

**Drive system for an elevator installation, elevator installation, and method for installing
a drive on a support element of an elevator installation**

5 Description

The invention relates to a drive system for an elevator installation, an elevator installation, and a method for installing a drive on a support element of an elevator installation.

10 Known elevator installations for transporting people or loads include an elevator car which can be moved vertically in an elevator shaft. The elevator car is usually connected to a counterweight via a carrier means. A drive for moving the elevator car along a guide rail can be arranged, for example, on a drive assembly in a shaft head of the elevator shaft or in a machinery room above the elevator shaft. However, previously known drive systems for elevator installations require a lot of space, for example in the shaft head of an elevator installation, or
15 they are complex to install.

The object of the invention is to specify a drive system for an elevator installation and in particular an elevator installation which is improved compared to drive systems or elevator installations known from the prior art, with the space requirement of the drive system being reduced or the assembly of the drive system being simplified. Another object of the invention is
20 to specify a method for installing a drive of an elevator installation.

The object is achieved with a drive system according to claim 1 and a method according to the additional independent claim. Advantageous developments and embodiments can be found in
25 the dependent claims and in this description.

One aspect of the invention relates to a drive system for an elevator installation, comprising a drive and a drive suspension for fastening the drive to a support element of the elevator installation, wherein the drive suspension comprises: a rotary joint for tiltably mounting the drive
30 on the support element; and an adjustment device for setting a tilt of the drive about the rotary joint.

A further aspect of the invention relates to an elevator installation comprising a drive system

according to any of the embodiments described herein, an elevator car, and a counterweight which is connected to the elevator car via a carrier means, the drive being designed to drive the carrier means.

5 Yet another aspect of the invention relates to a method for installing a drive on a support element of an elevator installation, comprising mounting the drive on the support element by means of a rotary joint, stabilizing the drive with respect to the support element, and setting a tilt of the drive about the rotary joint.

10 In preferred embodiments, the drive includes a motor, in particular a motor and a gear. The drive can be gearless. The drive has a drive shaft. The drive shaft is rotatable about a shaft axis of the drive. A friction drive pulley of the drive can be fastened to the drive shaft. The friction drive pulley is designed to provide contact between a carrier means of an elevator installation and the drive. In particular, the friction drive pulley is designed to transmit a force
15 provided by the drive to the carrier means. The drive suspension is preferably designed such that, when the drive is fastened to the support element, the friction drive pulley is arranged between the motor of the drive and the support element. The drive can have a drive cooling system or drive electronics, for example for controlling the drive. “Or” typically means “and/or” here. The drive cooling system or the drive electronics can be arranged in particular on an underside of the drive.
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The drive system preferably includes a guide rail for guiding an elevator car, with the guide rail forming the support element. In further preferred embodiments, the support element can be a shaft wall of an elevator installation or a carrying structure in an elevator shaft of an elevator installation.
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In preferred embodiments, the rotary joint of the drive suspension should be understood to be a rotatable connection between the drive and the support element. An axis of rotation of the rotary joint is preferably at least substantially perpendicular to a shaft axis of the drive. “At least substantially perpendicular” should be understood here in particular to mean a perpendicular orientation or an orientation deviating from a perpendicular orientation by a maximum of 15°, for example by a maximum of 10° or by a maximum of 5°. In embodiments, the axis of rotation can be aligned at least substantially perpendicularly to the shaft axis of the drive
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and perpendicularly to a longitudinal axis of a guide rail. The shaft axis of the drive can be aligned at least substantially perpendicularly to the axis of rotation of the rotary joint and at least substantially perpendicularly to a vertical direction, for example perpendicularly to the longitudinal axis of a guide rail. In preferred embodiments, the shaft axis of the drive is aligned with the guide rail.

The adjustment device is preferably arranged below the rotary joint. The rotary joint is designed in particular to transfer a tensile load from the drive to the support element. The adjustment device is designed, for example, to transfer a compressive load from the drive to the support element. In embodiments, the rotary joint is arranged above a friction drive pulley of the drive and the adjustment device is arranged below the friction drive pulley. In particular, the friction drive pulley is arranged between the rotary joint and the adjustment device. In further embodiments, the adjustment device is arranged around the friction drive pulley. For example, the adjustment device can extend in the form of a cage around the friction drive pulley in the direction of the support element, with the adjustment device having at least one window for a carrier means to pass through. In preferred embodiments, the friction drive pulley has a friction drive pulley diameter of at most 150 mm, in particular at most 100 mm, or at most 70 mm.

