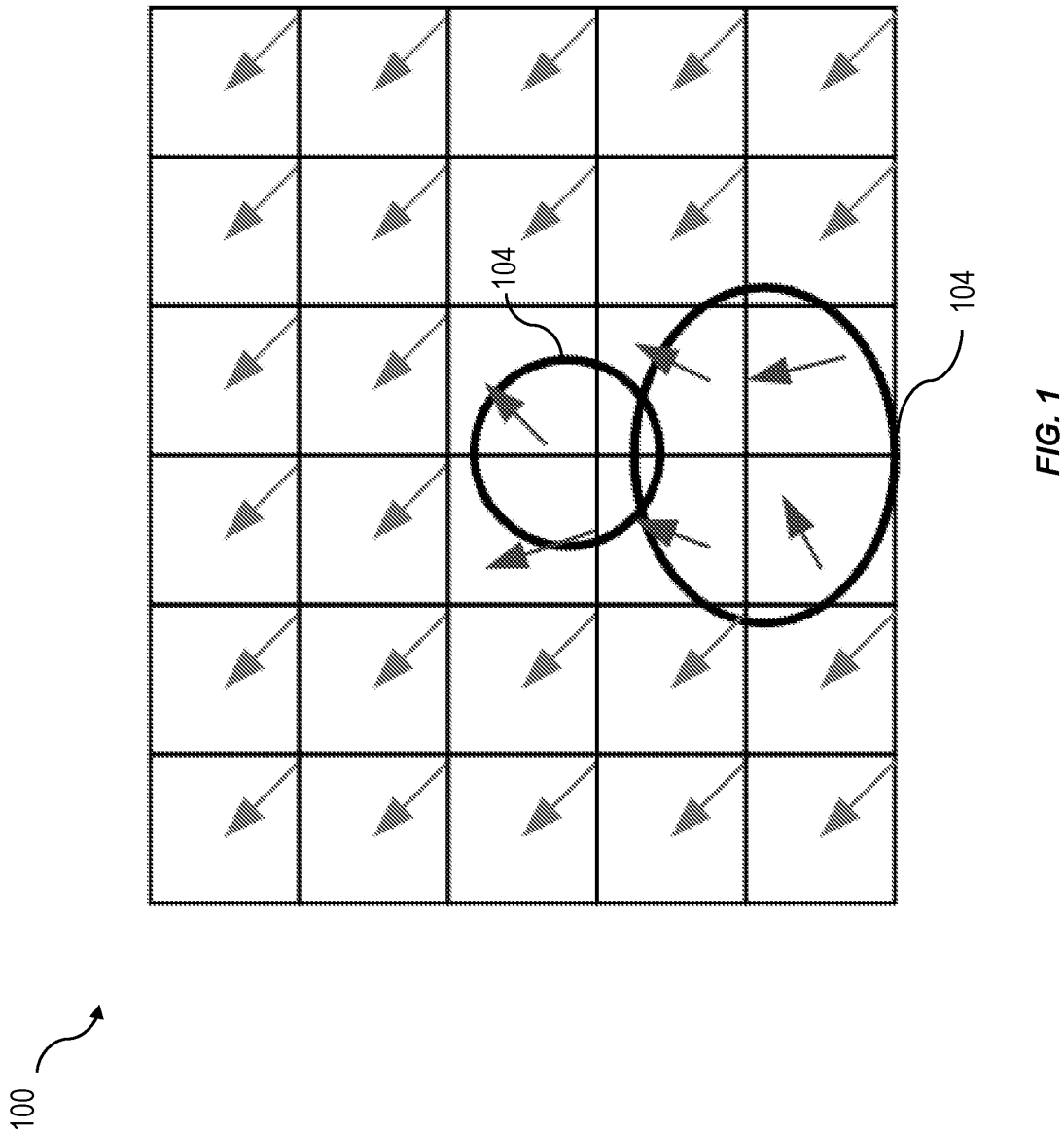




200 

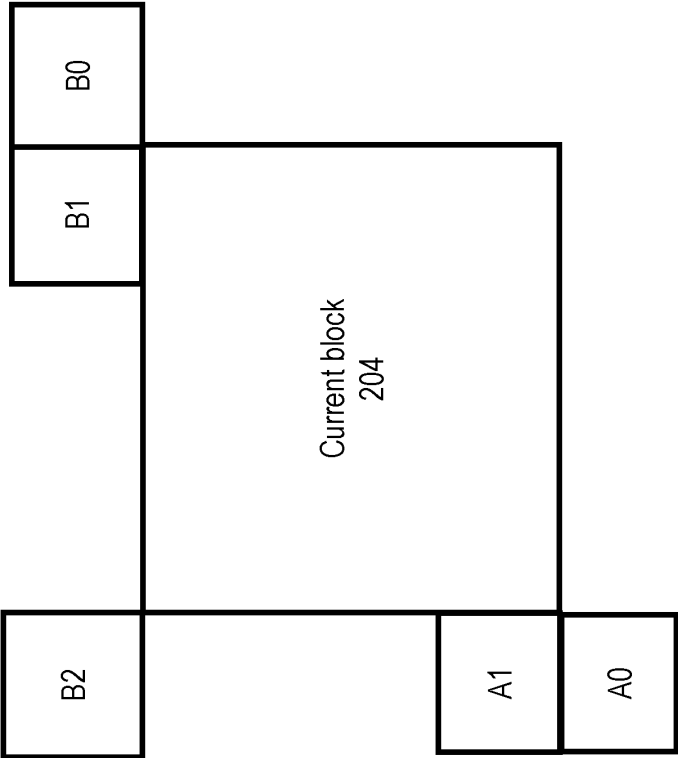


FIG. 2

300 

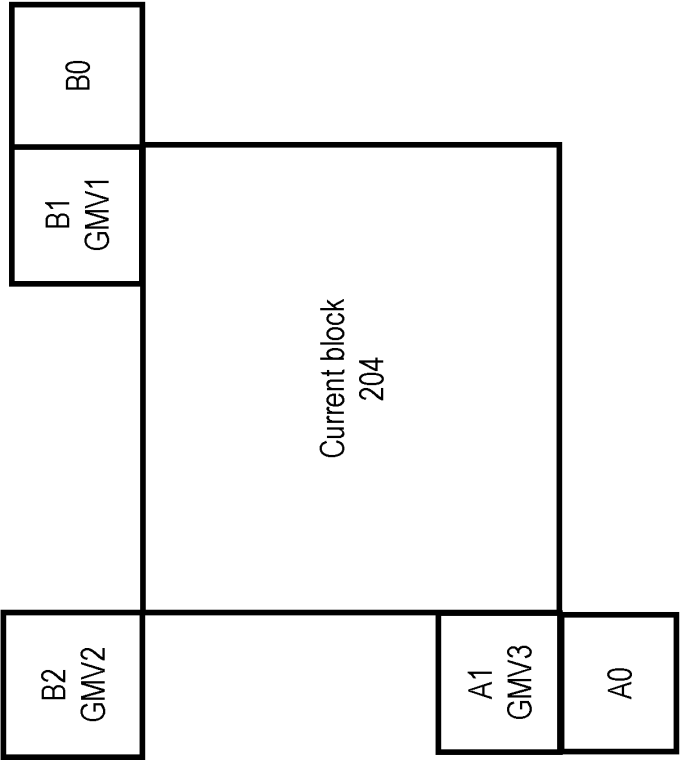


FIG. 3

400 

MotionModelIdx[x][y]	Motion model for motion compensation
0	Translational motion
1	4-parameter affine motion
2	6-parameter affine motion

