FIG. 4

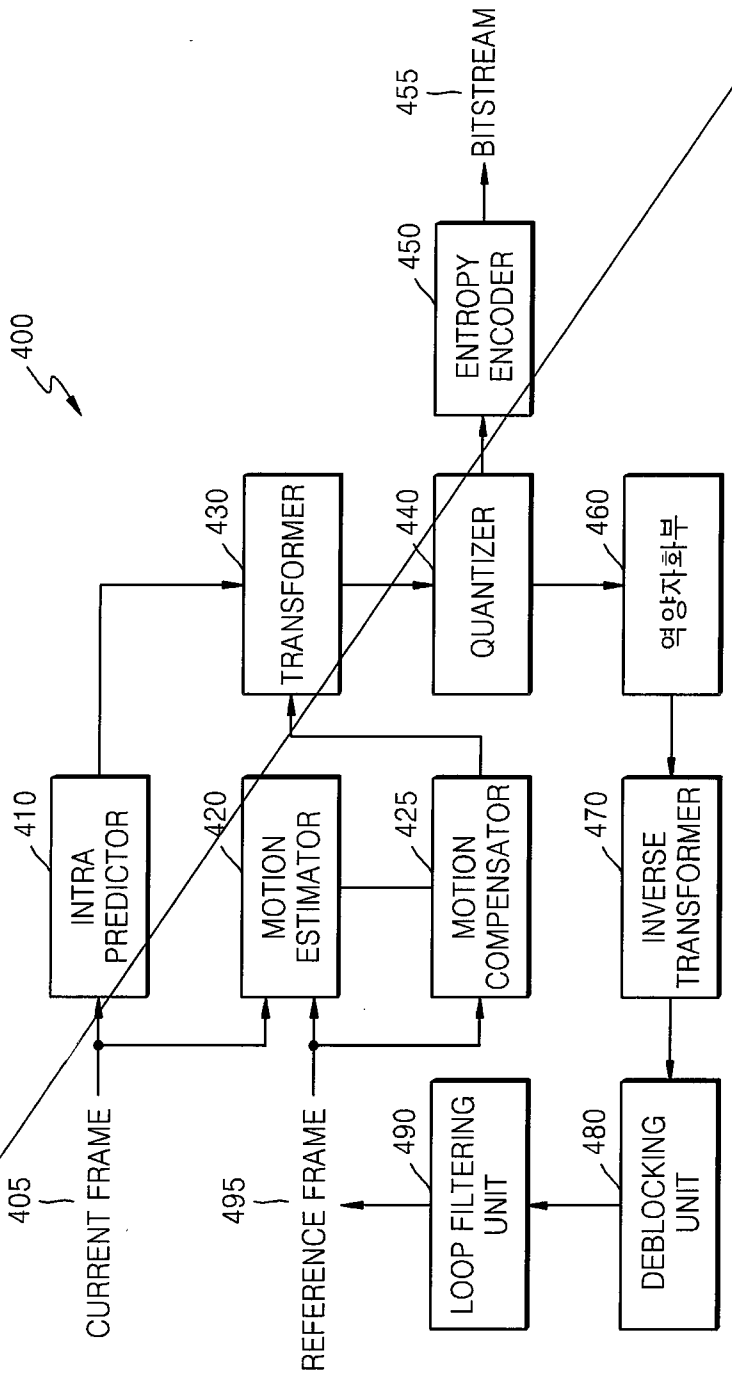
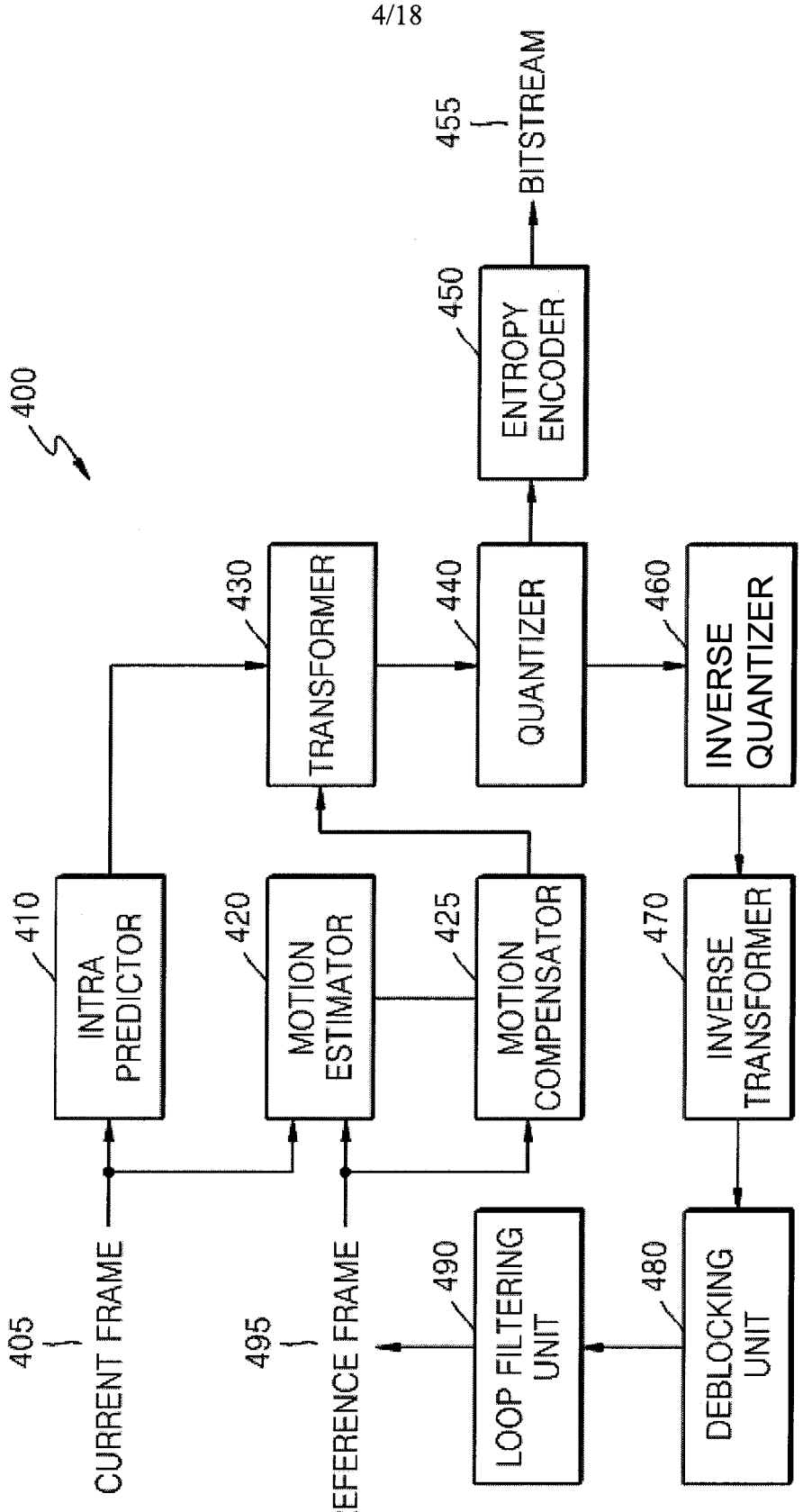

400
405
CURRENT FRAME
410
INTRA PREDICTOR
420
MOTION ESTIMATOR
425
MOTION COMPENSATOR
430
TRANSFORMER
440
QUANTIZER
450
ENTROPY ENCODER
455
BITSTREAM
460
역양자화부
470
INVERSE TRANSFORMER
480
DEBLOCKING UNIT
490
LOOP FILTERING UNIT
495
REFERENCE FRAME

FIG. 4


400
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CURRENT FRAME
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INTRA PREDICTOR
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LOOP FILTERING UNIT
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REFERENCE FRAME