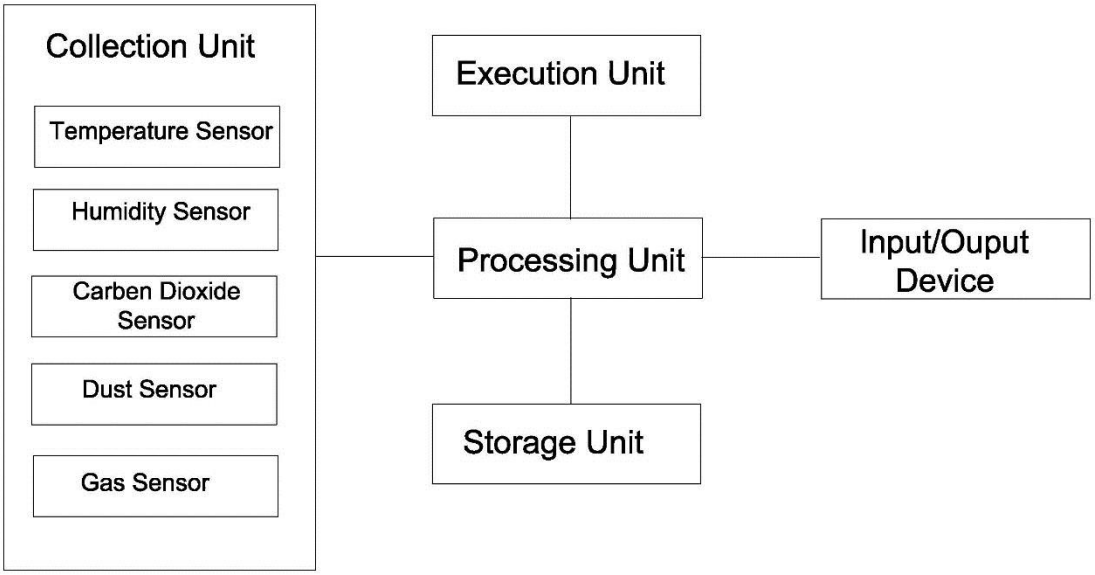

Collection Unit
Temperature Sensor
Humidity Sensor
Carben Dioxide Sensor
Dust Sensor
Gas Sensor
Execution Unit
Processing Unit
Input/Ouput Device
Storage Unit

Figure 1

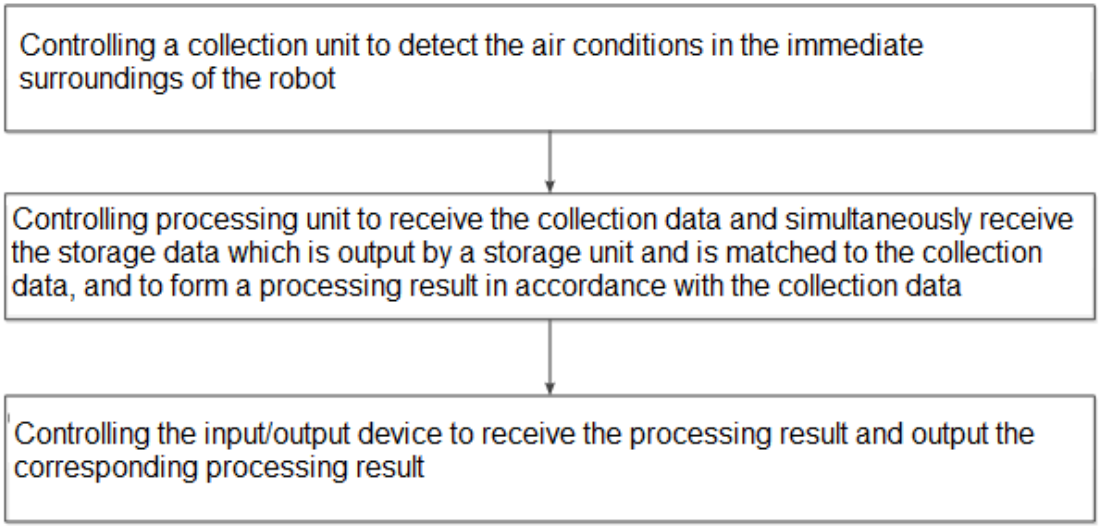

Controlling a collection unit to detect the air conditions in the immediate surroundings of the robot
Controlling processing unit to receive the collection data and simultaneously receive the storage data which is output by a storage unit and is matched to the collection data, and to form a processing result in accordance with the collection data
Controlling the input/output device to receive the processing result and output the corresponding processing result

Figure 2