In preferred embodiments, the rotary joint of the drive suspension comprises a fixing part, which is designed for fastening to the support element, and a first suspension part, which is fastened to the drive. The fixing part and the first suspension part are rotatably connected to one another. The fixing part is preferably rigidly connected to the support element and the first suspension part is rigidly connected to the drive. Rigid connections can be provided by joining methods, for example by screwing.

In preferred embodiments, the first suspension part has at least one first opening and the fixing part has at least one second opening. The rotary joint includes a connecting element arranged so as to pass through the at least one first opening and the at least one second opening. The connecting element can be a pin, a bolt, or a screw, for example. In particular, the connecting element is arranged along the axis of rotation of the rotary joint.

In preferred embodiments, the rotary joint is designed as a hinge. In embodiments, the first

suspension part has at least two first openings along the axis of rotation of the rotary joint. The fixing part extends between the at least two first openings of the first suspension part, wherein the at least one second opening of the fixing part is arranged between two first openings of the first suspension part. In further embodiments, the fixing part has at least two second openings along the axis of rotation of the rotary joint. The first suspension part extends between the at least two second openings of the fixing part, with the at least one first opening of the first suspension part being arranged between two second openings of the fixing part.

In preferred embodiments, the rotary joint is designed to support torques or torque components in directions perpendicular to the axis of rotation. In particular, the rotary joint is designed to support torques or torque components in the direction of the shaft axis of the drive or in the direction of the longitudinal axis of a guide rail. The fixing part and the first suspension part can be in contact along the axis of rotation via at least two contact surfaces, with the contact surfaces extending around the axis of rotation, in particular around the axis of rotation and perpendicular to the axis of rotation. In particular, the fixing part and the first suspension part can form a torque support. For example, the rotary joint can at least partially support torques or torque components that result from the driving of a carrier means or the movement of an elevator car or a counterweight.

Preferably, the adjustment device of the drive suspension comprises a fixing part, which is designed for fastening to the support element, and a second suspension part, which is fastened to the drive and connected to the fixing part. The fixing part and the second suspension part are displaceable relative to one another in a settable manner. The adjustment device can be designed in particular as a linear adjustment device. The adjustment device can comprise an adjustment screw, the adjustment device being designed to displace the fixing part and the second suspension part relative to one another, in particular to move them linearly relative to one another, by rotating the adjustment screw. The second suspension part is preferably rigidly connected to the drive and the fixing part is rigidly connected to the support element.

In preferred embodiments, the tilt of the drive about the rotary joint can be set by displacing the second suspension part relative to the fixing part. For example, the tilt can be set by rotating an adjustment screw of the adjustment device, the second suspension part being displaced relative to the fixing part by rotating the adjustment screw. In particular, the drive suspension

is designed to tilt the drive about the axis of rotation of the rotary joint with respect to the support element, for example with respect to a guide rail, by means of the displacement. In particular, a maximum tilt of 20°, for example a maximum of 10° or a maximum of 5°, can be set by the displacement. In embodiments, the fixing part is part of the rotary joint and the adjustment device.

The drive suspension preferably comprises at least one isolation element, in particular a mechanical isolation element or a buffer element, the at least one isolation element being designed to reduce or prevent the transmission of vibrations or structure-borne noise from the drive to the support element. The isolation element is preferably a spring-damping element. The drive can be decoupled from the support element with regard to the propagation of vibrations or structure-borne noise by means of the isolation element. In particular, the isolation element is designed to damp vibrations or structure-borne noise between the drive and the support element. The isolation element can be arranged between a first suspension part and a fixing part or between a second suspension part and a fixing part. A connecting means, which is arranged so as to pass through at least one first opening of the first suspension part and at least one second opening of the fixing part, is preferably at least partially encased by an isolation element. In particular, the connecting means is surrounded by the isolation element in the region of the at least one first opening or the at least one second opening, for example in the region of the at least one first opening and the at least one second opening. In embodiments, the at least one isolation element comprises plastic or rubber. The at least one isolation element can offer the advantage that structure-borne noise is prevented from spreading to a building in which an elevator installation comprising a drive system according to the embodiments described herein is installed.

