the shooting sector (S, S', S'') is determined and is maintained in each sub region.

14. The method as claimed in claim 13, characterized in that the orientation of the shooting sector (S, S', S'') is determined when the vehicle (1) crosses a position line (20, 20', 20") that is disposed in a sub region.

15. The method as claimed in any one of the preceding claims, characterized in that the shooting sector (S, S', S'') encloses an azimuth angle (σ) that is maintained during movement of the vehicle (1).

16. The method as claimed in any one of ~~the preceding~~ claims 1-14, characterized in that the shooting sector (S, S', S'') encloses an azimuth angle (σ) that is changed during movement of the vehicle (1).

17. The method as claimed in claim 16, characterized in that the shooting sector (S, S', S'') is determined by means of boundary points (A_1, B_1, A_2, B_2, A_3, B_3) and the boundary points (A_1, B_1, A_2, B_2, A_3, B_3) are maintained during movement of the vehicle (1).