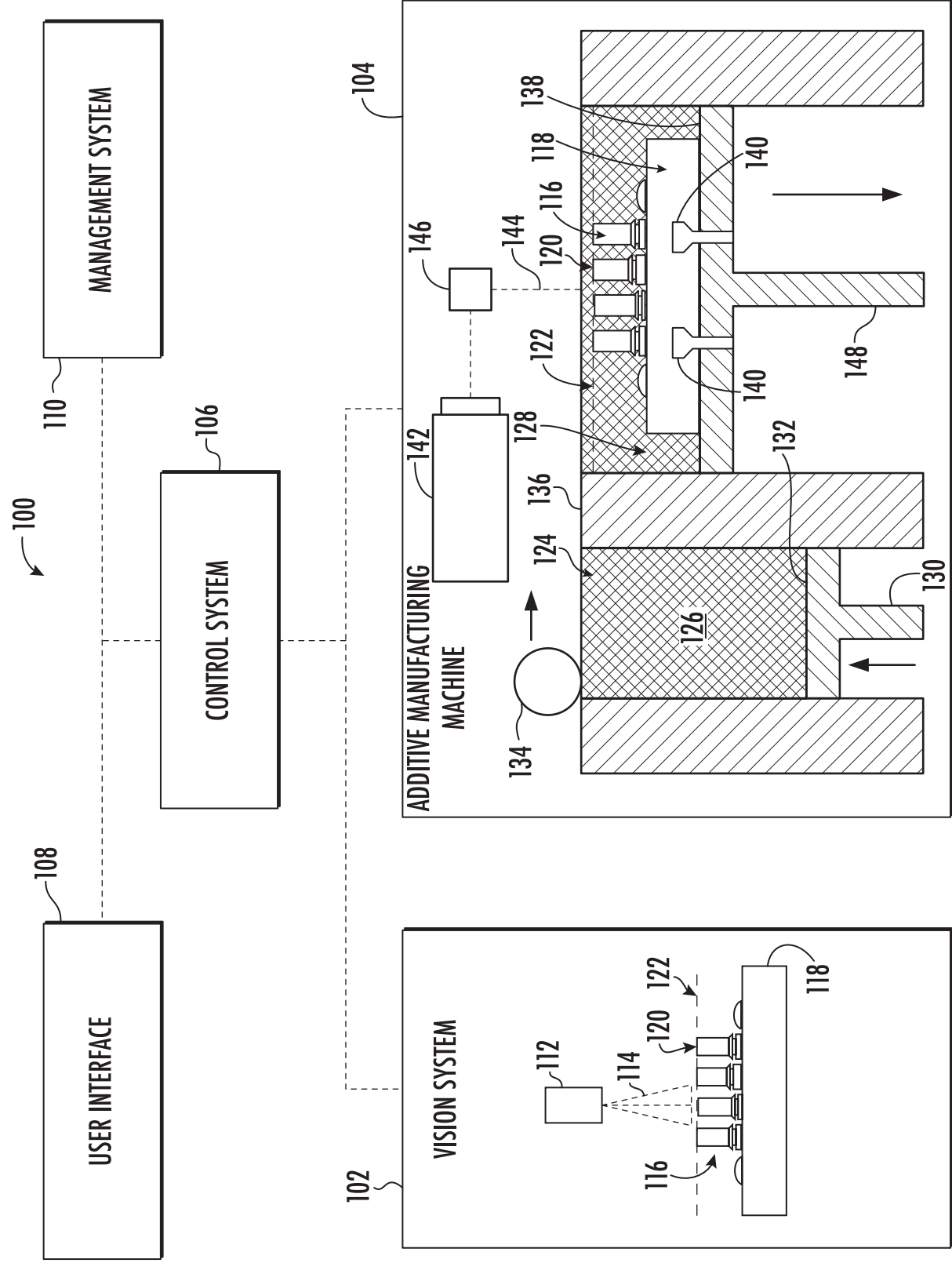




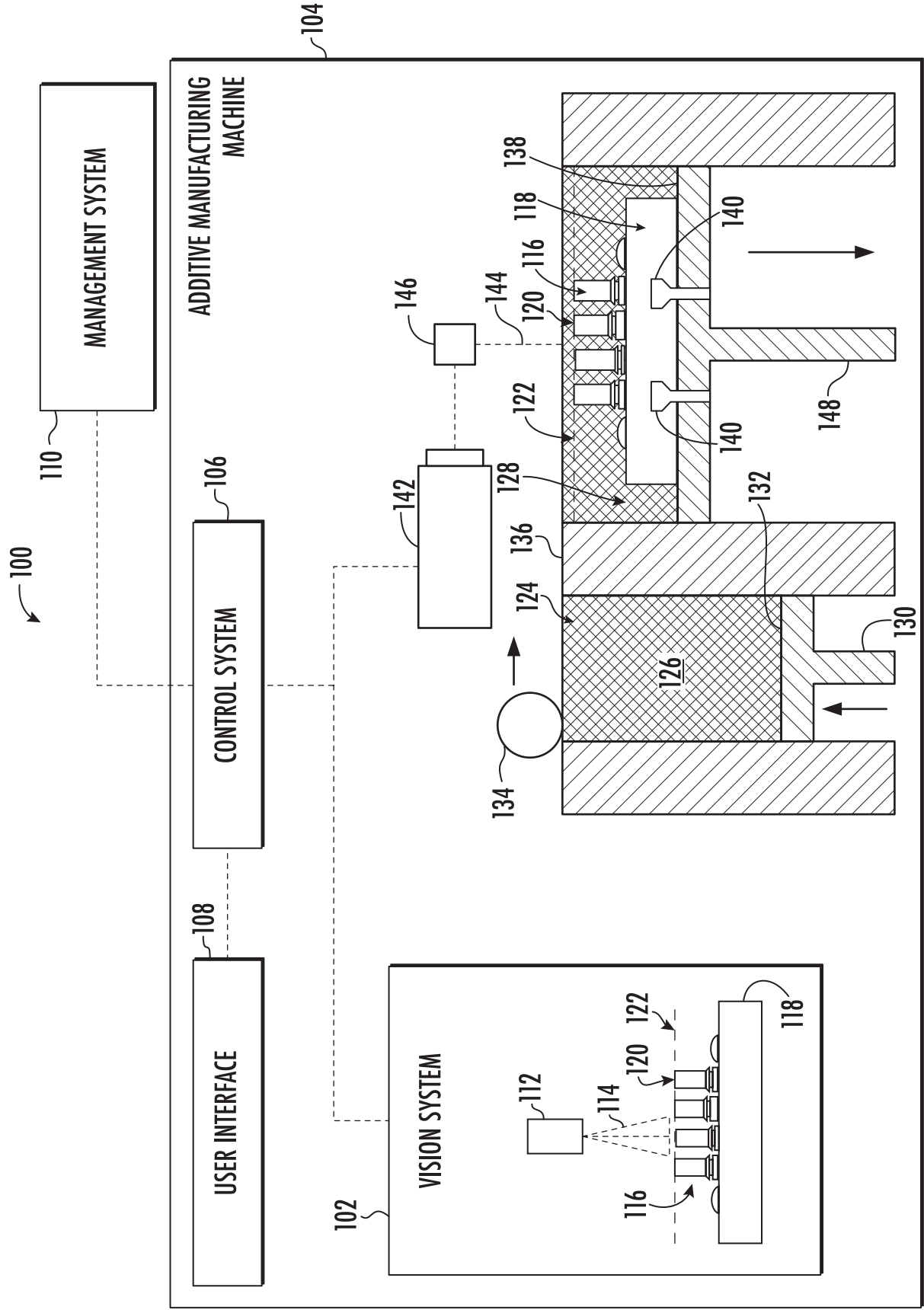


FIG. 1B

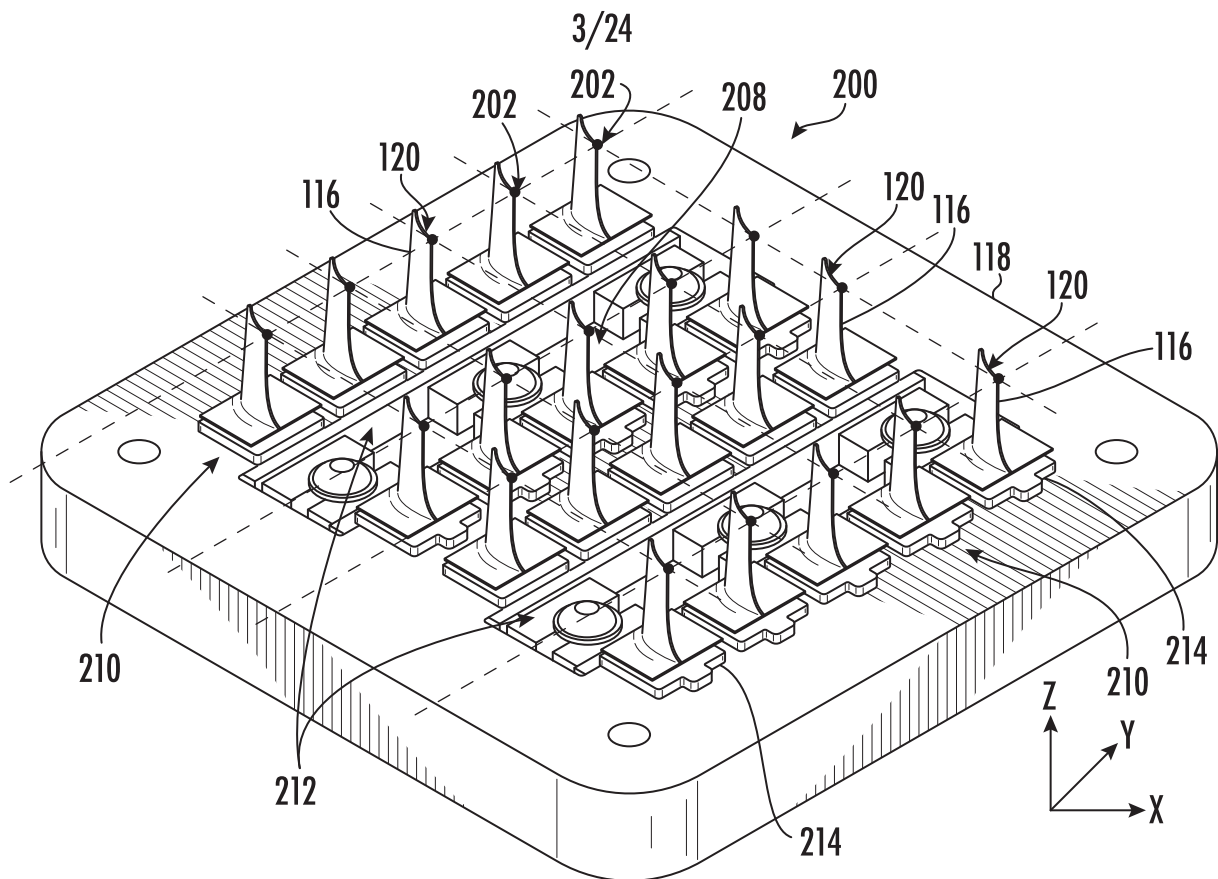


FIG. 2A

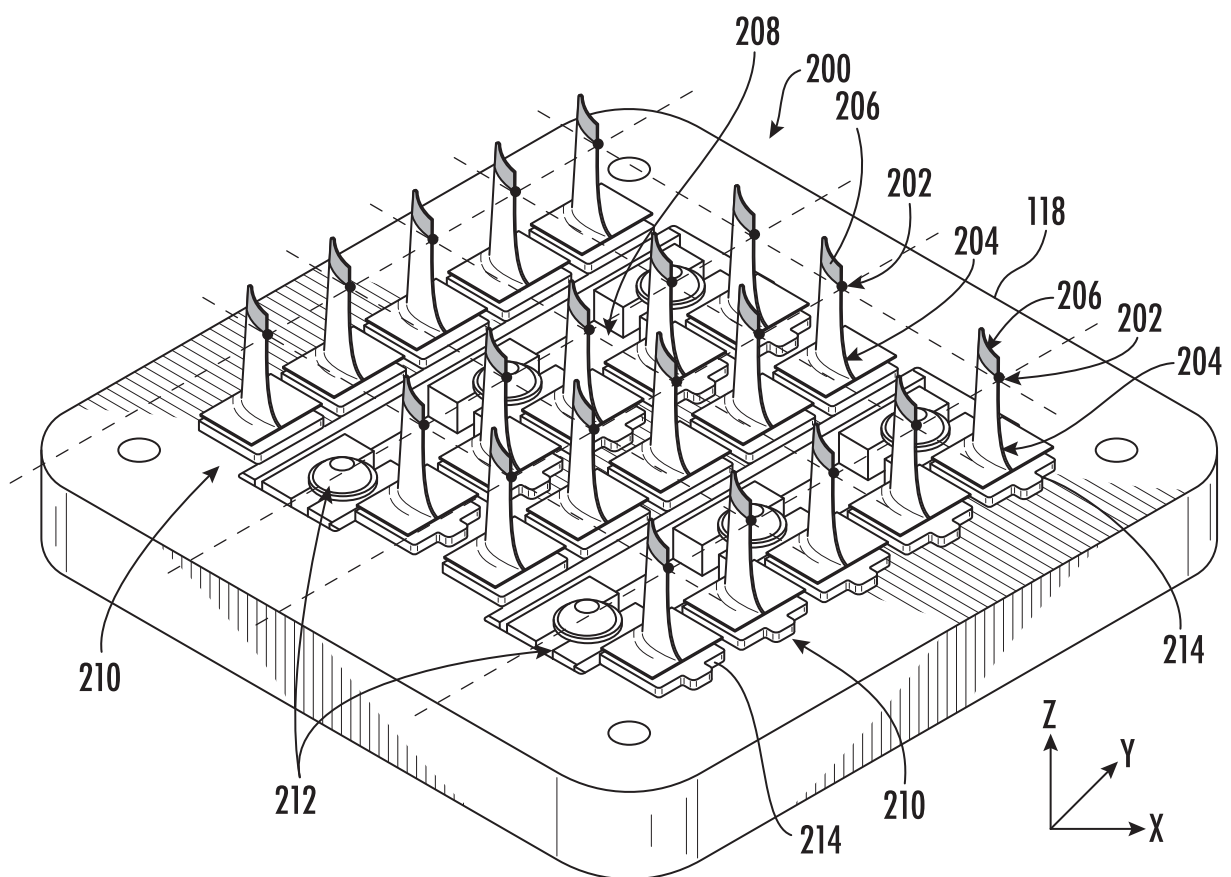


FIG. 2B

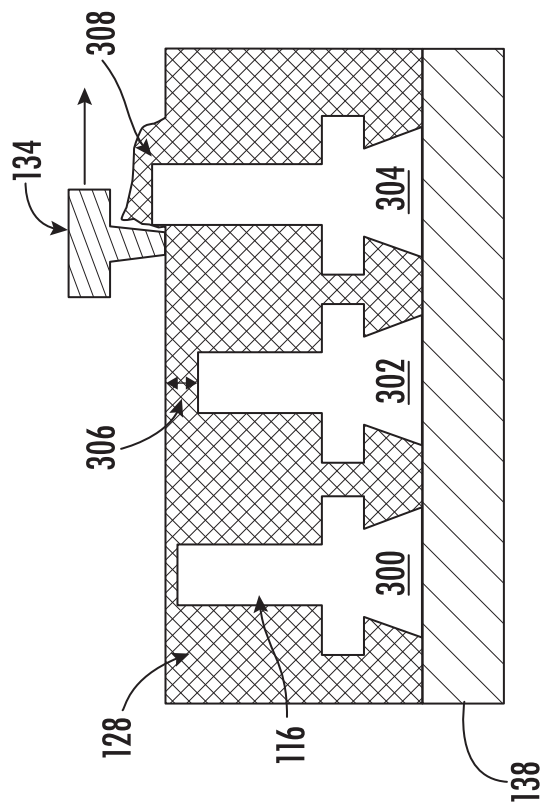


FIG. 3B

