

MULTI-AXIS VIBRATION METHOD AND APPARATUS

BACKGROUND

Electronic products and in particular, portable electronic products are susceptible to vibration. Vibration can interfere with operation and degrade lifetime performance of such products. For example, various portable electronic products, such as mobile phones, include data storage devices, which have rotating data storage elements. Vibration can interfere with the operation of said rotating data storage elements.

SUMMARY

The present application relates to a vibration test apparatus and method. The vibration test apparatus includes a platform assembly, which receives a vibration input from a vibration source and imparts a multi-axial vibration to a test specimen on the platform assembly. In illustrated embodiments the platform assembly includes one or more platforms having an adjustable incline angle. The incline angle is adjusted to provide the desired output vibration based upon a measured or determined vibration profile. Other features and benefits that characterize embodiments of the present invention will be apparent upon reading the following detailed description and review of the associated drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a schematic illustration of a portable electronic device susceptible to vibration.

FIG. 2 schematically illustrates a test apparatus including a platform assembly and vibration source.

FIG. 3 is a schematic illustration of a first inclined platform of a platform assembly for a test apparatus as illustrated in FIG. 2.

FIG. 4 is a schematic illustration of a second inclined platform of a platform assembly for a test apparatus as illustrated in FIG. 2.

FIG. 5 schematically illustrates an embodiment of a platform assembly including a plurality of adjustable platforms.

FIG. 6 schematically illustrates an embodiment of a bracket portion for hinge assemblies for pivotally connecting inclined platforms of the platform assembly illustrated in FIG. 5.

FIG. 7 is a cross-sectional view taken along line 7—7 of FIG. 6.

FIG. 8 is a flow chart illustrating steps for vibration testing using a test apparatus including an input vibration and one or more adjustable inclined platforms.

FIGS. 9-11 graphically illustrate measured vibration for use in determining vibration input for a vibration test apparatus as illustrated in FIG. 2.

DETAILED DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS

Device such as portable electronic devices of the type illustrated in FIG. 1 are exposed to vibration during use. Such vibration can interfere with operation of the device. The device illustrated in FIG. 1 is a mobile phone device 100, which includes a data storage media 102 enclosed within a housing or casing 104 of the device. The device 100 also includes host component(s) 106 that interface with the data storage media 102 to read and/or write data to the data storage media 102. Illustratively, the data storage media 102 includes one or more rotating discs and one or more adjustable heads to read and/or write data to the rotating discs. Vibration of the device 100 can interfere with operation of the data storage media, and in particular, operation of the one or more heads and discs, or other components of the device. Typically electronic devices include damping components or other design features to limit the effects of vibration. Damping components or features can be designed utilizing mathematical modeling techniques, however, mathematical modeling techniques may not adequately predict actual vibration performance.

FIG. 2 illustrates an embodiment of a test apparatus 120 for testing vibration performance of a test specimen 122 such as the portable electronic device 100 of the type illustrated in FIG. 1. The illustrated test apparatus 120 includes a platform assembly 124, which is configured to receive a vibration input F_{input} from a vibration source 126 and output a multi-axial vibration to the test specimen 122 supported on or coupled to the platform assembly 124. Illustratively, the vibration source 126 is a shaker device or similar device, which provides an input vibration along a single axis such as one of the x, y or z axes illustrated in FIG. 2.

In the embodiment illustrated in FIG. 2, the platform assembly 124 includes a base

portion 130, a first inclined platform 132 coupled to the base portion 130 and a second inclined platform 134 coupled to the first inclined platform 132. As shown the first inclined platform 132 is coupled to the base portion 110 at an incline angle θ_1 . The second inclined platform 134 is coupled to the first inclined platform 132 at an incline angle θ_2 to impart a multi-axial vibration to the test specimen 122 supported on the second platform 134 as shown. The axis of incline angle θ_2 is orthogonal to the axis of incline angle θ_1 .

As previously described, the multi-axial vibration is imparted to the test specimen 122 through the platform assembly 124 in response to the vibration input F_{input} from the vibration source 126. In the embodiment illustrated in FIG. 2, the platform assembly 124 is orientated to receive a vibration input F_{input} along the z-axis (i.e., $F_{input} = F_{input-z}$), although application is not limited to a particular orientation or F_{input} . For example, the input vibration from the vibration source 126 can be orientated relative to the x, y or z axes to provide $F_{input} = F_{input-x}$, $F_{input} = F_{input-y}$, or $F_{input} = F_{input-z}$.

FIGS. 3-4 illustrate components of the platform assembly 124 illustrated in FIG. 2. As shown in FIG. 3, the first platform 132 is coupled to base platform 138 and receives input vibration F_{input} from the vibration source 126 to provide multi-axis vibration components through the first platform as follows:

$$F_1 = F_{input} \cos\theta_1;$$

$$F_2 = F_{input} \sin\theta_1$$

where F_{input} is the input vibration from the vibration source 126; and

θ_1 is the incline angle of the first platform 132.