FIG. 4

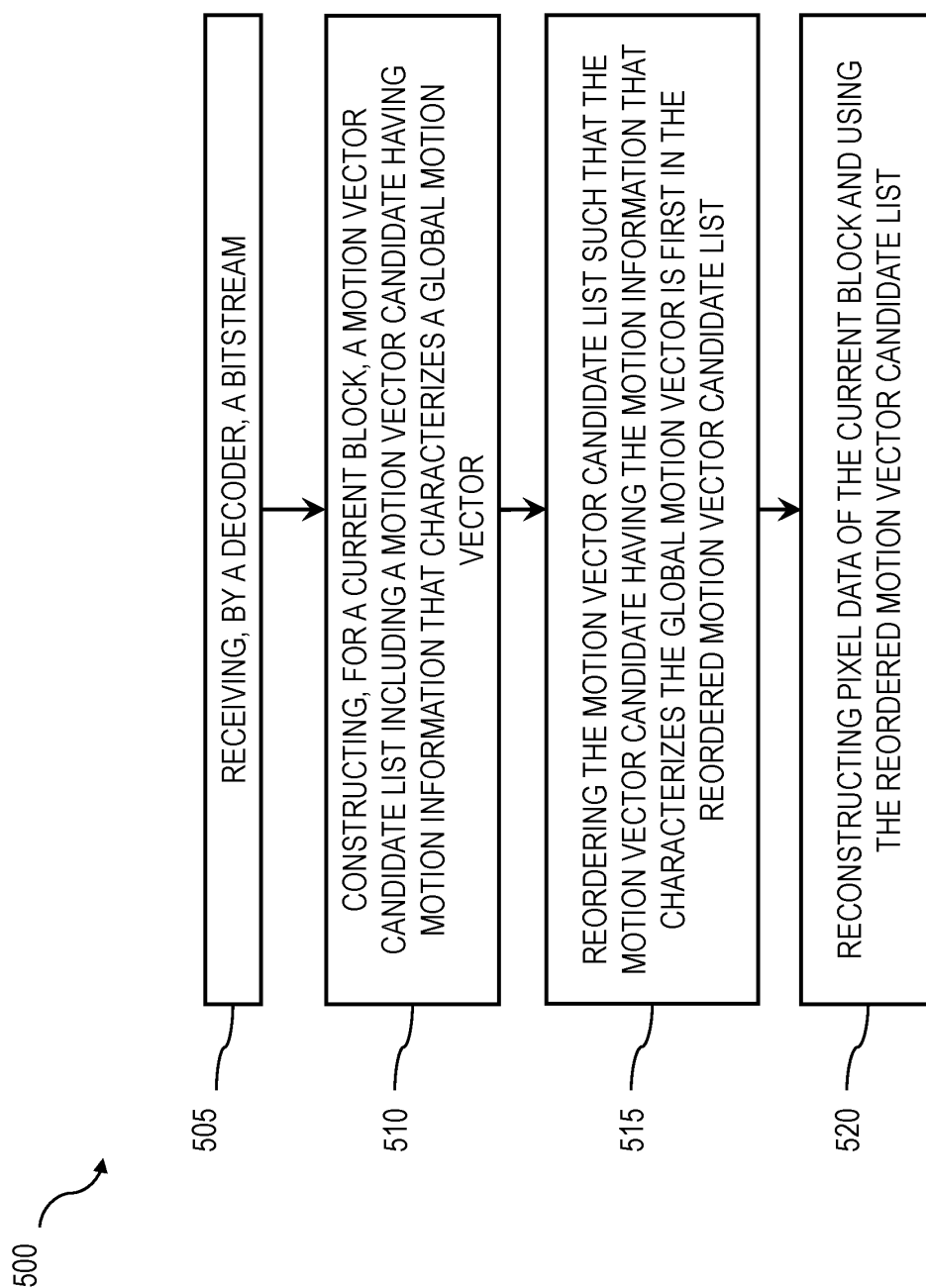


FIG. 5

