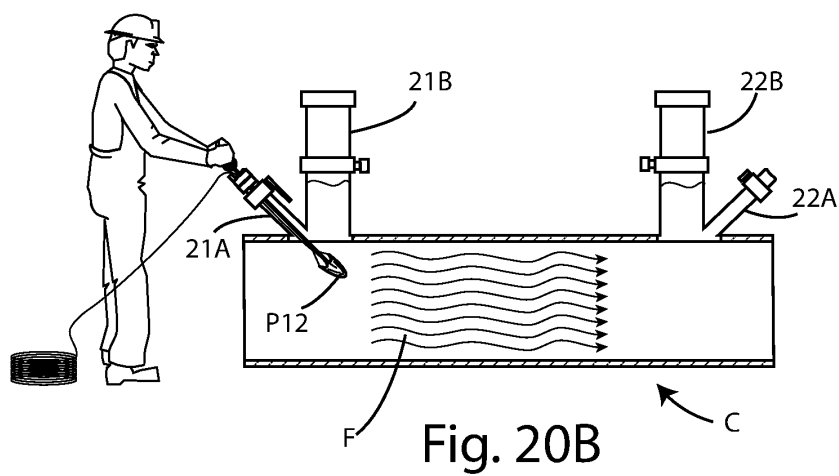
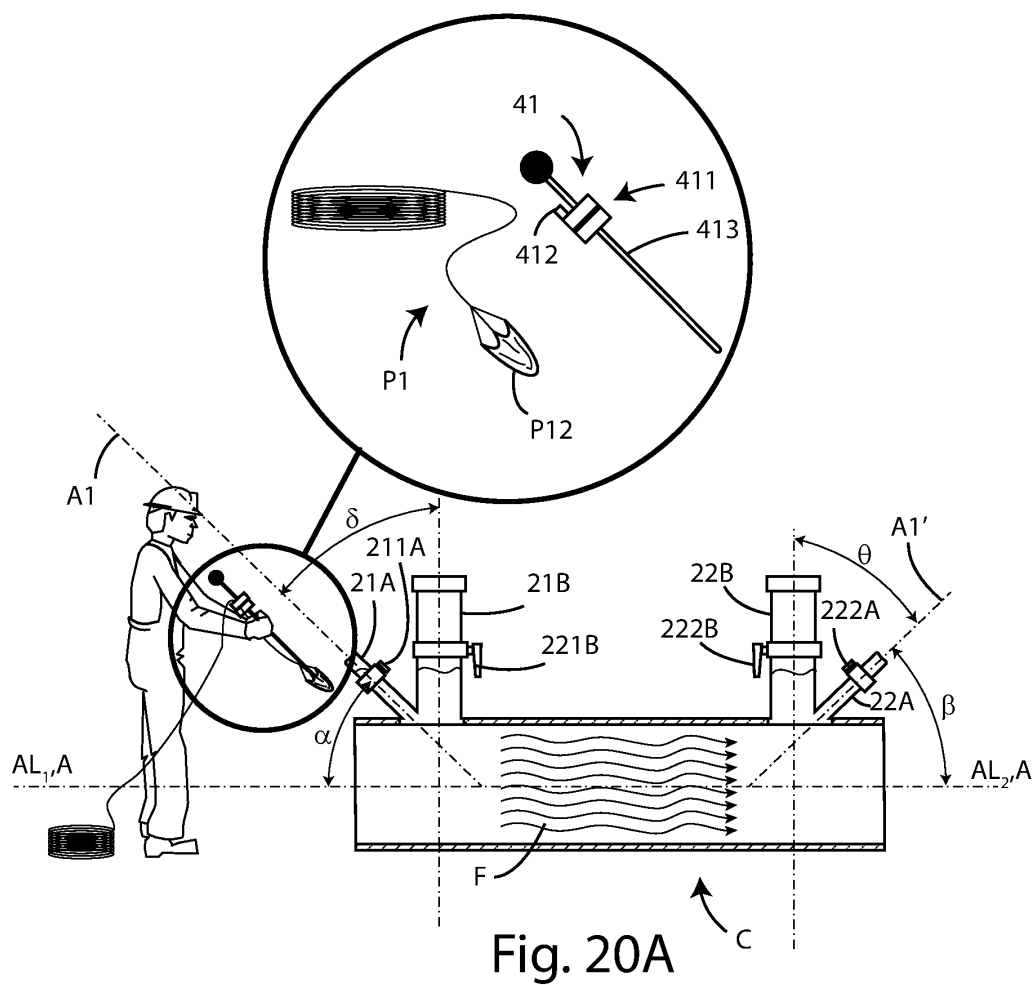