In preferred embodiments, the drive suspension, in particular the first suspension part or the second suspension part, comprises an adapter plate which is designed for fastening the drive suspension to a suspension-side end of the drive. The adapter plate is rigidly connected, for example screwed, to the drive. The adapter plate can have a shaft opening for a drive shaft of the drive to pass through. In embodiments, the adapter plate is manufactured as a separate component. In further embodiments, the adapter plate is manufactured as part of the first suspension part or as part of the second suspension part. In particular, the first suspension part and the second suspension part, including the adapter plate, can be manufactured in one piece.

According to embodiments, an elevator installation comprises a drive system according to any of the embodiments described herein. The elevator installation comprises an elevator car. The elevator car is designed to be moved along a guide rail. The elevator installation comprises a counterweight, which is connected to the elevator car via a carrier means. The guide rail is preferably arranged between the elevator car and the counterweight. The drive is designed to drive the carrier means. As a result of the carrier means being driven, the elevator car and the counterweight can be moved vertically, for example in opposite vertical directions. Directional statements regarding “upward”, “downward”, “horizontally”, or “vertically” should be understood here in particular in relation to the direction of gravitational force.

In preferred embodiments, the drive is arranged in an upper end region of the elevator installation. An upper end region of the elevator installation should be understood, for example, to mean a vertical region of the elevator installation, the vertical region corresponding to the upper 30%, in particular the upper 20% or the upper 10%, of the height of the elevator installation. For example, the drive can be arranged in a low shaft head. In particular, the elevator installation can be designed without a machinery room.

The carrier means preferably comprises a belt. For example, a belt may be made of sheathed cords, such as sheathed steel cables. In cross section, the belt has a width which is greater than a thickness of the belt. For example, setting a tilt of the drive relative to the support element can prevent or reduce skewing of the belt or uneven loading of the belt. In particular, the tilt can be readjusted over the lifetime of the elevator installation. In further embodiments, the carrier means comprises at least one cable, for example at least one steel cable.

In elevator installations according to preferred embodiments, the elevator car has a drive-side side wall that faces the drive system, and a shaft axis of the drive runs at least substantially parallel to the drive-side side wall. “At least substantially parallel” should be understood here in particular to mean a parallel alignment or an alignment deviating from a parallel alignment by a maximum of 20°, for example by a maximum of 10° or by a maximum of 5°. In particular, a friction drive pulley of the drive can be arranged between the counterweight and the elevator car in a plan view of the elevator installation.

Preferred embodiments include at least one further drive system. In particular, elevator installations include at least one further drive system according to the embodiments described herein. The drive system and the at least one further drive system can be arranged on opposite sides of the elevator car. The at least one further drive system preferably drives a further carrier means which is connected to the elevator car and in particular to a further counterweight. The use of at least two drive systems can offer the advantage that smaller or lighter drives can be used. In particular, the space requirement of a drive system can be reduced. For example, in a plan view of the elevator installation, a drive can be arranged between the elevator car and a shaft wall or a counterweight.

In preferred embodiments of the method for installation, mounting the drive comprises fastening a first suspension part of a drive suspension to the drive and a fixing part of the drive suspension to the support element. The mounting preferably includes connecting the first suspension part to the fixing part to form a rotary joint of the drive suspension. For example, the drive, together with the first suspension part, can be arranged relative to the fixing part, which is fastened to the support element, in such a way that at least one first opening of the first suspension part and at least one second opening of the fixing part are arranged along the axis of rotation of the rotary joint to be formed. A connecting means, for example a pin, a bolt, or a screw, can then be guided or arranged through the at least one first opening and the at least one second opening to form the rotary joint.

In preferred methods, stabilizing the drive includes connecting a second suspension part, which is fastened to the drive, to a fixing part to form an adjustment device. In further preferred methods, the stabilization includes fastening a second suspension part, which is connected to the fixing part, to the drive. After stabilization, for example, a friction drive pulley of the drive can be loaded with the weight of an elevator car and a counterweight to be borne by the drive system, without the drive being deflected significantly from the stabilized position of the drive. The second suspension part connected to the fixing part can be displaced relative to the fixing part in a settable manner. As a result, for example, setting a tilt after stabilization can be made possible.

Setting a tilt preferably includes aligning the drive relative to the support element by displacing the second suspension part relative to the fixing part. The displacement can be carried out

by rotating an adjustment screw of the adjustment device. In particular, a tilt about the axis of rotation of the rotary joint is set. In preferred methods, the drive is installed on a guide rail as a support element.