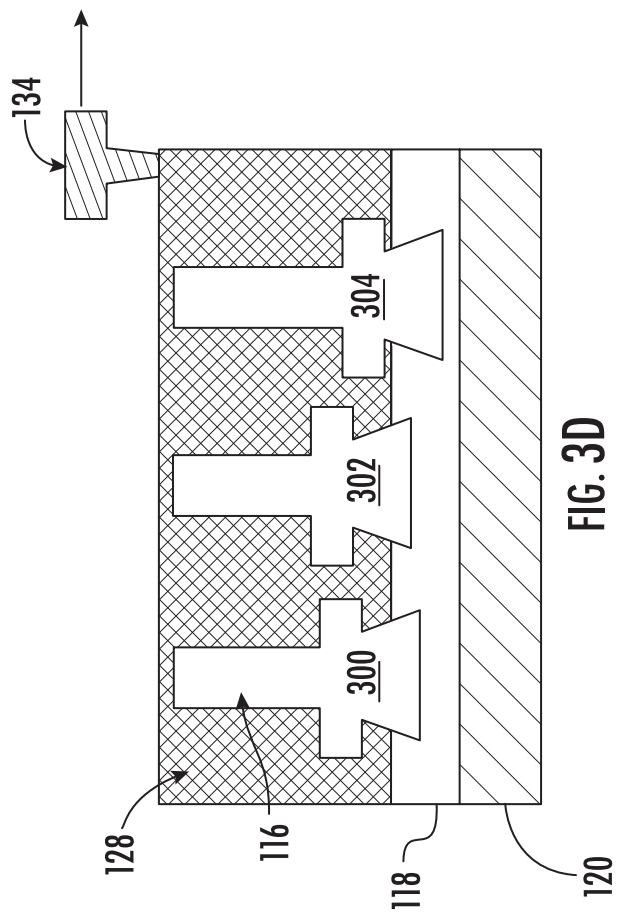


FIG. 3D

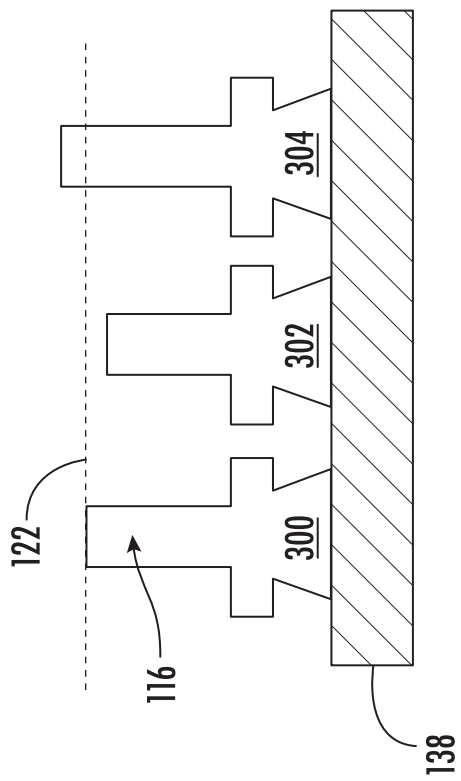


FIG. 3A

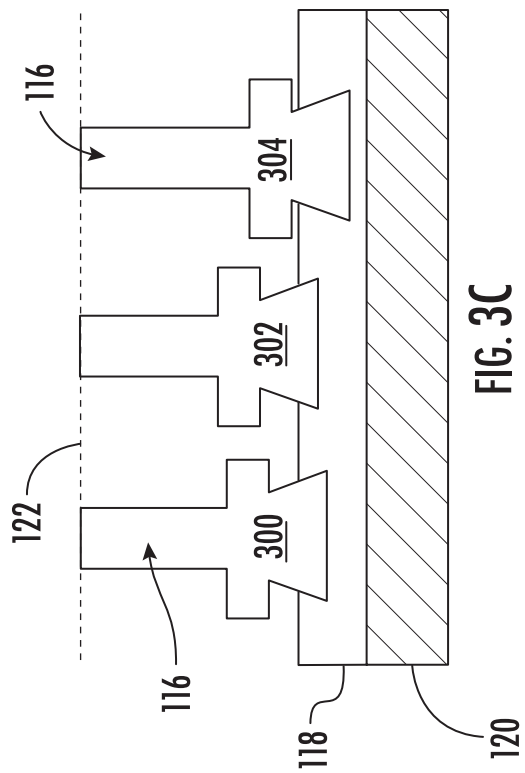


FIG. 3C

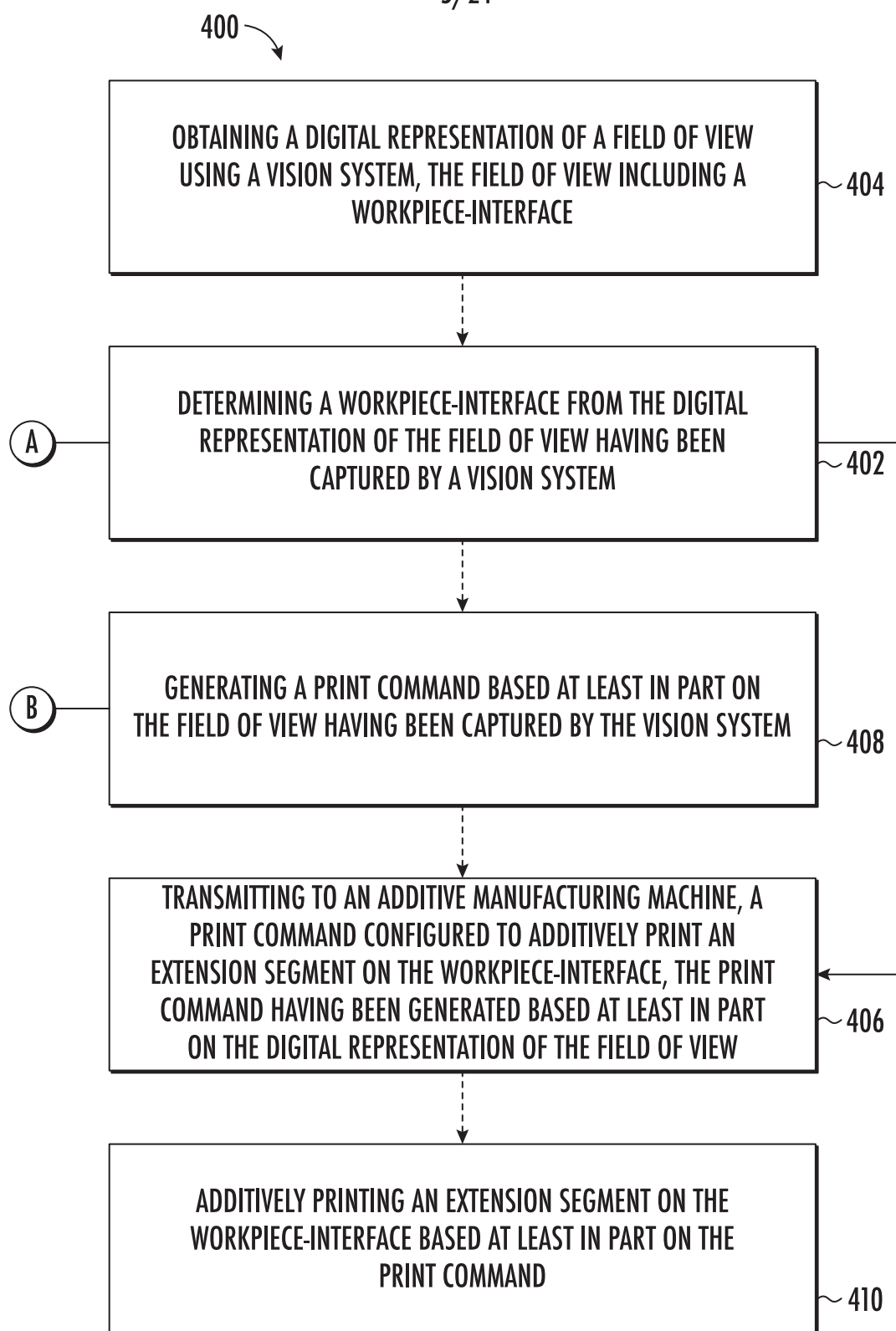


FIG. 4

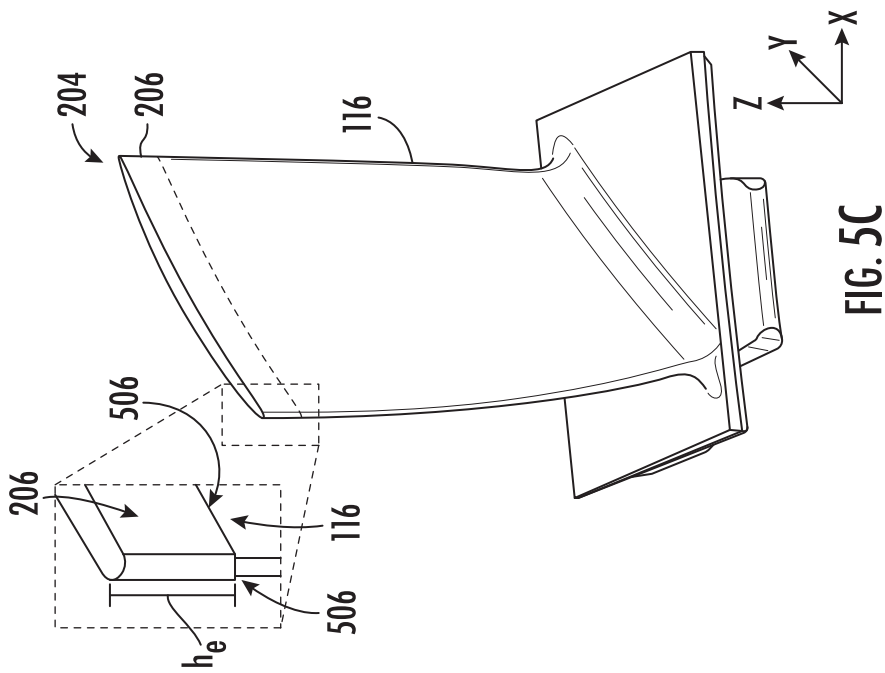
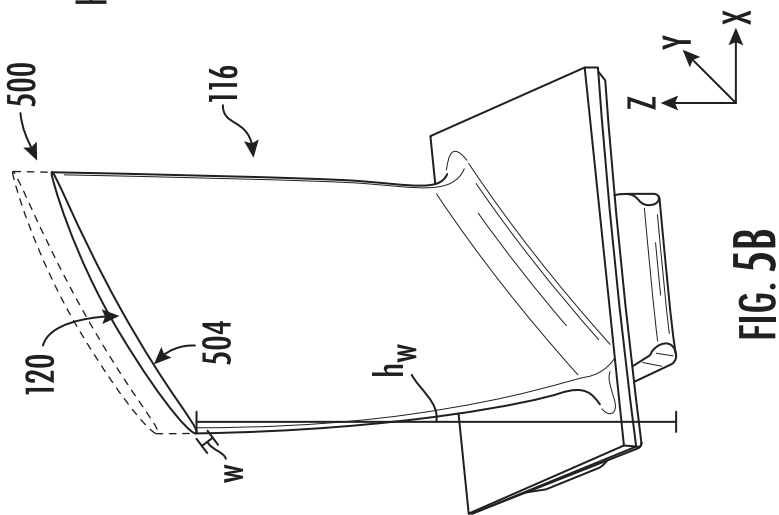
