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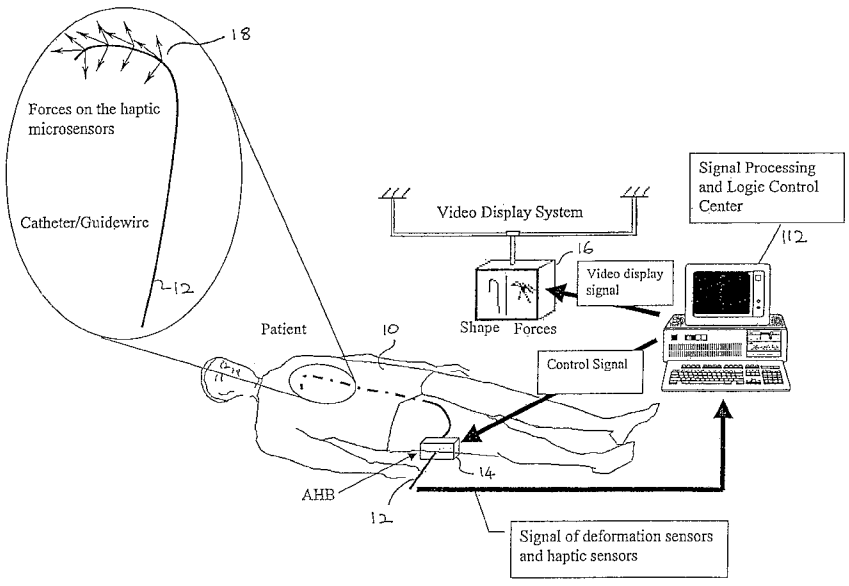
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(54) Title: APPARATUS FOR MEDICAL AND/OR SIMULATION PROCEDURES



(57) Abstract: In a preferred embodiment, medical apparatus comprising a catheter (12) which operable to be inserted into a human subject (10) is disclosed herein. Haptic sensors (22, 24) and deformation sensors (26, 27) are connected to the catheter (12) and these are disposed at a plurality of locations along the length of the catheter (12). The haptic sensors measures 3D forces (18) acting on the catheter (12) at the disposed locations and these forces are provided to a haptic feedback device (14) which provides haptic feedback to, an interventional radiologist. The deformation sensors (26, 27) on the other hand, measures the deformation of the catheter (12) at the disposed locations and this information determines the shape of the catheter (12) which is represented on a display (16) for viewing by the radiologist.

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