Fig. 16





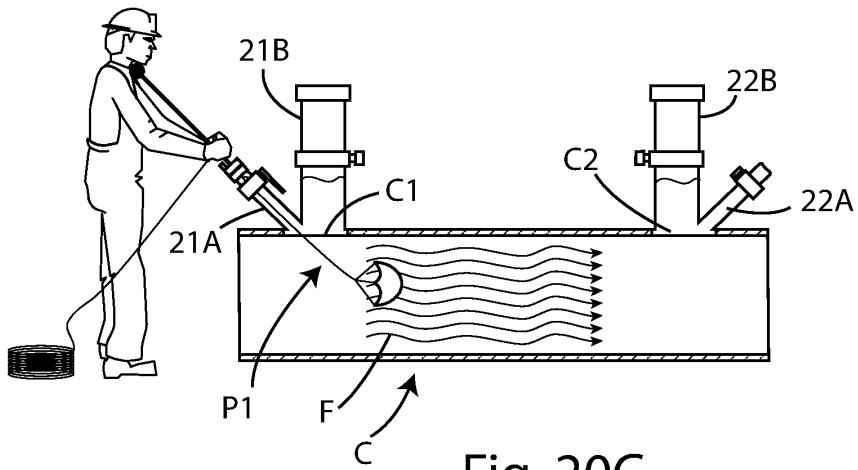


Fig. 20C

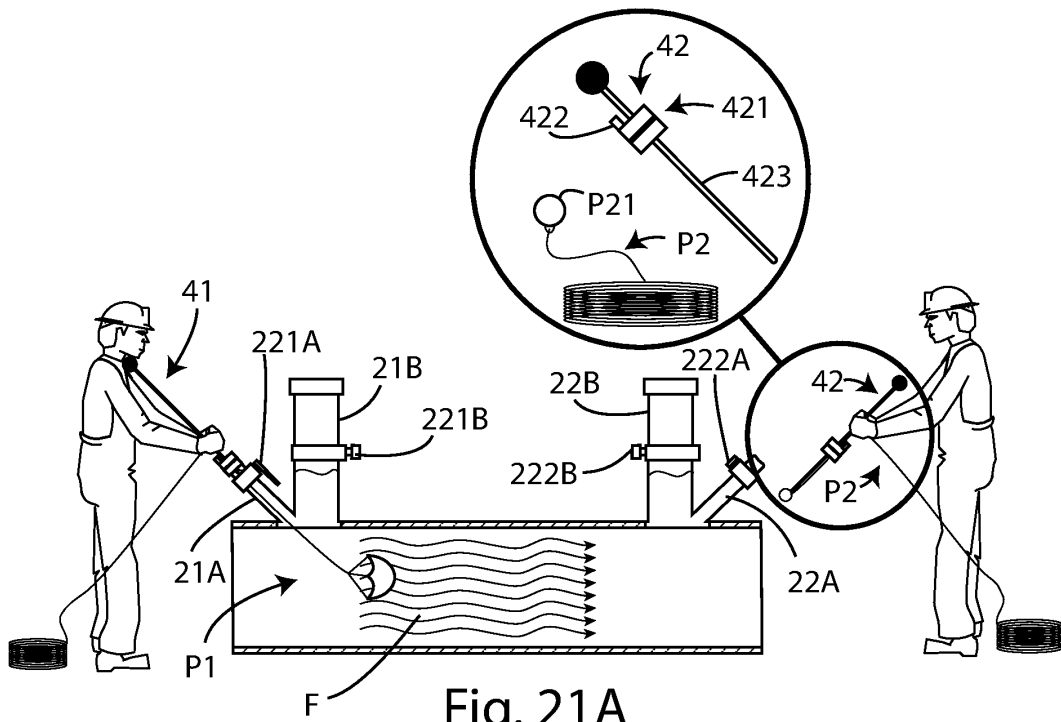
