

**TITLE OF INVENTION: A CONTROL METHOD, DEVICE,
EQUIPMENT, AND STORAGE MEDIUM FOR BAGGAGE HANDLING
ROBOT**

ABSTRACT

The present disclosure provides a control method, device, equipment, and storage medium for a baggage handling robot in the field of robotics, solving problems of labor-intensive, inefficient, and error-prone manual handling processes. A control method for a baggage handling robot comprises: Step S1: activating the baggage handling robot and setting a target position; Step S2: performing an automatic baggage handling operation based on the target position; Step S3: monitoring a performance of the automatic baggage handling operation and outputting real-time monitoring data. Use of this control method in the baggage handling robot of the present disclosure automates the handling process, saves time and labor, and significantly improves handling efficiency.

FIG. 1