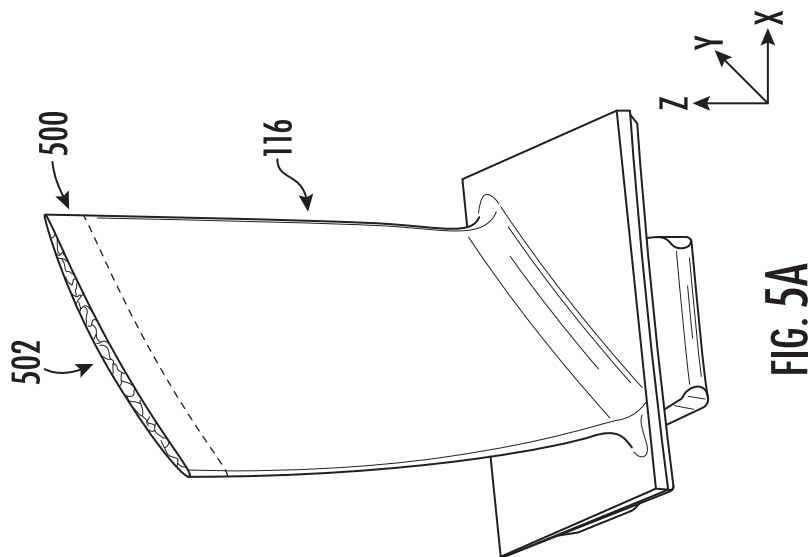


FIG. 5C

FIG. 5B

FIG. 5A

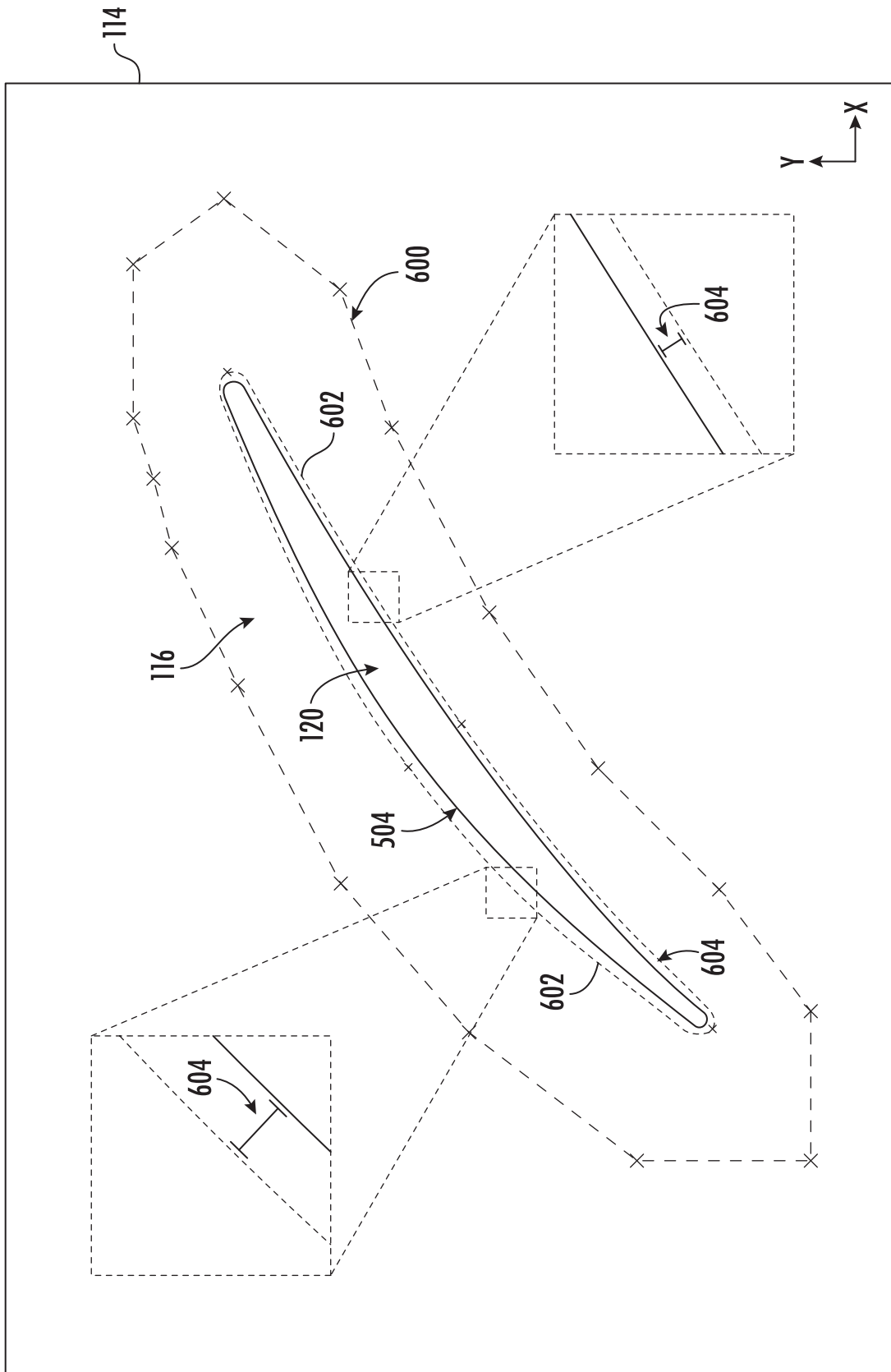


FIG. 6A

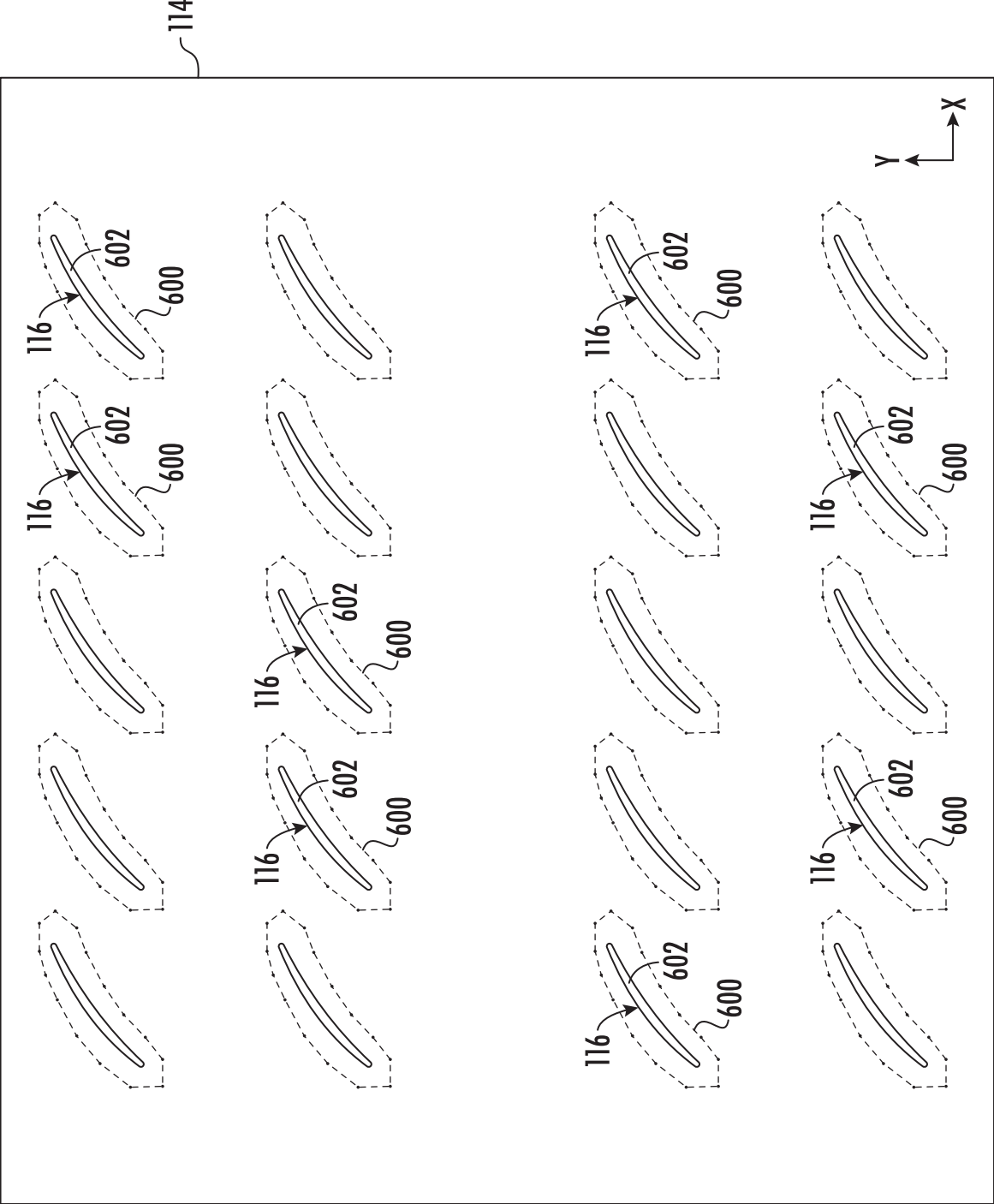


FIG. 6B

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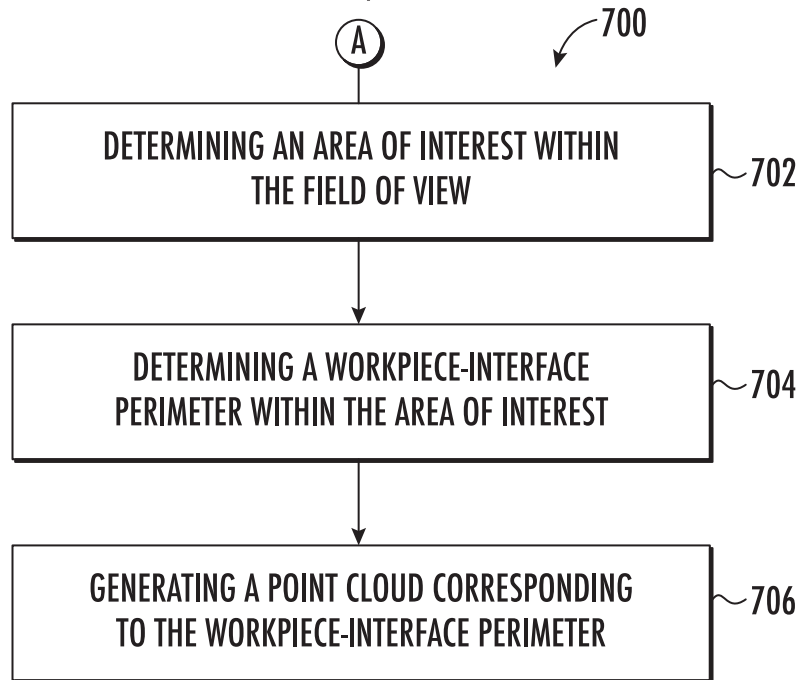