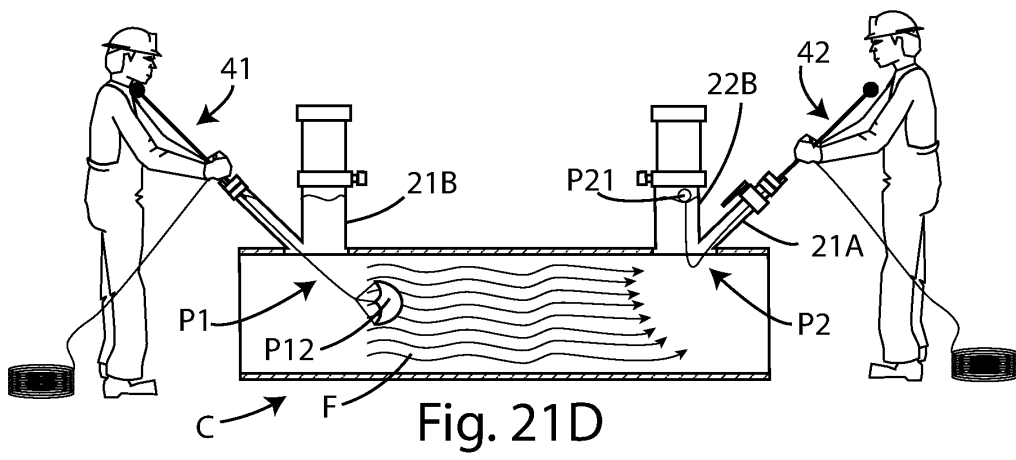
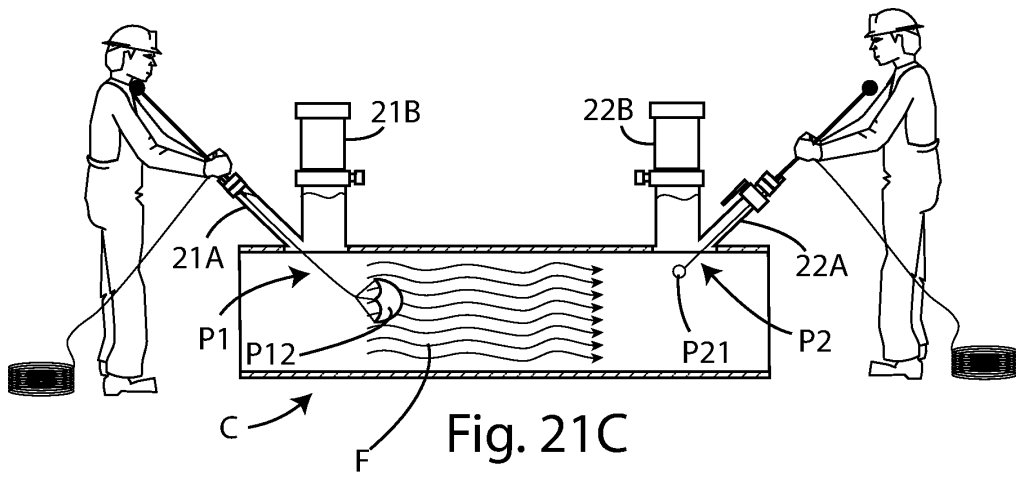
