



(51) International Patent Classification:
H04N 7/32 (2006.01) *H04N 7/24* (2006.01)

(21) International Application Number:
PCT/US2009/069159

(22) International Filing Date:
22 December 2009 (22.12.2009)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
12/346,979 31 December 2008 (31.12.2008) US

(71) Applicant (for all designated States except US): **INTEL CORPORATION** [US/US]; 2200 Mission College Boulevard, Santa Clara, California 95052 (US).

(72) Inventor; and

(75) Inventor/Applicant (for US only): **BUKIN, Dov** [IL/IL]; Harisonim 101, Haifa (IL).

(74) Agents: **VINCENT, Lester J.** et al.; Blakely Sokoloff Taylor & Zafman, 1279 Oakmead Parkway, Sunnyvale, California 94085 (US).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ,

CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PE, PG, PH, PL, PT, RO, RS, RU, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

— with international search report (Art. 21(3))

— before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments (Rule 48.2(h))

(88) Date of publication of the international search report:
30 September 2010

(54) Title: MOTION ESTIMATION TECHNIQUES

100

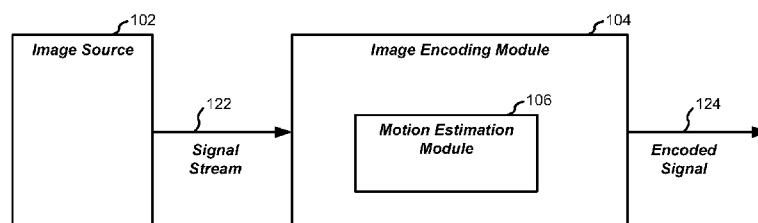


FIG. 1

(57) Abstract: Techniques for motion estimation are disclosed. For example, embodiments may determine error metric lower bound values for a block in a current image, where each of the error metric lower bound values corresponds to a search position in a reference image. Based on a separation threshold, a plurality of candidate positions may be identified from the search positions. A matching position is then identified from the candidate positions. Based on the matching position, a motion vector is determined.