FIG. 7A

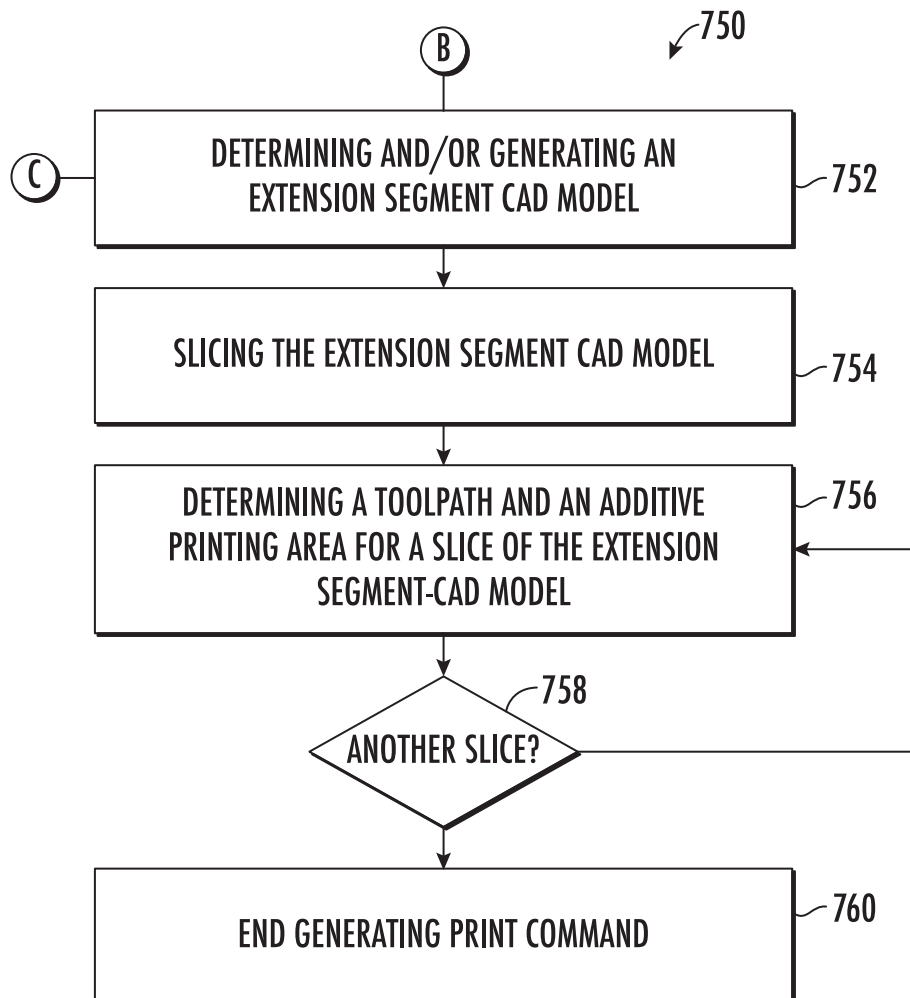


FIG. 7B

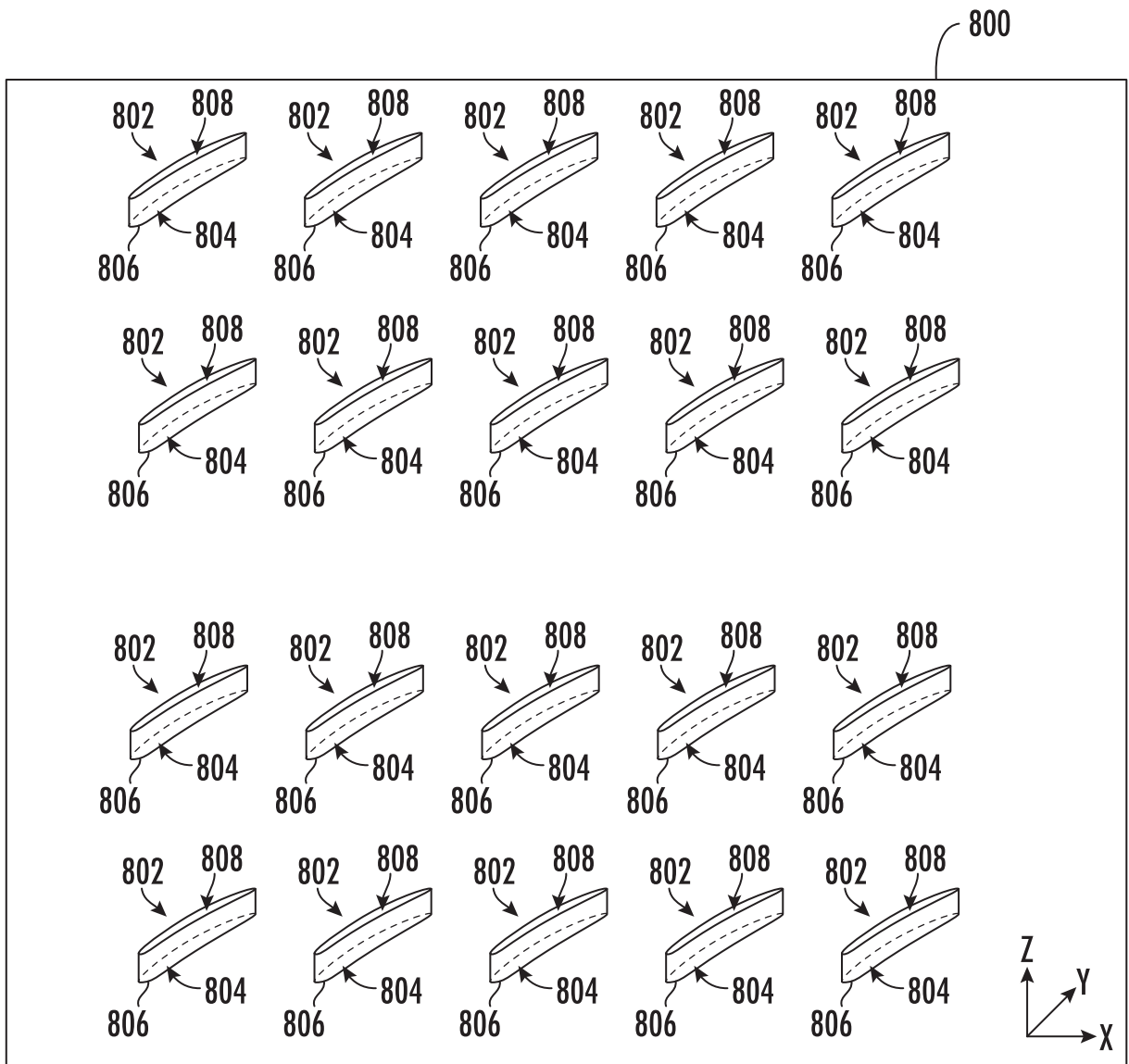


FIG. 8A

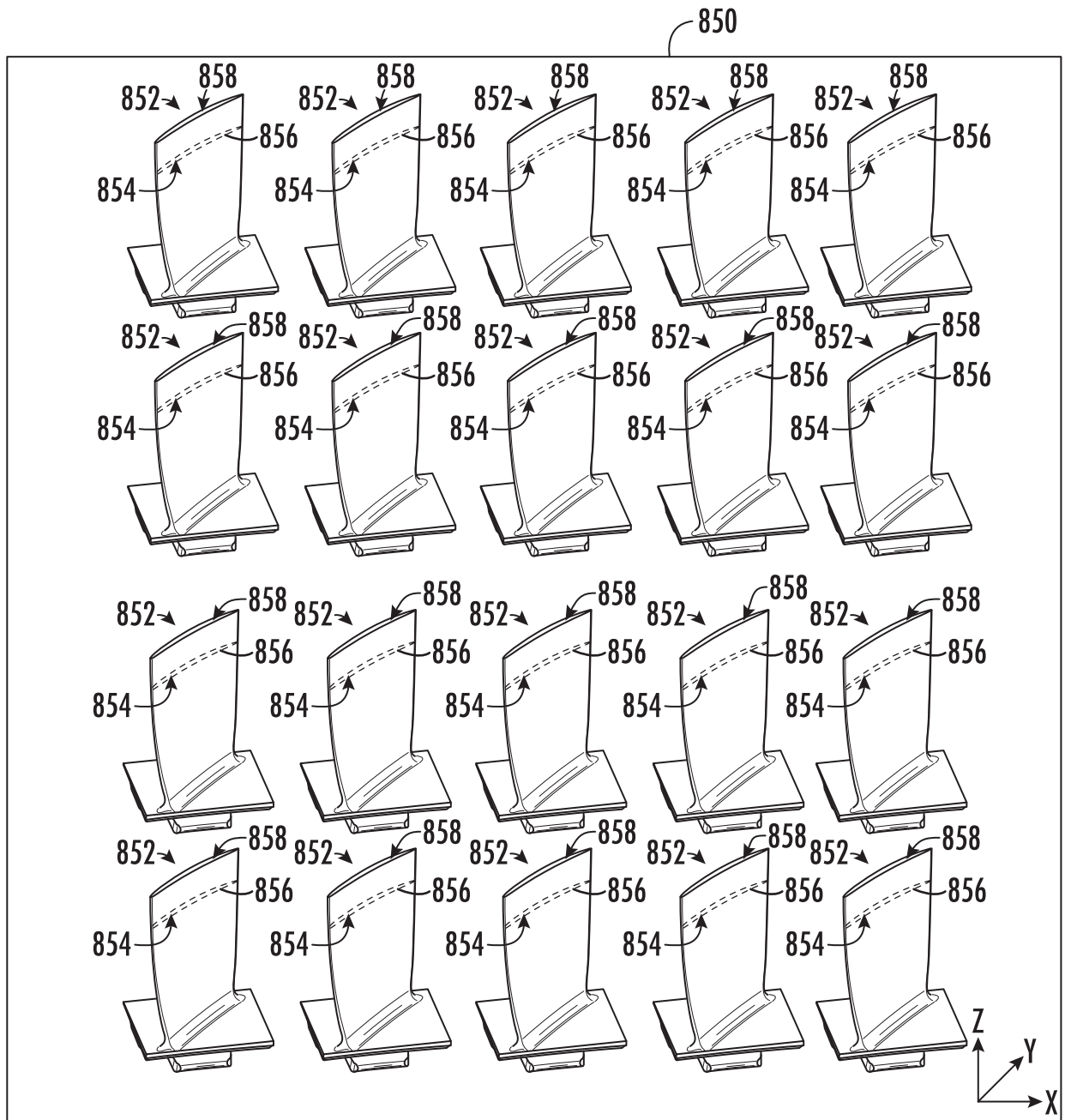


FIG. 8B

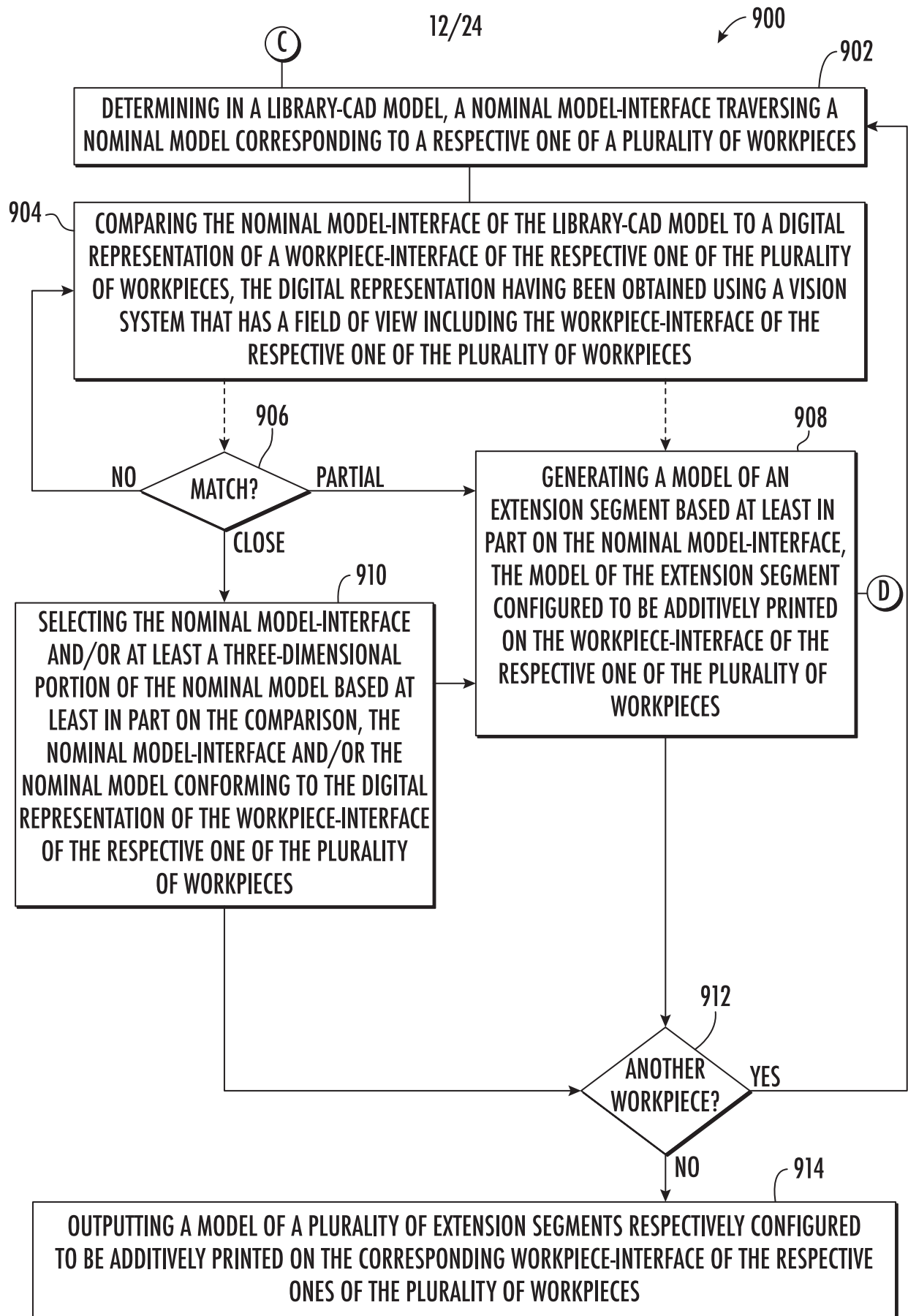


FIG. 9A

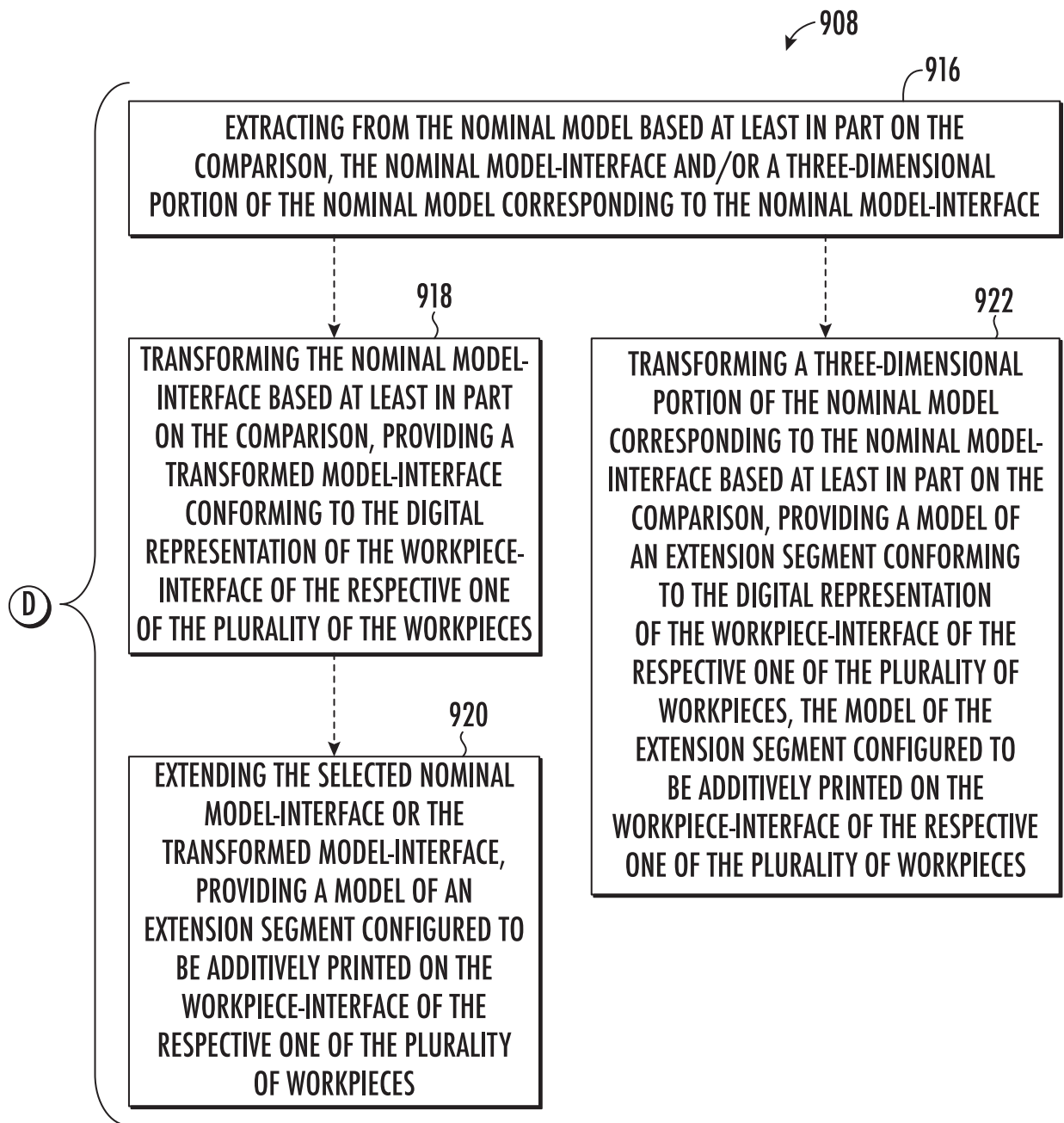


FIG. 9B

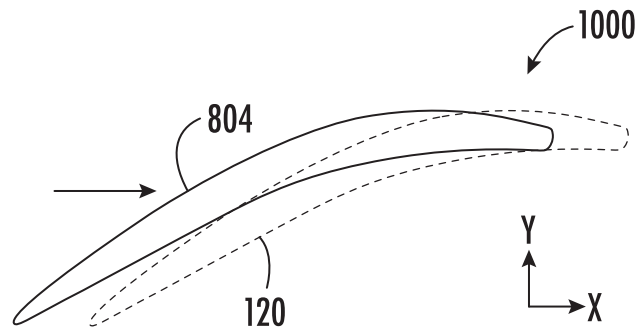


FIG. 10A