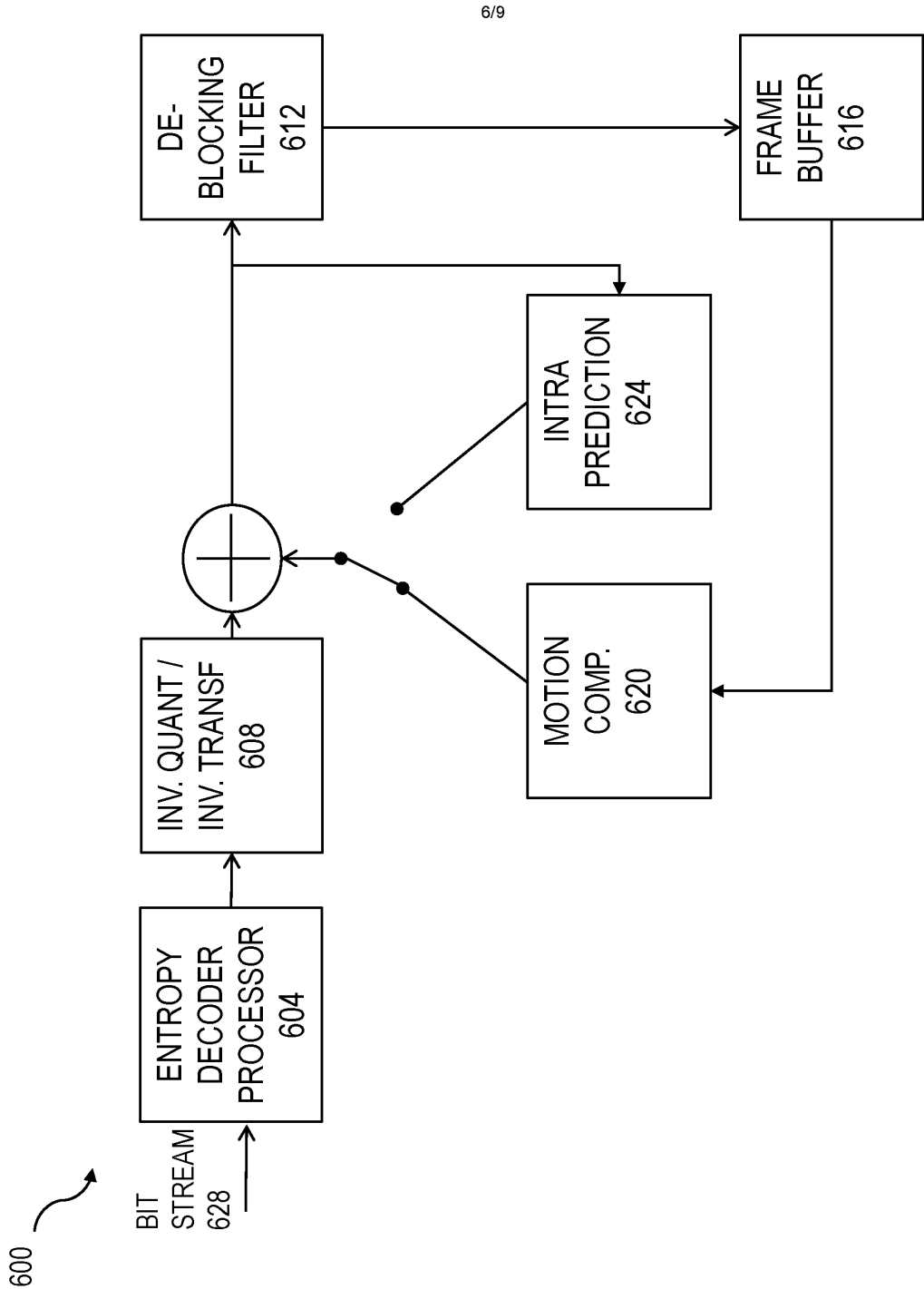


FIG. 6

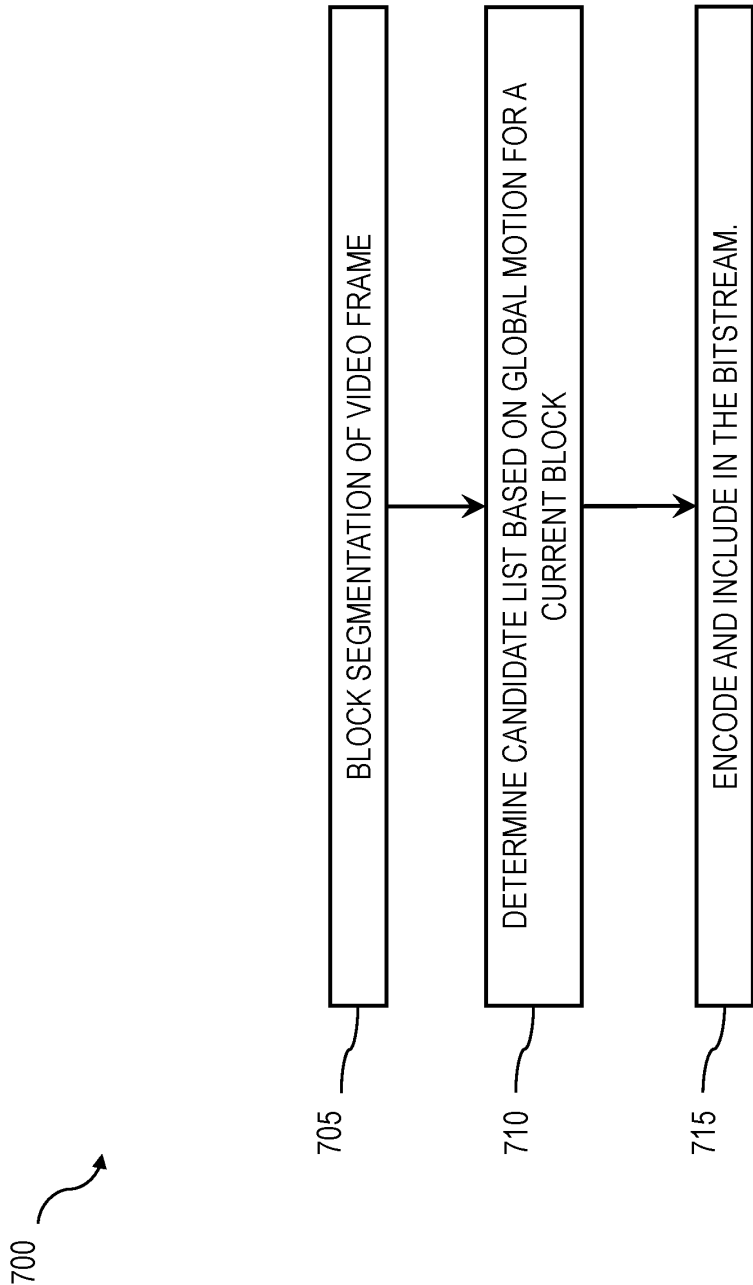


