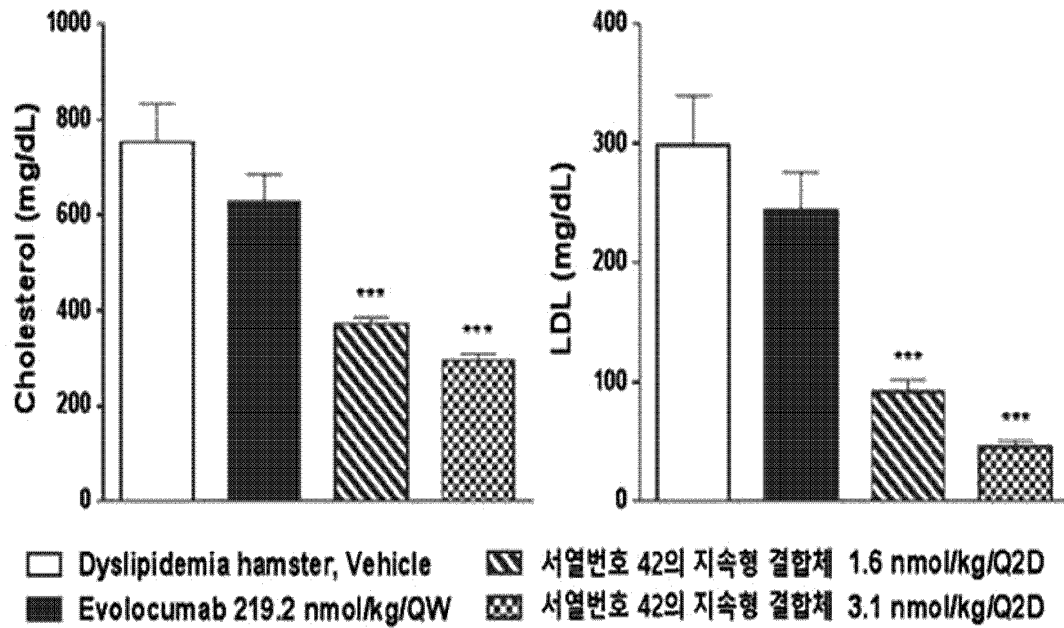


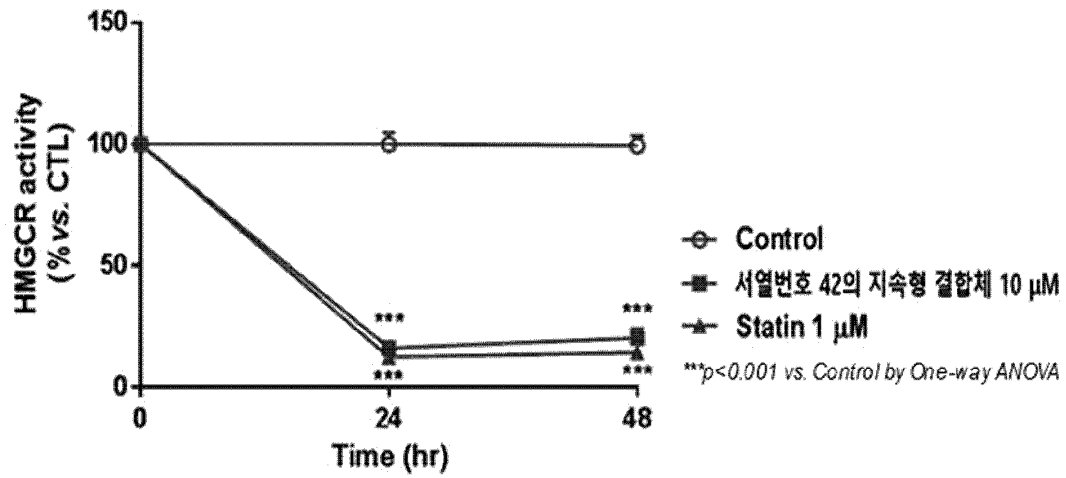
[도1]

*** $p < 0.001$ vs. Vehicle by One-way ANOVA

[도2]

*** $p < 0.001$ vs. Control by One-way ANOVA

[도3]



[도4]