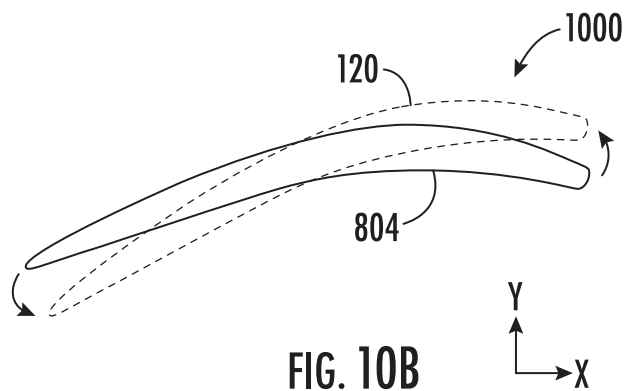


FIG. 10B

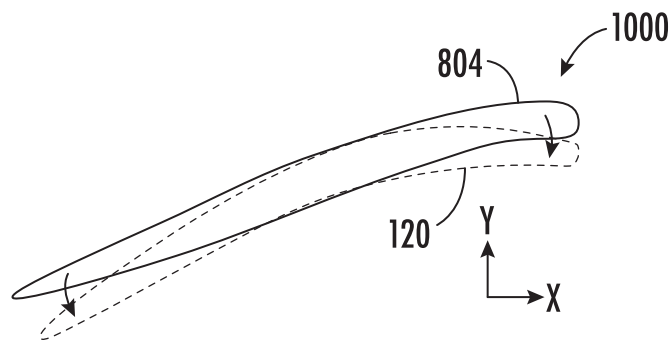


FIG. 10C

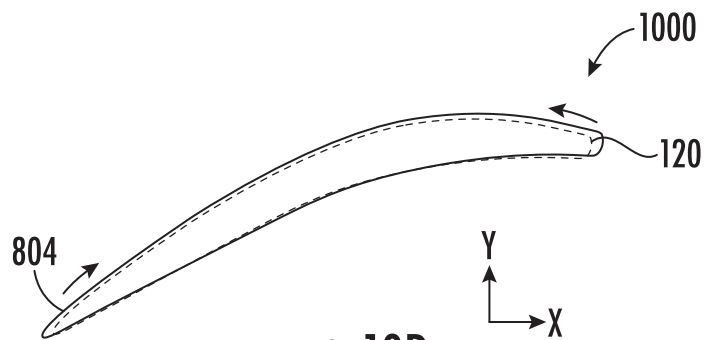


FIG. 10D

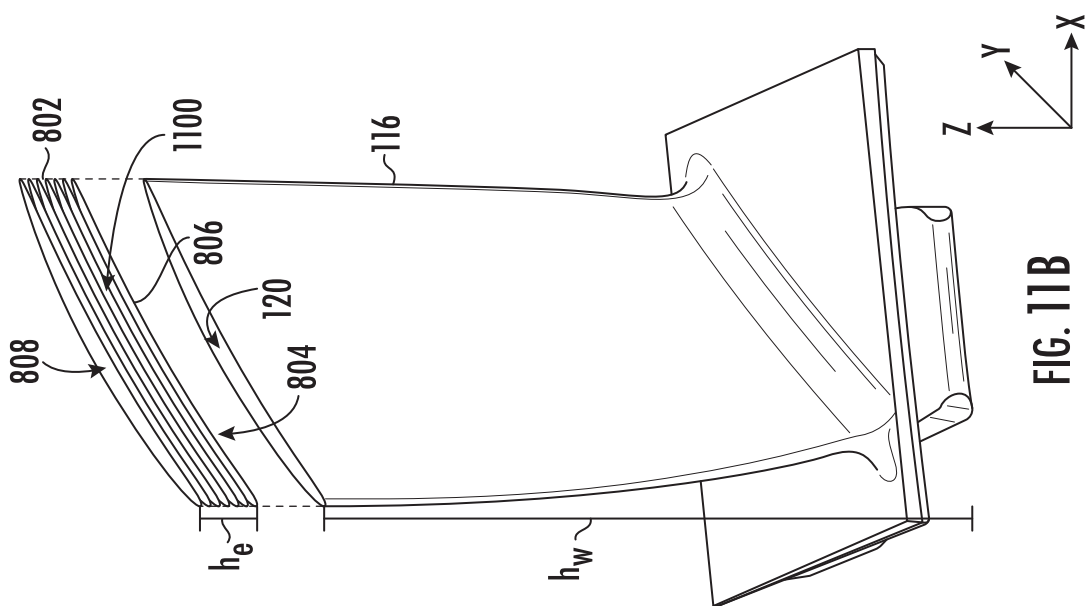


FIG. 11B

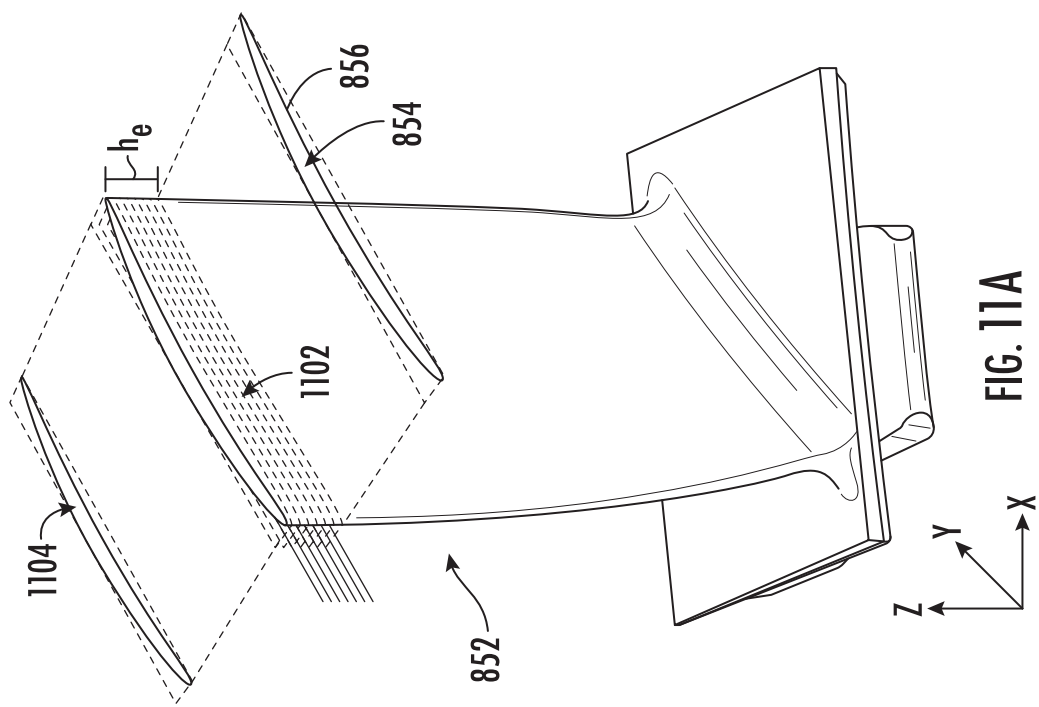


FIG. 11A

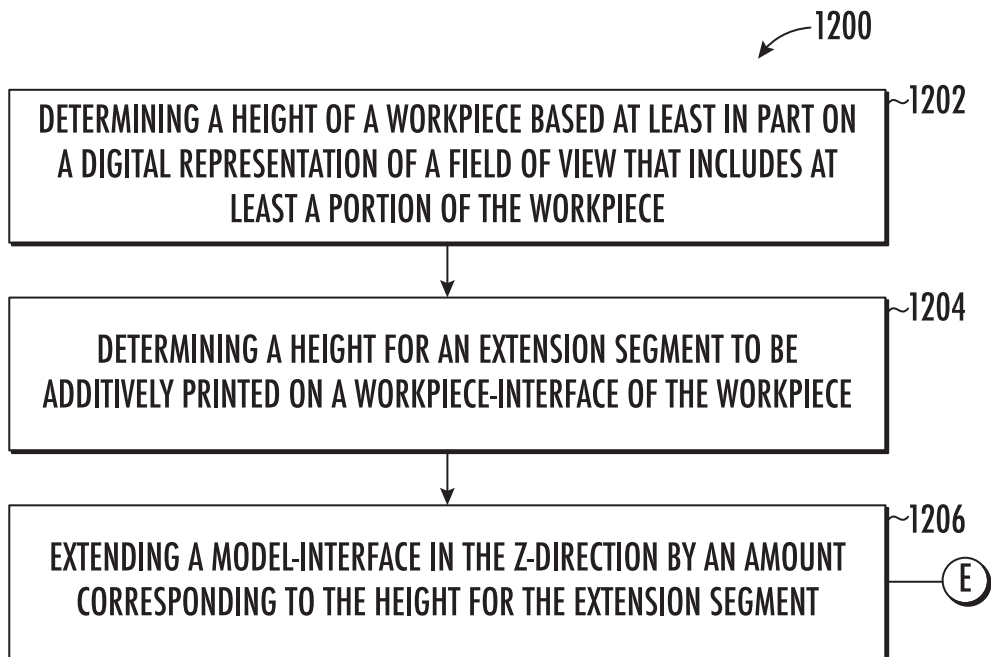