FIG. 7

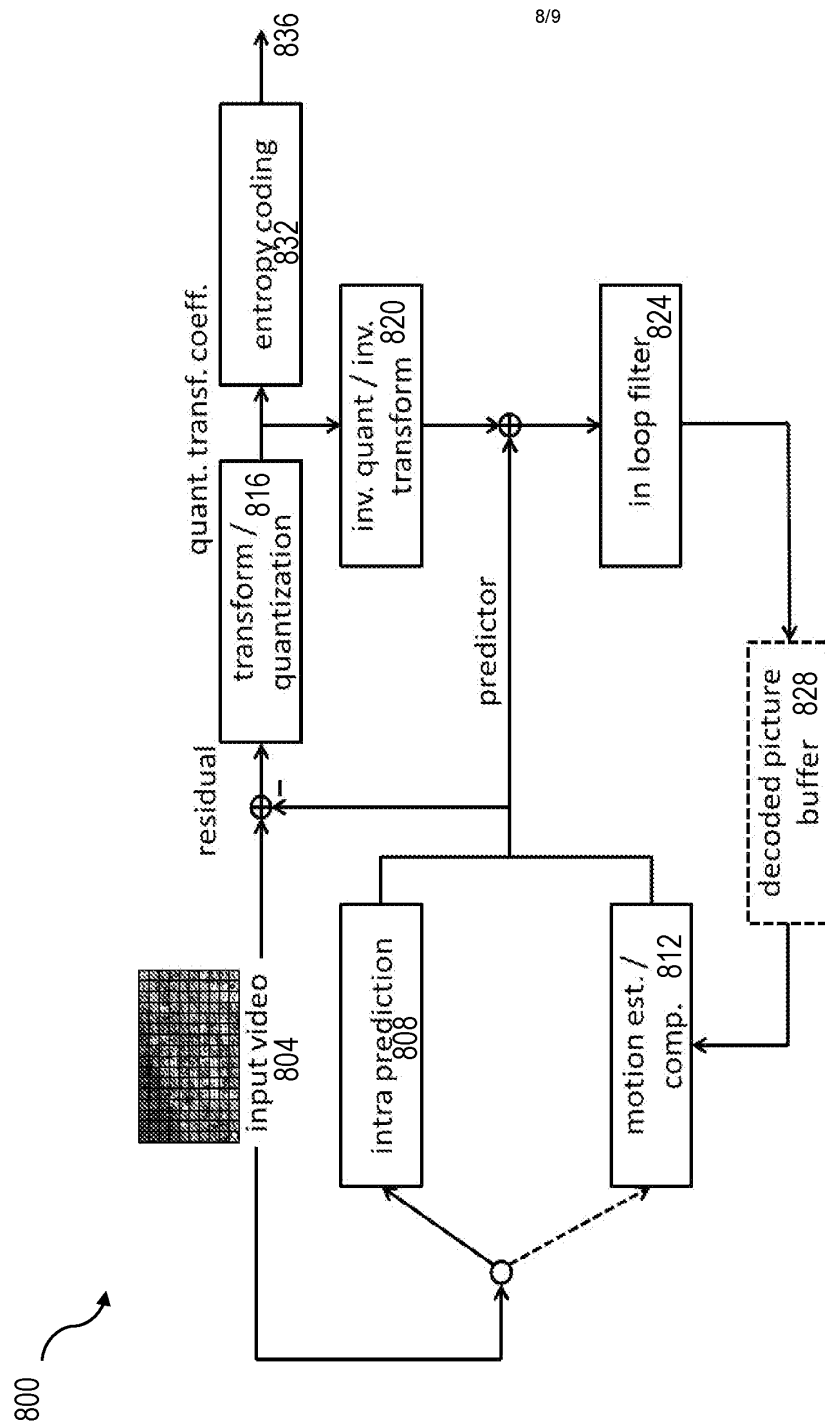


FIG. 8