5 Preferred embodiments can offer the advantage over the prior art that a drive can be installed on a support element, for example on a guide rail, in a space-saving manner. In particular, according to preferred embodiments, drive systems can be installed without superstructures on or above the guide rail or without a machinery room. Drive systems according to preferred
10 embodiments can be installed in elevator shafts with low shaft heads. In particular, according to embodiments, drive systems can be equipped with particularly small or light drives. Preferred embodiments can also offer the advantage that a tilt of the drive with respect to the support element can be set. Skewing can be prevented or reduced in particular when a belt is used as the carrier means. The tilt can be readjusted over the lifetime of the elevator installation.

15 Various aspects of the invention are explained in more detail with reference to embodiments in conjunction with the drawings, in which:

Fig. 1 is a schematic view of a preferred embodiment of a drive system;

Fig. 2 is a schematic sectional view of a preferred embodiment of a drive system;

20 Fig. 3 is a schematic sectional view of a further preferred embodiment of a drive system;

Fig. 4 is a schematic view of a preferred embodiment of an elevator installation;

Fig. 5 is a schematic plan view of an elevator installation according to preferred embodiments; and

Fig. 6 is a schematic representation of a preferred method for installing a drive on a support
25 element of an elevator installation.

Fig. 1 is a schematic view of a drive system 1 according to a possible embodiment of the invention. The drive system 1 comprises a drive 3 which is fastened to a support element 5 via a drive suspension 7. In Fig. 1, the drive system 1 comprises a guide rail for guiding an elevator
30 car, the guide rail forming the support element 5. Fig. 2 is a schematic sectional view of the drive system 1. The sectional view shows a section along a shaft axis 61 of a drive shaft 15 of the drive 3 parallel to a longitudinal axis of the guide rail. In Fig. 1 and 2, the shaft axis 61 of

the drive 3 is aligned at least substantially perpendicularly to the axis of rotation 31 of the rotary joint 9. In particular, the drive system 1 is designed such that the shaft axis 61 runs at least substantially parallel to a drive-side side wall of an elevator car.

5 The drive suspension 7 comprises a rotary joint 9 for tiltably mounting the drive 3 on the support element 5. The rotary joint 9 comprises a fixing part 21 which is fastened to the support element 5. The rotary joint 9 also comprises a first suspension part 23 which is fastened to the drive 3. The fixing part 21 is rigidly connected to the support element 5 and the first suspension part 23 is rigidly connected, in particular screwed, to the drive 3. In the embodiments of
10 Fig. 1 and 2, the first suspension part 23 has two first openings along the axis of rotation 31 of the rotary joint 9. As shown, for example, in Fig. 2, the fixing part 21 extends between the two first openings of the first suspension part 23, with a second opening of the fixing part 21 being arranged between the two first openings of the first suspension part 23. The hinge-like interlocking of the fixing part and the first suspension part can, for example, increase the flex-
15 ural rigidity of the rotary joint 9 with respect to torques perpendicular to the axis of rotation 31 of the rotary joint 9, in particular with respect to torques in the direction of the longitudinal axis of the guide rail. A connecting means 29 is arranged so as to pass through the two first openings and the second opening. In Fig. 1 and 2, the connecting means 29 is designed as a bolt, in particular as a threaded bolt, which is guided through the first openings and the second
20 opening and fixed with a nut.

The drive suspension 7 comprises an adjustment device 11. The adjustment device 11 comprises the fixing part 21 and a second suspension part 41. The second suspension part 41 can be linearly displaced relative to the fixing part 21. In the embodiment of Fig. 2, the second
25 suspension part 41 can be displaced relative to the fixing part 21 by rotating an adjustment screw 43 of the adjustment device 11. By displacing the second suspension part 41 relative to the fixing part 21, a tilt of the drive 3 about the axis of rotation 31 of the rotary joint 9 relative to the support element 5 can be set or adjusted. In particular, a tilt of the drive shaft 15 and a friction drive pulley 13 arranged on the drive shaft 15 relative to the support element 5 can
30 also be set. Setting the tilt of the friction drive pulley 13 can prevent or reduce skewing of the belt, for example when using a belt as a carrier means.

The drive suspension 7 of Fig. 1 and 2 comprises isolation elements 47 which are arranged

between the first suspension part 23 and the fixing part 21 and between the second suspension part 41 and the fixing part 21. In particular, a further isolation element 47 is arranged around the connecting means 29 in the region of the first opening of the first suspension part 23 and in the region of the second openings of the fixing part 21. The isolation elements 47 are designed to reduce, in particular to damp, the propagation of vibrations or structure-borne noise from the drive 3 to the support element 5.