FIG. 12A

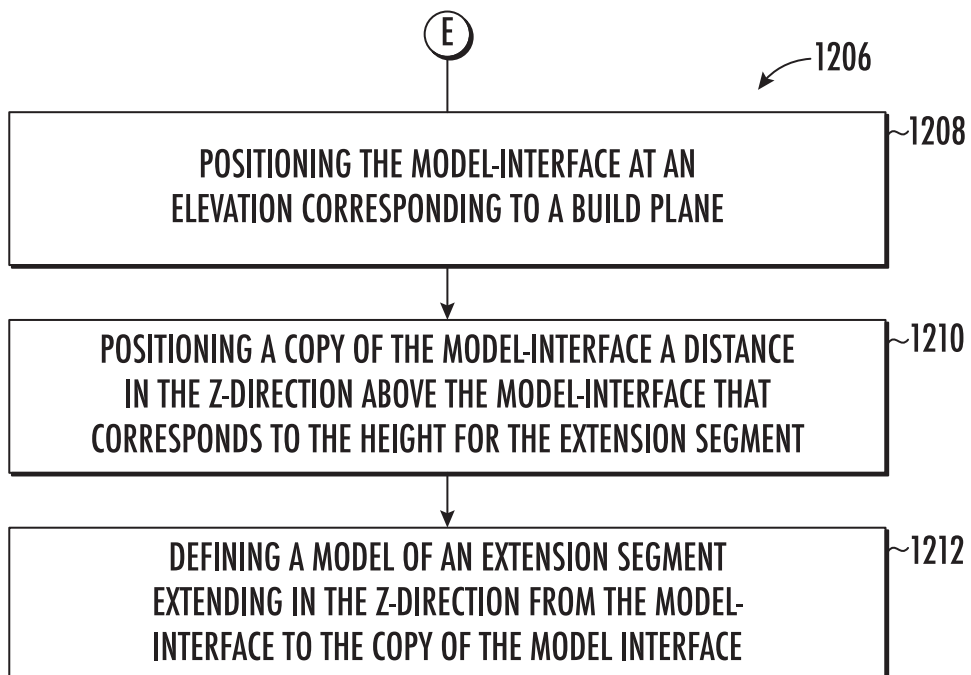


FIG. 12B

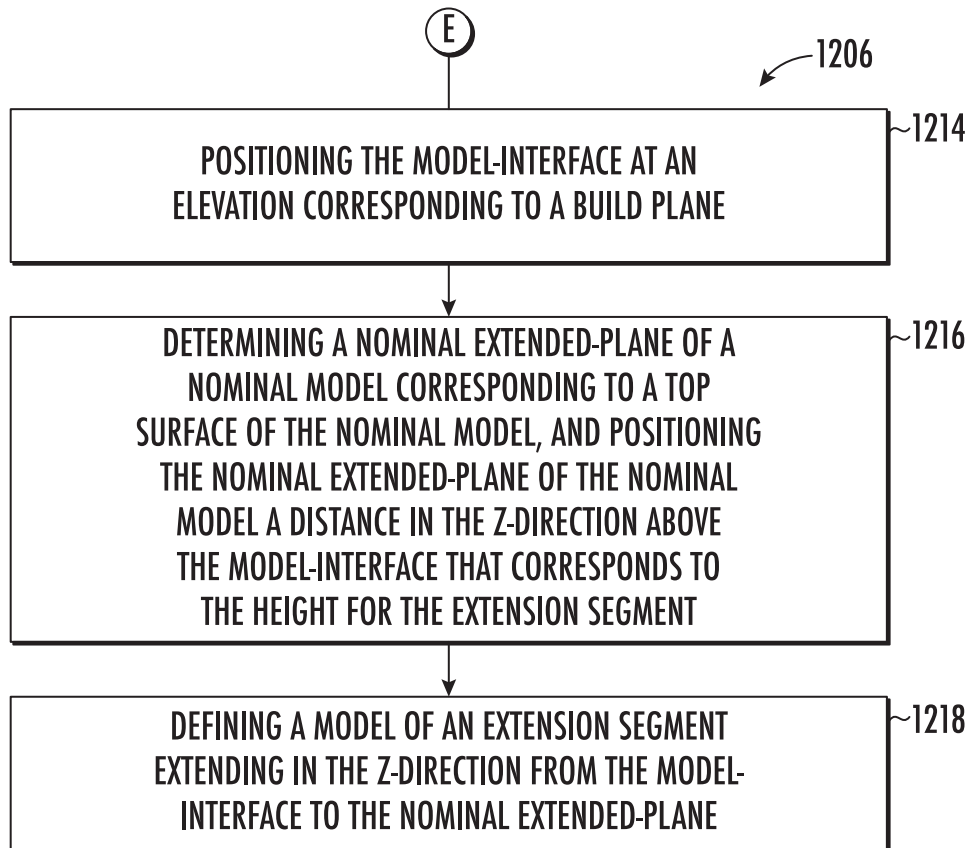


FIG. 12C

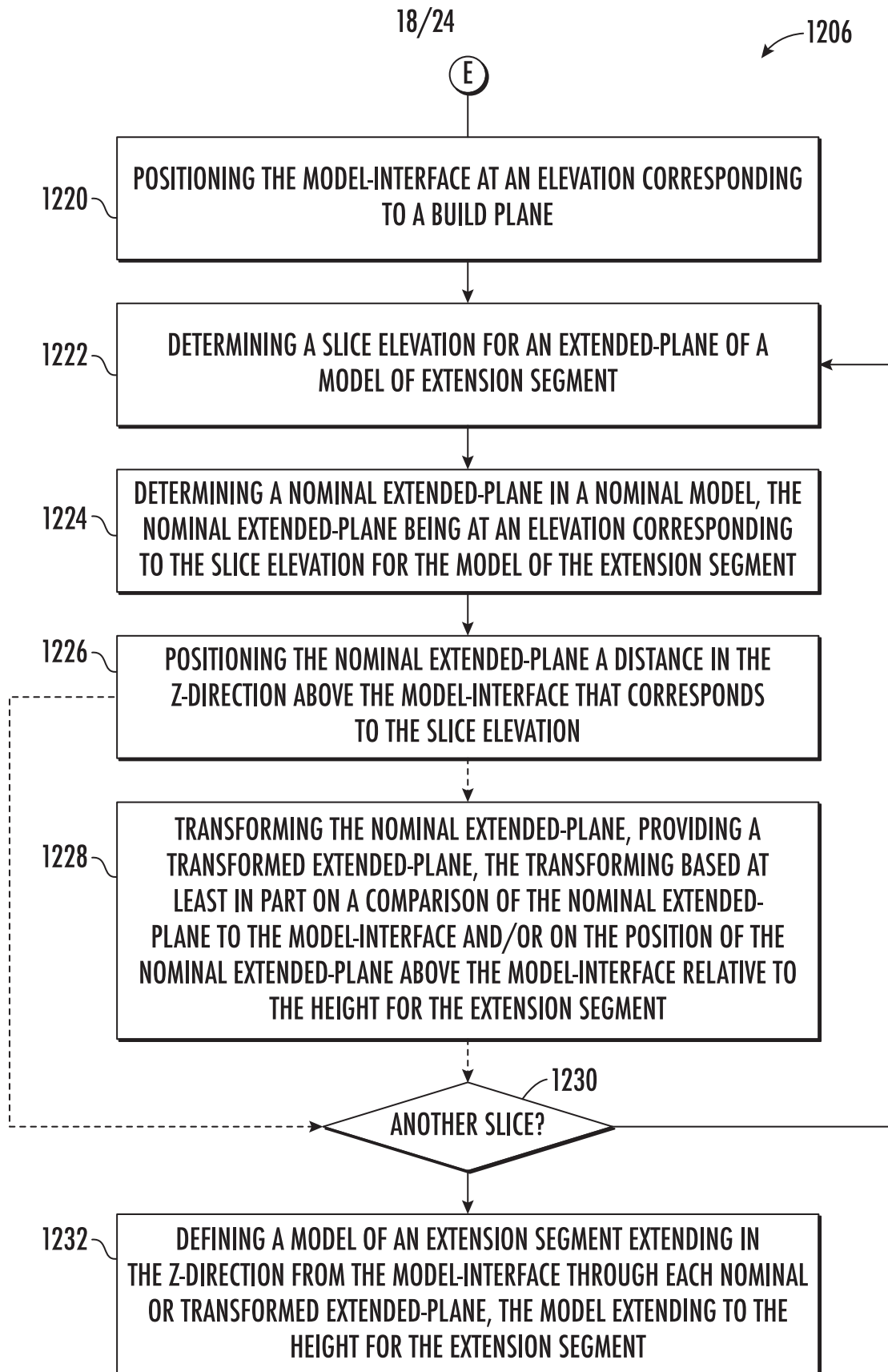


FIG. 12D

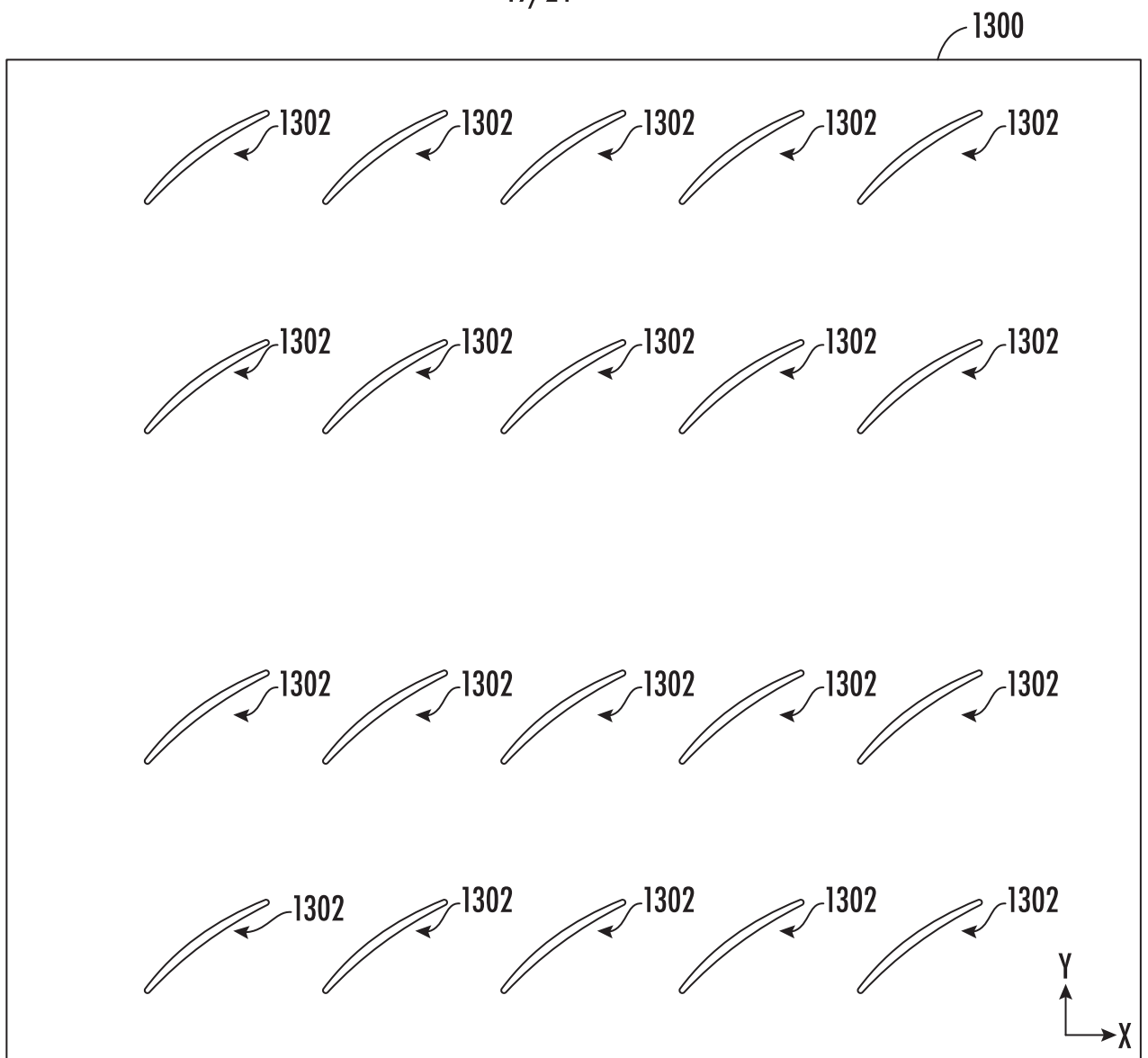


FIG. 13

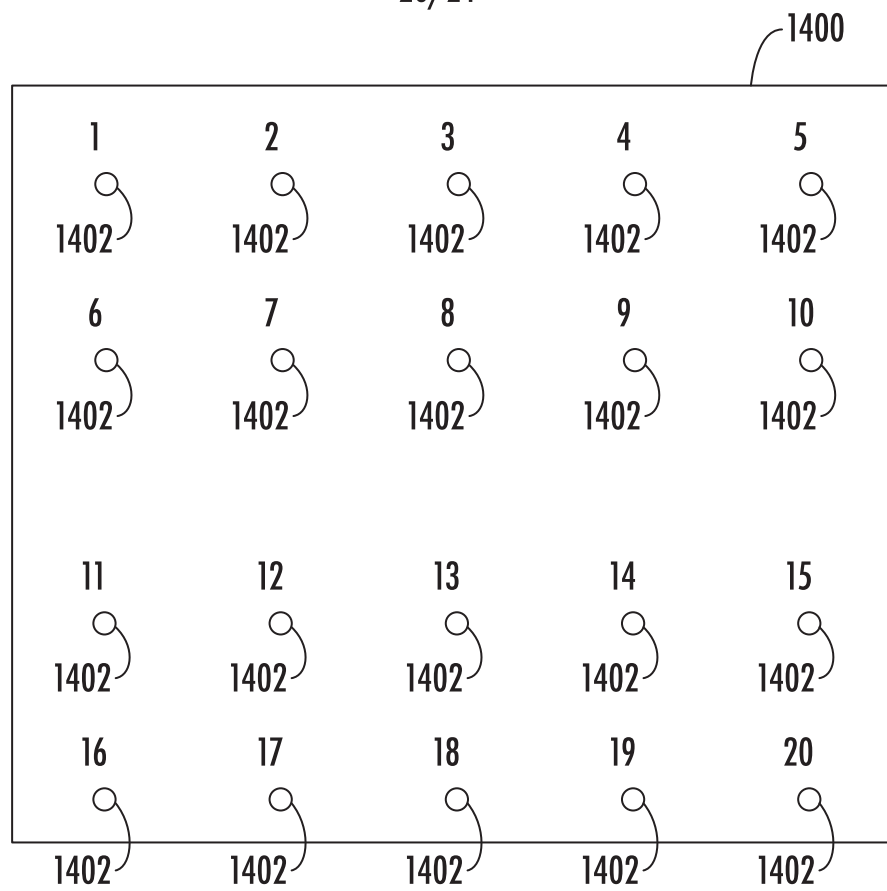


FIG. 14

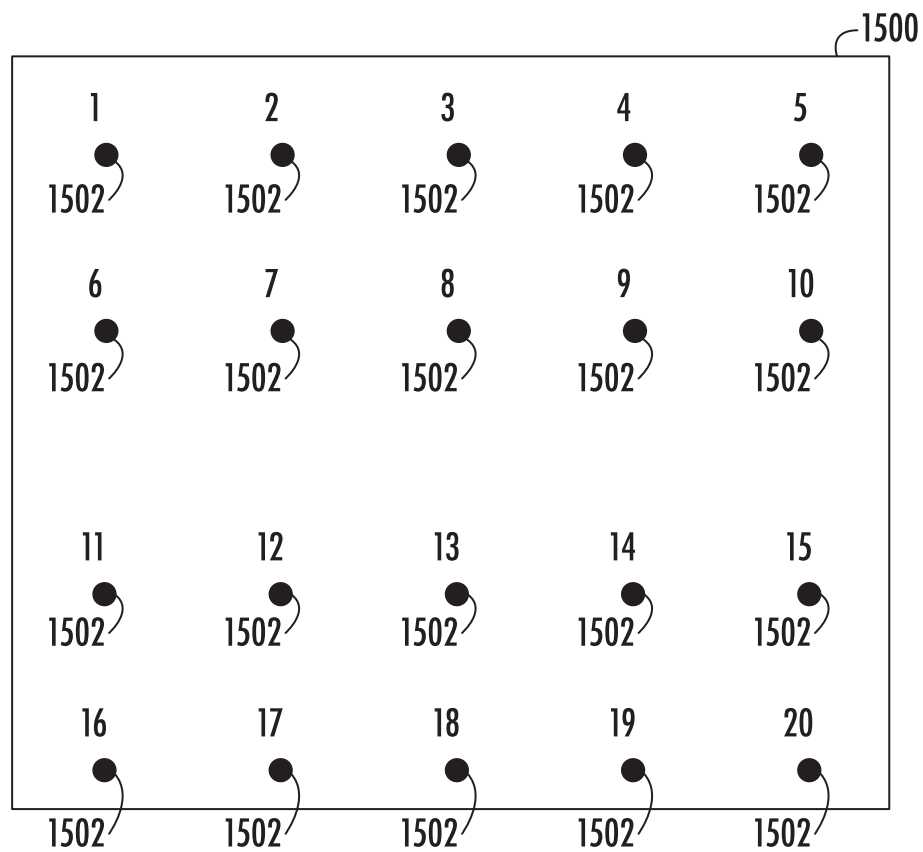


FIG. 15