In the illustrated embodiment shown, where $F_{input} = F_{input-z}$ and the first platform 132 is inclined relative to the y axis at angle θ_1 the force components are provided as follows:

$$F_z = F_{input-z} \cos \theta_1; \text{ and}$$

$$F_x = F_{input-z} \sin \theta_1$$

FIG. 4 illustrates the second platform 134 inclined at angle θ_2 relative to first platform 132. As shown in FIG. 4, the second platform 134 is coupled to the first platform 132 and receives input vibration components $F_{input1} = F_{input} \cos\theta_1$ and $F_{input2} = F_{input} \sin\theta_1$

to provide a multi-axial test vibration through the second platform 134 including vibration components as follows:

$$\begin{aligned} F_1 &= F_{\text{input}} \cos \theta_1 \cos \theta_2; \\ F_2 &= F_{\text{input}} \cos \theta_1 \sin \theta_2; \\ F_3 &= F_{\text{input}} \sin \theta_1 \end{aligned}$$

In the illustrated embodiment shown, where $F_{\text{input}} = F_{\text{input}-z}$ and the first platform 132 is inclined relative to the y axis at θ_1 and the second platform 134 is inclined relative to the x axis at θ_2 , the platform assembly 124 provides vibration components:

$$\begin{aligned} F_z &= F_{\text{input}-z} \cos \theta_1 \cos \theta_2; \\ F_y &= F_{\text{input}-z} \cos \theta_1 \sin \theta_2; \\ F_x &= F_{\text{input}-z} \sin \theta_1 \end{aligned}$$

where $F_{\text{input}-z}$ is an input vibration from the vibration source 126 orientated along the z axis;

θ_1 is the incline angle of the first platform 132 relative to the y-axis.

θ_2 is the incline angle of the second platform 134 relative to the x-axis.

In the platform assembly 124 shown in FIG. 2, the first platform 132 is inclined relative to the base portion 110 and the second platform 134 is inclined relative to the first platform 132 to provide the multi-axis test vibration to the test specimen 122 through the platform assembly 124. FIGS. 5-7 illustrate an embodiment of a platform assembly 124 where the first platform 132 is pivotally coupled to the base portion 130 and the second platform 134 is pivotally coupled to the first platform 132 to provide adjustable incline angles θ_1 and θ_2 for platforms 132, 134 respectively. The incline angles θ_1 and θ_2 are adjusted to provide a desired vibration profile to the test specimen 122.

In the embodiment illustrated in FIG. 5, the first platform 132 is pivotally coupled to a base portion or platform (not visible in FIG. 5) through a hinge assembly 150 and the second platform 134 is pivotally coupled to the first platform 132 via hinge assembly 152. As shown in FIG. 5 each of the hinge assemblies 150, 152 includes a plurality of bracket portions to pivotally connect the first platform 132 to the base portion and the second platform 134 to the first platform 132. In the embodiments shown in FIG. 5, the plurality

of bracket portions includes bracket portions 160-1, 160-2 connected to a perimeter edge of the base portion (not visible in FIG. 5) and bracket portions 160-3, 160-4 connected to a perimeter edge of the first platform 132. The bracket portions 160-1, 160-2, 160-3, 160-4 are connected to the base portion and the first platform 132, respectively, via fasteners 162. In the illustrated embodiment fastener 162 is a bolt however, application is not limited to a bolt fastener and other fastening devices or adhesives can be used. Bracket portions 160-3, 160-4 rotate relative to bracket portions 160-1, 160-2 to adjust the incline angle θ_1 of the first platform 132 relative to the base portion 110.

Similarly, hinge assembly 152 includes bracket portions 160-1, 160-2 connected to a perimeter edge of the first platform 132 and bracket portions 160-3, 160-4 connected to a perimeter edge of the second platform 134. Bracket portions 160-3, 160-4 rotate relative to bracket portions 160-1, 160-2 to adjust the incline angle θ_2 of the second platform 134 relative to the first platform 132. Although a particular number of bracket portions are shown for hinge assemblies 150, 152, application is not limited to the particular number shown as the hinge assemblies 150, 152 can include any number of bracket portions.

Bracket portions 160-3 and 160-4 rotate relative to bracket portions 160-1, 160-2 via an elongate rod 163 that rotationally connects the plurality of bracket portions 160-1 - 160-4 along a rotation axis. In the illustrated embodiment, bracket portions of the hinge assembly 150 rotate about a first rotation axis 164-1 and the bracket portions of the hinge assembly 152 rotate about a second rotation axis 164-2 orthogonal to the first rotation axis 164-1 to provide orthogonal incline angles θ_1 and θ_2 . In the illustrated embodiment, the first rotation axis 164-1 is aligned with the y-axis and the second rotation axis 164-2 is aligned with the x-axis. In an alternate embodiment, the first rotation axis 164-1 is aligned with the x-axis and the second rotation axis 164-2 is aligned with the y-axis, as application is not limited to any specific orientation for the vibration source 126 or platform assembly 124.