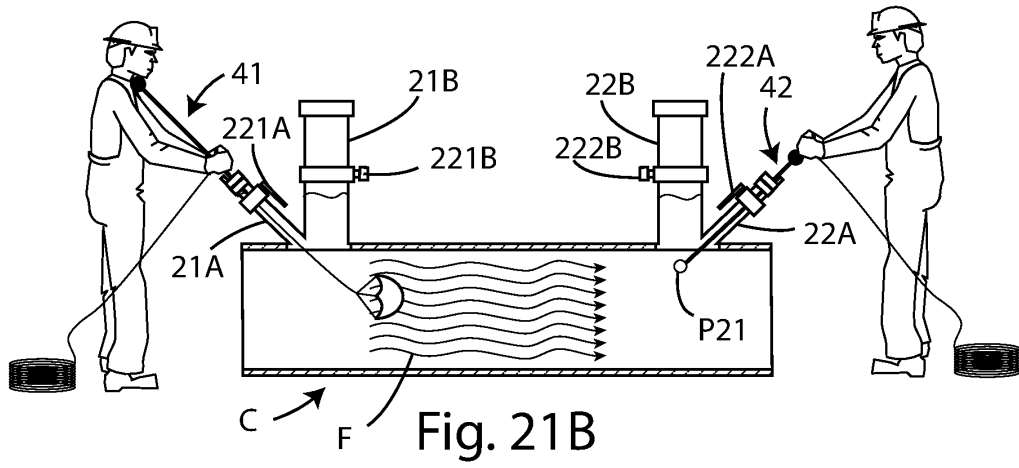
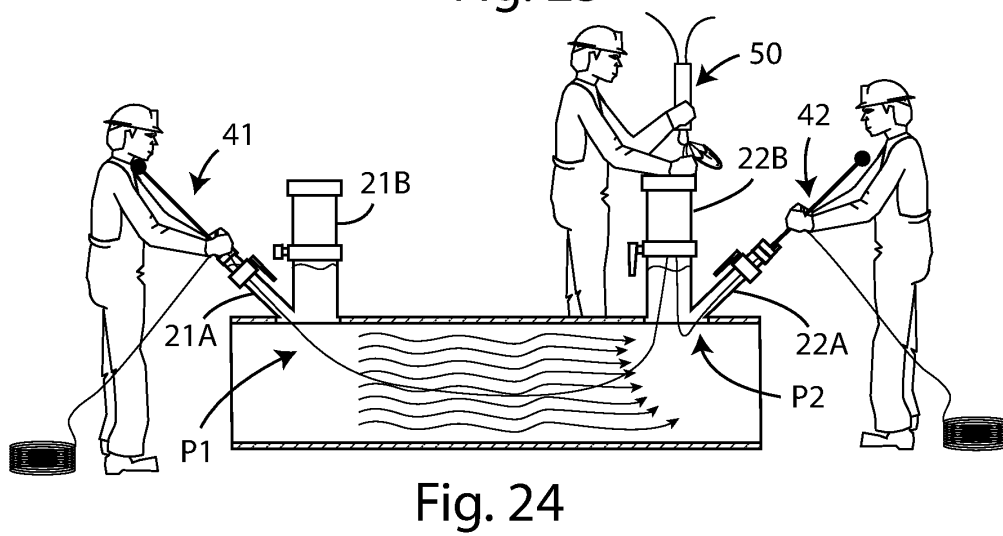