The drive 3 is designed as a gearless electric motor in Fig. 2. The drive suspension 7 comprises an adapter plate 33 which is fastened to the electric motor. The first suspension part 23 and the second suspension part 41 are fastened to the drive 3 via the adapter plate 33. The drive 3 comprises drive electronics 35 and a drive cooling system 37. In Fig. 1 and 2, the drive electronics 35 and the drive cooling system 37 are arranged on an underside of the drive 3. As a result, the space requirement of the drive 3 in horizontal directions can be reduced, for example.

Fig. 3 is a view of a further embodiment of a preferred drive system 1. In Fig. 3, the fixing part 21 has two second openings along the axis of rotation 31 of the rotary joint 9. The first suspension part 23 extends between the two second openings of the fixing part 21, with a first opening of the first suspension part 23 being arranged between the two second openings. A connecting means 29 extends through the two second openings and the first opening. In Fig. 3, the fixing part 21 comprises a frame structure 40, which is fastened to the support element, and intermediate blocks 39, in each of which blocks a second opening of the fixing part 21 is formed. In particular, the intermediate blocks 39 can transmit loads between the connecting element 29 and the frame structure 40. The frame structure 40 and the intermediate blocks 39 are rigidly connected to one another, for example screwed together, in Fig. 3.

In Fig. 3, the adjustment device 11 comprises a second suspension part 41 which partially encloses the friction drive pulley 13 of the drive 3. The second suspension part 41 is designed in the form of a cage around the friction drive pulley 41, the cage-shaped second suspension part 41 having windows for a carrier means to pass through. On the side of the second suspension part 41 that faces the support element 5, the adjustment device 11 has an adjustment screw for setting the tilt of the drive 3 with respect to the support element 5. Isolation elements 47 are arranged between the first suspension part 23 and the fixing part 21 and between the second

suspension part 41 and the fixing part 21. In the embodiment of Fig. 3, the first suspension part 23, the second suspension part 41, and the adapter plate 33 are formed in one piece. A one-piece design can in particular give a drive suspension a high level of stability.

Fig. 4 and 5 show an embodiment of an elevator installation 51. The elevator installation 51 comprises a drive system 1 according to the embodiments described herein comprising a drive 3 and a drive suspension 7 for fastening the drive 3 to a support element 5. A guide rail for guiding an elevator car 53 is provided as the support element 5 in Fig. 4 and 5. The elevator car 53 is connected to a counterweight 55 via a carrier means 57. The carrier means 57, for example a belt, is guided over a friction drive pulley 13 of the drive 3. The drive 3 is designed to drive the carrier means 57 and to move the elevator car 53 and the counterweight 55 vertically.

In Fig. 4 and 5, the drive 7 is arranged in an upper end region of the elevator installation 51. As shown by way of example in the plan view of the elevator installation 51 in Fig. 5, a shaft axis 61 of the drive 3 is aligned at least substantially parallel to a drive-side side wall 63 of the elevator car 53. The axis of rotation 31 of a rotary joint of the drive suspension 7 is oriented at least substantially perpendicularly to the shaft axis 61 and at least substantially perpendicularly to a vertical direction. The tilt of the shaft axis 61 with respect to a vertical direction or with respect to the longitudinal axis of the guide rail is set, for example, so as to be at least substantially perpendicular.

The elevator installation 51 of Fig. 4 and 5 has a further drive system 71 according to the embodiments of a drive system described herein. The further drive system 71 comprises a further drive 73 and a further drive suspension 75 for fastening the further drive 73 to a further support element 79, which is formed by a further guide rail in Fig. 4 and 5. The further drive 73 is designed to drive a further carrier means 81 which is connected to the elevator car 53 and a further counterweight 77. The use of a further drive system can allow the use of smaller or lighter drives. In particular, the space requirement of a drive in a shaft head or a shaft pit can be reduced. In addition, smaller or lighter drives can be installed more easily.

Fig. 6 shows a method 100 for mounting a drive on a support element of an elevator installation in an embodiment. At 110, the method 100 includes mounting the drive on the support

element via a rotary joint. For example, a fixing part of a drive suspension is fastened, for example screwed tight, to a guide rail at 110. A first suspension part and a second suspension part are fastened to the drive via an adapter plate. The drive is then positioned in such a way that a bolt is guided through at least one first opening of the first suspension part and at least one second opening of the fixing part to form a hinge-like rotary joint. The bolt is fixed with a nut. The method can offer the advantage that the drive can be positioned and mounted on the support element manually, for example.