FIG. 6 is a detailed illustration of an embodiment of the bracket portions 160-1 - 160-4 of the hinge assemblies 150, 152. As shown, bracket portions 160-1 through 160-4 include rigid end portions 170 and a flexible inner portion 172 between the rigid end portions 170. Rod 163 extends through a channel 174 formed through the rigid end portions 170 and the flexible inner portion 172 to form the rotation axes 164-1 and 164-2 as previously described.

As shown in FIG. 7, the flexible inner portion 172 forms a clamping mechanism to restrict rotation of the bracket portions in a clamp position and allow rotation of the bracket portions in an unclamped position to adjust incline angles θ_1 and/or θ_2 as previously described. The flexible inner portion 172 includes a “U” shaped body forming a channel portion 180 and opposed flexible arm portions 182 separated by a gap 184. Rod 163 extends through channel portion 180 to provide the pivotal connection for the bracket portions. The spacing or gap 184 for the opposed flexible arm portions 182 is adjusted to adjust the diameter or dimension of the channel portion 180 to selectively clamp and release the bracket portions relative to rod 163. The spacing or position of the opposed flexible arm portions 182 is adjusted via a bolt 186 that extends through arm portions 182 and gap 184 to adjust the spacing between flexible arm portions 182.

To clamp or lock the incline angles θ_1 and/or θ_2 , the bolt 186 is tightened to reduce the spacing or gap between the arm portions 182 so that the flexible inner portion 172 squeezes against rod 163 to restrict rotation of the bracket portions about rod 163. To release the hinge assemblies 150 and/or 152, the bolt 186 is loosened to increase the spacing or gap 184 to facilitate rotation of the bracket portion about rod 163 to adjust the incline angles θ_1 and/or θ_2 as previously described. In the embodiment illustrated in FIG. 5, the platform assembly includes first and second adjustable platforms, however application is not limited to the particular embodiment shown. For example, in one embodiment, the platform assembly 124 can include one or more adjustable incline platforms depending upon the desired vibration profile.

FIG. 8 is a flow chart for vibration testing. As shown, the vibration profile for the test apparatus is determined in step 200 to provide a desired vibration test profile. In an illustrated embodiment, the vibration profile is determined by measuring vibration on a test device using an accelerometer or other measurement device. The accelerometer is coupled to the test device to measure vibrations. For example, the accelerometer can be coupled to a mobile phone device or casing to measure vibration input to a data storage media of the mobile phone device. In an illustrated example, the accelerometer is an tri-axial accelerometer to measure tri-axial vibration components for the test application.

The measured vibration or profile is used to determine input vibration components for the test apparatus 120 as shown in step 202. In particular, in step 202, the measured vibration is used to calculate input vibration F_{input} for the vibration source 126 and incline

angles θ_1 and θ_2 for platforms of a test apparatus. As shown in step 204, the platforms are adjusted to the incline angles calculated in step 202 and locked into position for testing. For testing, the test specimen 122 is secured to the platform assembly 124 and the vibration input F_{input} from the vibration source 126 is supplied to the platform assembly 124 as shown in step 206 as previously described. The test specimen 122 is secure to the platform assembly 124 of the test apparatus via fasteners or an adhesive and application is not limited to any particular device for securing the test specimen 122 to the platform assembly 124 for testing.

In the illustrated embodiment, test components F_x , F_y and F_z are derived based upon measurement data for x, y, z tri-axial vibration components 210, 212, 214 of a test device as illustrated in FIGS. 9-11, respectively. The incline angles θ_1 and θ_2 of the platform assembly 124 and the F_{input} for the vibration source 126 are calculated using the following equations to provide the desired or measured vibration components F_x , F_y and F_z .

$$F_{input} = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

$$\Theta_1 = \sin^{-1} \left(\frac{F_x}{F_{input}} \right)$$

$$\Theta_2 = \sin^{-1} \left(\frac{F_y}{F_{input} \cos \Theta_1} \right)$$

It is to be understood that even though numerous characteristics and advantages of various embodiments of the invention have been set forth in the foregoing description, together with details of the structure and function of various embodiments of the invention, this disclosure is illustrative only, and changes may be made in detail, especially in matters of structure and arrangement of parts within the principles of the present invention to the full extent indicated by the broad general meaning of the terms in which the appended claims are expressed. For example, the particular elements may vary depending on the particular application while maintaining substantially the same functionality without departing from the scope and spirit of the present invention.