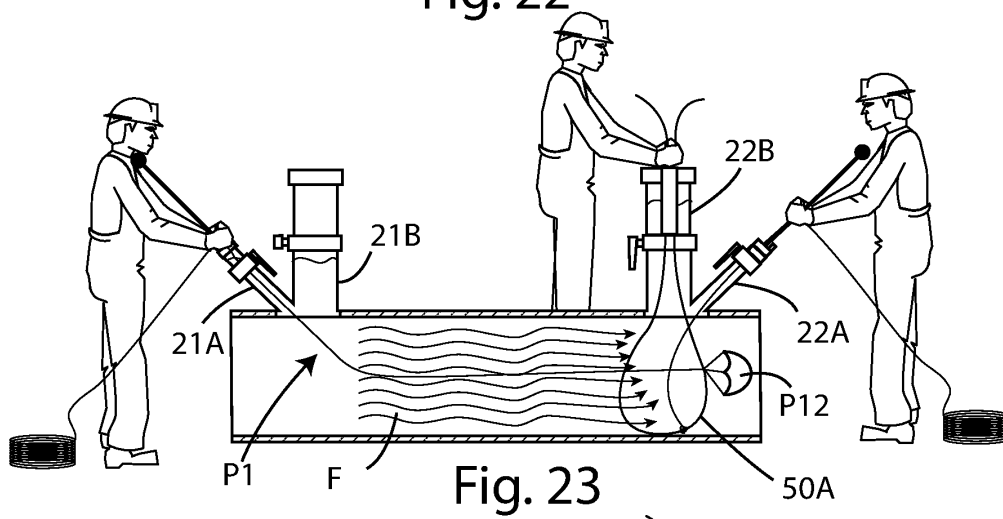
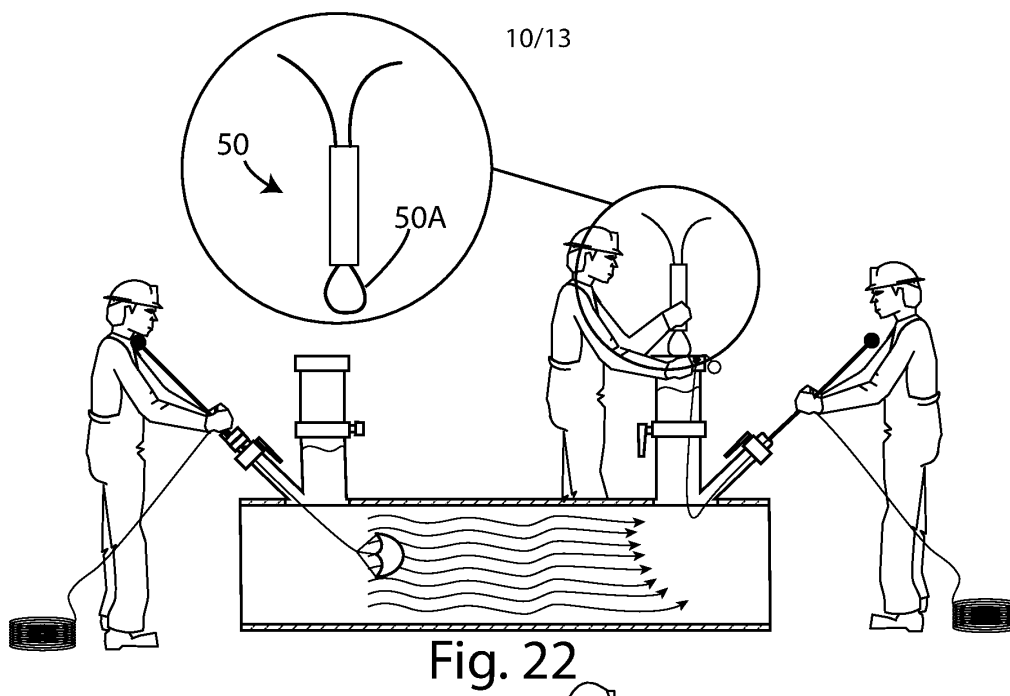