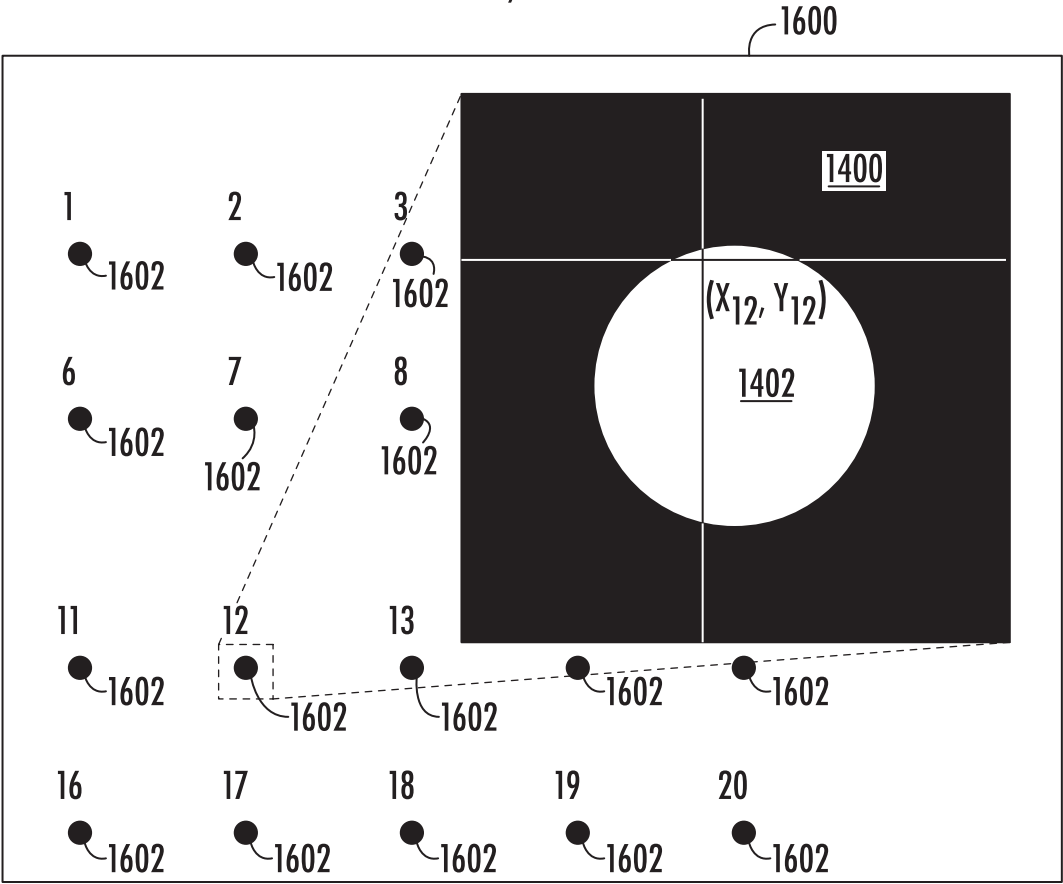


FIG. 16

REGISTRATION POINT	1702		1704		1706	
	X	Y	X	Y	X	Y
1	x_1^0	y_1^0	x_1	y_1	Δx_1	Δy_1
2	x_2^0	y_2^0	x_2	y_2	Δx_2	Δy_2
...						
n	x_n^0	y_n^0	x_n	y_n	Δx_n	Δy_n

FIG. 17

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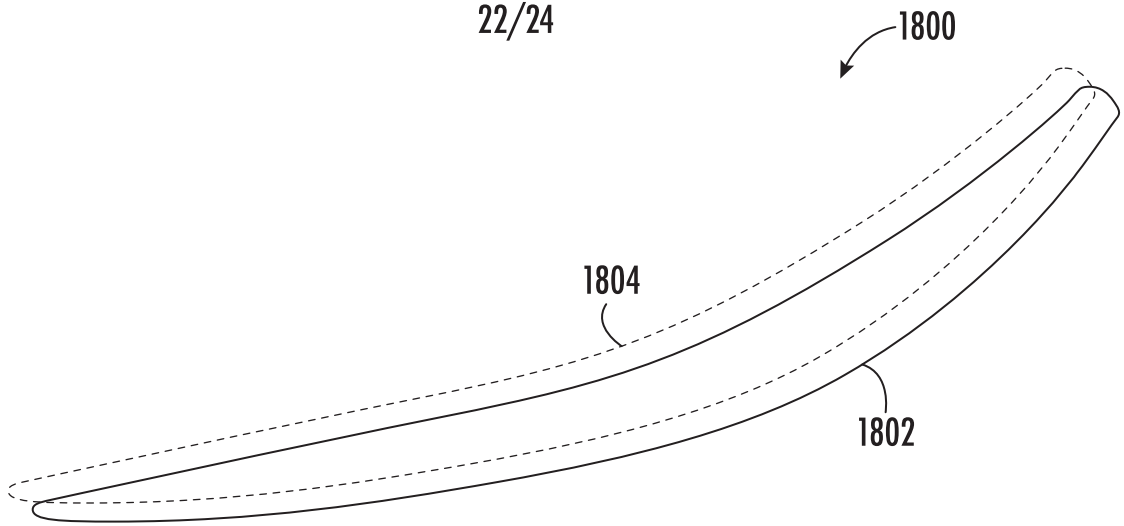