After mounting, the drive is stabilized with respect to the support element at 120. In the embodiment, the second suspension part is connected to the fixing part to form an adjustment device, with the second suspension part and the fixing part being displaceable relative to one another in a settable manner via an adjustment screw after the connection. In particular, the drive can no longer be moved freely about the axis of rotation of the rotary joint after stabilization; rather, it can only be moved by rotating the adjustment screw.

At 130, a tilt of the drive about the rotary joint is set by rotating the adjustment screw. The tilt of the drive or the shaft axis of the drive is set in such a way that the shaft axis runs at least substantially perpendicularly to a vertical direction or such that a skewing of a belt is prevented or reduced.

Claims

1. Drive system (1) for an elevator installation, comprising

a drive (3), and

5 a drive suspension (7) for fastening the drive (3) to a support element (5) of the elevator installation,

wherein the drive suspension (7) comprises:

- a rotary joint (9) for tiltably mounting the drive (3) on the support element (5); and

- an adjustment device (11) for setting a tilt of the drive (3) about the rotary joint (9).

10 2. Drive system (1) according to claim 1, comprising a guide rail for guiding an elevator car, wherein the guide rail forms the support element (5).

3. Drive system (1) according to either of the preceding claims, wherein the rotary joint (9) comprises:

a fixing part (21) which is designed for fastening to the support element (5); and

15 a first suspension part (23) which is fastened to the drive (3);

wherein the fixing part (21) and the first suspension part (23) are rotatably connected to each other.

4. Drive system (1) according to claim 3, wherein the first suspension part (23) has at least one first opening and the fixing part (21) has at least one second opening; and wherein the rotary joint (9) comprises a connecting element (29) which is arranged so as to pass through the
20 at least one first opening and the at least one second opening.

5. Drive system (1) according to any of the preceding claims, wherein the adjustment device (11) comprises:

a fixing part (21) which is designed for fastening to the support element (5); and

a second suspension part (41) which is fastened to the drive (3) and connected to the fixing part (21);

wherein the fixing part (21) and the second suspension part (41) are displaceable relative to one another in a settable manner.

6. Drive system (1) according to claim 5, wherein the tilt of the drive (3) about the rotary joint (9) can be set by displacing the second suspension part (41) relative to the fixing part (21).

7. Drive system (1) according to any of the preceding claims, wherein the rotary joint (9) is arranged above a friction drive pulley (13) of the drive (3); and wherein the adjustment device (11) is arranged below the friction drive pulley (13).

8. Drive system (1) according to any of the preceding claims, wherein an axis of rotation (31) of the rotary joint (9) is at least substantially perpendicular to a shaft axis (61) of the drive (3) and/or wherein the rotary joint (9) is designed to support torques or torque components in directions perpendicular to the axis of rotation (31).

9. Drive system (1) according to any of the preceding claims, wherein the drive suspension (7) comprises at least one isolation element (47), wherein the at least one isolation element (47) is designed to reduce or prevent a transmission of vibrations or structure-borne noise from the drive (3) to the support element (5).

10. Elevator installation (51), comprising

a drive system (1) according to any of the preceding claims;

an elevator car (53); and

a counterweight (55) which is connected to the elevator car (53) via a carrier means (57);

wherein the drive (3) is designed to drive the carrier means (57).

11. Elevator installation (51) according to claim 10, wherein the drive (3) is arranged in an upper end region of the elevator installation (51).

12. Elevator installation (51) according to either claim 10 or claim 11, wherein the carrier means (57) comprises a belt.

13. Elevator installation (51) according to any of claims 10 to 12, wherein the elevator car (53) has a drive-side side wall (63) that faces the drive system (1); and wherein a shaft axis (61) of the drive runs at least substantially parallel to the drive-side side wall (63).

14. Elevator installation (51) according to any of claims 10 to 13, wherein the elevator installation (51) comprises at least one further drive system (71).

15. Method for installing a drive (3) on a support element (5) of an elevator installation (51), in particular an elevator installation (51) according to any of claims 10-14, comprising

mounting the drive (3) on the support element (5) by means of a rotary joint (9);

stabilizing the drive (3) with respect to the support element (5); and

setting a tilt of the drive (3) about the rotary joint (9).