Fig. 21 A





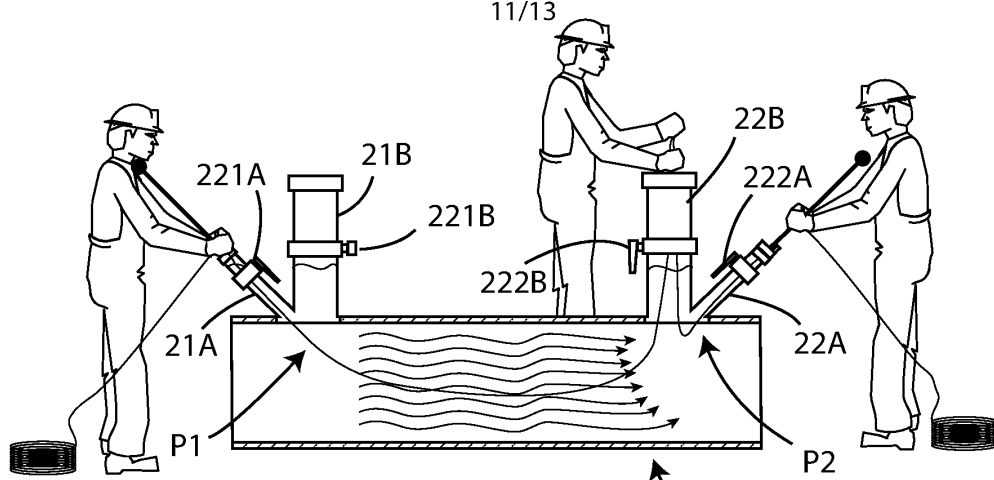


Fig. 25 ^c

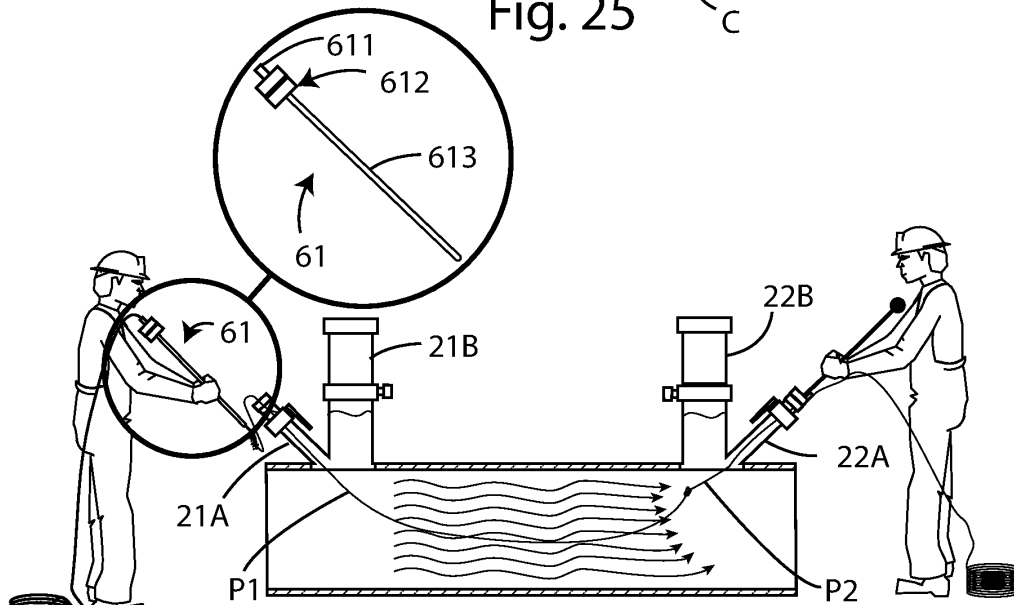


Fig. 26 ^c

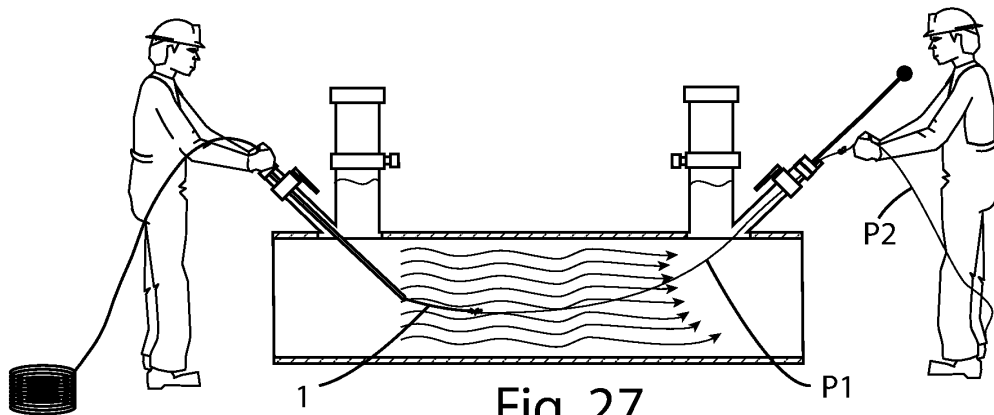


Fig. 27