WHAT IS CLAIMED IS:

1. A test apparatus comprising:

5 a platform assembly in combination with a vibration source including a base portion configured to receive a vibration input from the vibration source and a plurality of platforms pivotally coupled to the base portion at an adjustable incline angle to provide a multi-axis vibration through the at least one platform, the plurality of platforms including a first platform pivotally coupled to the base portion at a first incline angle and a second platform pivotally coupled to the first platform at a second incline angle.

15 2. The test apparatus of claim 1 wherein the first platform is pivotally coupled to the base portion to rotate about a first axis and the second platform is pivotally coupled to the first platform to rotate about a second axis orthogonal to the first axis.

3. The test apparatus of claim 2 wherein the first and second axes are orthogonal to an axis of the vibration input.

20 4. The test apparatus of claim 1 wherein the at least one platform is pivotally coupled to the base portion via a hinge assembly connecting the at least one platform to the base portion.

25 5. The test apparatus of claim 4 wherein the hinge assembly includes a clamping portion having a clamping position to restrict rotation of the hinge assembly and an unclamped position to adjust the incline angle of the at least one platform.

6. A vibration test platform assembly for a test apparatus comprising:
a base portion adapted to receive an input vibration from a vibration source; and

30

5 a first platform coupled to the base portion at a first incline angle and
configured to receive the input vibration and provide a multi-
axial vibration input to a second platform coupled to the first
platform at a second incline angle, and the second platform is
configured to receive the multi-axis vibration input and provide
a tri-axial vibration input to a test specimen.

10 7. The vibration test platform assembly of claim 6 wherein the first platform is
pivotally coupled to the base portion to adjust the first incline angle of the first
platform.

15 8. The vibration test platform assembly of claim 6 wherein the second platform is
pivotally coupled to the first platform to adjust the second incline angle of the second
platform.

9. The vibration test platform of claim 6 wherein the first incline angle is inclined
relative to a first axis and the second incline angle is inclined relative to a second axis
and the first and second axes are orthogonal.

20 10. The vibration test platform of claim 6 wherein the vibration output of the first
platform includes a first force $F_1 = F_{\text{input}} \cos \theta_1$ and second $F_2 = F_{\text{input}} \sin \theta_1$, where F_{input} is
the input vibration and θ_1 is the incline angle of the first platform.

25 11. The vibration test platform of claim 6 wherein the vibration output of the second
platform includes force components $F_1 = F_{\text{input}} \cos \theta_1 \cos \theta_2$; $F_2 = F_{\text{input}} \cos \theta_1 \sin \theta_2$; and
 $F_3 = F_{\text{input}} \sin \theta_1$ where F_{input} is the input vibration and θ_1 is the incline angle of the first
platform and θ_2 is the incline angle of the second platform.

30 12. A method comprising:
determining a multi-axial test vibration; and

5 configuring a platform assembly to impart the determined multi-axial
test vibration to a test specimen coupled to the platform
assembly wherein configuring the platform assembly comprises:
calculating an incline angle for a first platform of the platform
assembly and vibration input F_{input} to the platform assembly; and
adjusting the first platform to the calculated incline angle.

13. A method comprising:
determining a multi-axial test vibration; and
10 configuring a platform assembly to impart the determined multi-axial
test vibration to a test specimen coupled to the platform assembly wherein
configuring the platform assembly comprises:
calculating a first incline angle for a first platform;
calculating a second incline angle for a second platform coupled to the
15 first platform; and
adjusting the first and second platforms to the calculated first and
second incline angles for the first and second platforms.

14. The method of claim 12 or claim 13 and further comprising:
20 supplying an input vibration to the platform assembly to impart the
determined multi-axial test vibration through the platform
assembly.

15. The method of claim 14 wherein determining the multi-axial test vibration
25 comprises:
attaching an accelerometer device to a product specimen; and
receiving vibration data from the accelerometer.

16. The method of claim 15 wherein the accelerometer is a tri-axial accelerometer to
30 measure a tri-axial test vibration.

17. The method of claim 13 and comprising calculating an input vibration F_{input} to the platform assembly and the first and second incline angles using the equations:

$$F_{input} = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

5

$$\Theta_1 = \sin^{-1} \left(\frac{F_x}{F_{input}} \right)$$

$$\Theta_2 = \sin^{-1} \left(\frac{F_y}{F_{input} \cos \Theta_1} \right)$$

where F_{input} is the input vibration from a vibration source and F_z , F_y , F_x are the tri-axial test vibration components and θ_1 and θ_2 are the first and second incline angles.

10

18. The method of claim 13 wherein the step of adjusting the first and second platforms comprises:

releasing a clamping mechanism for the first and second platforms;

rotating the first platform about first axis to adjust the first incline angle

15

of the first platform; and

rotating the second platform about a second axis to adjust the second

incline angle of the second platform.