FIG. 18A

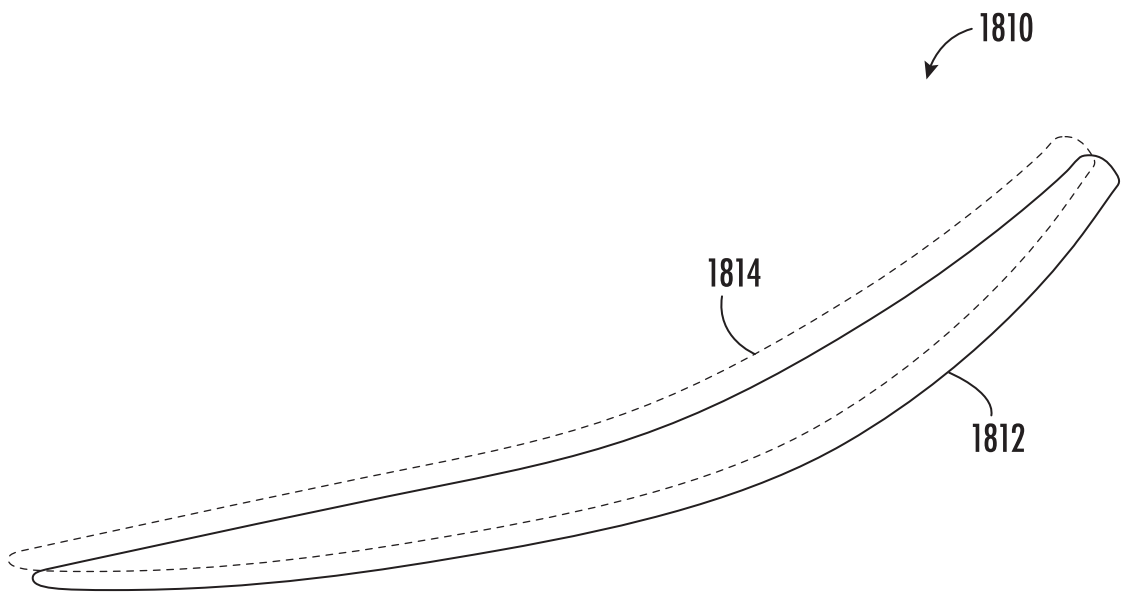


FIG. 18B

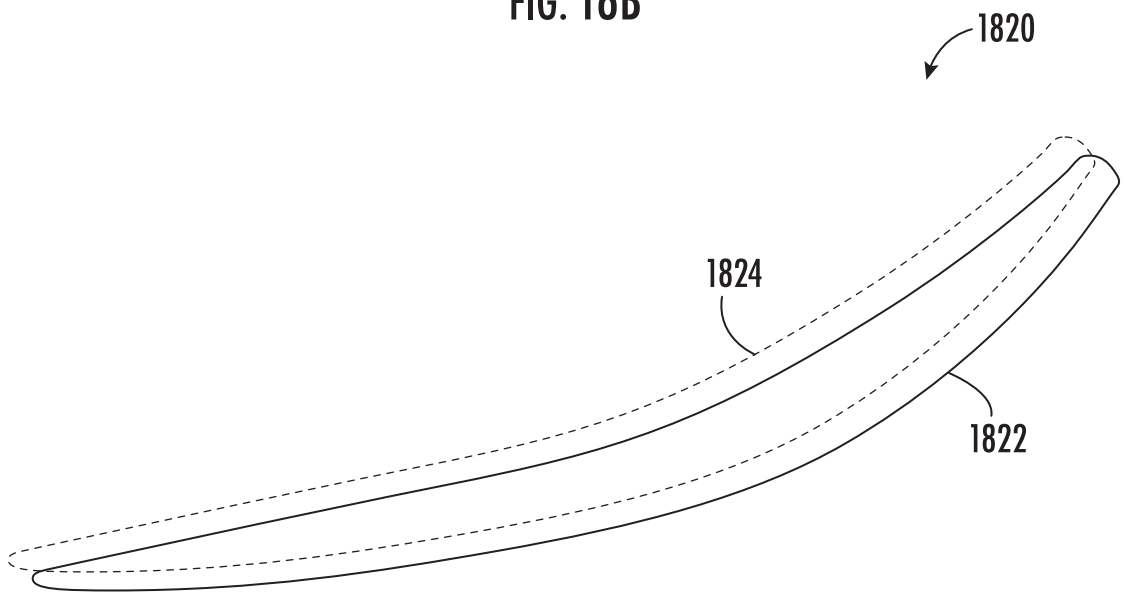


FIG. 18C

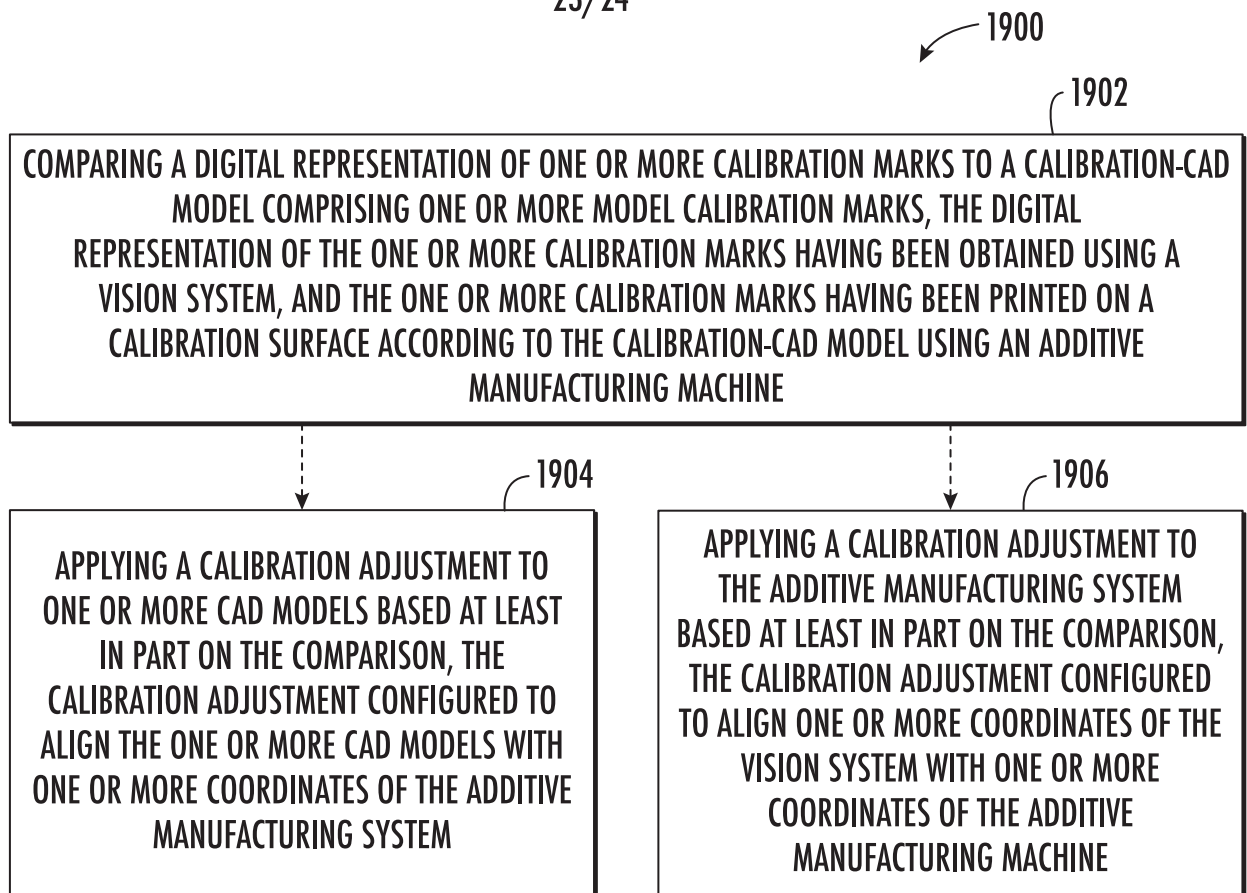


FIG. 19

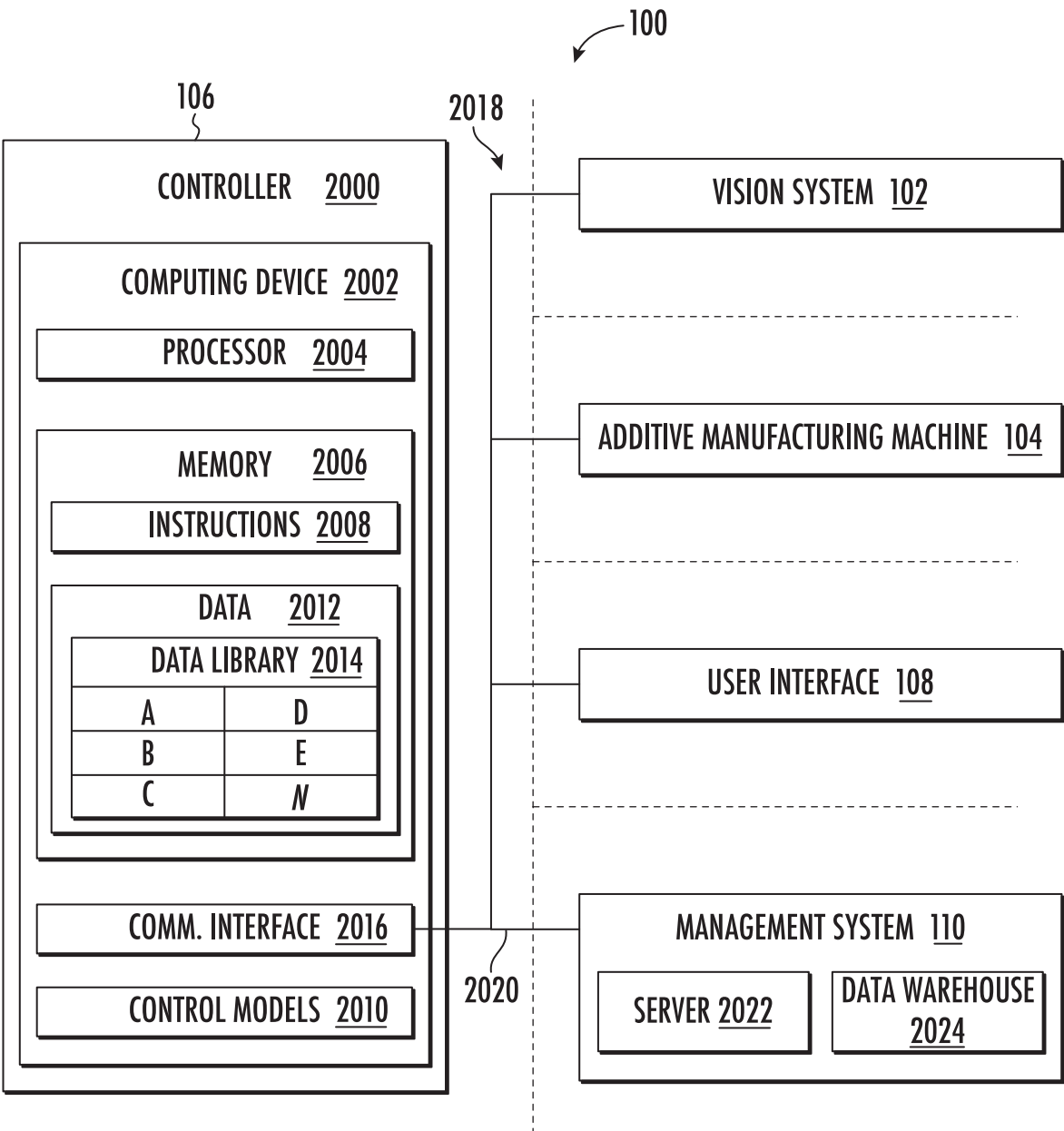


FIG. 20