

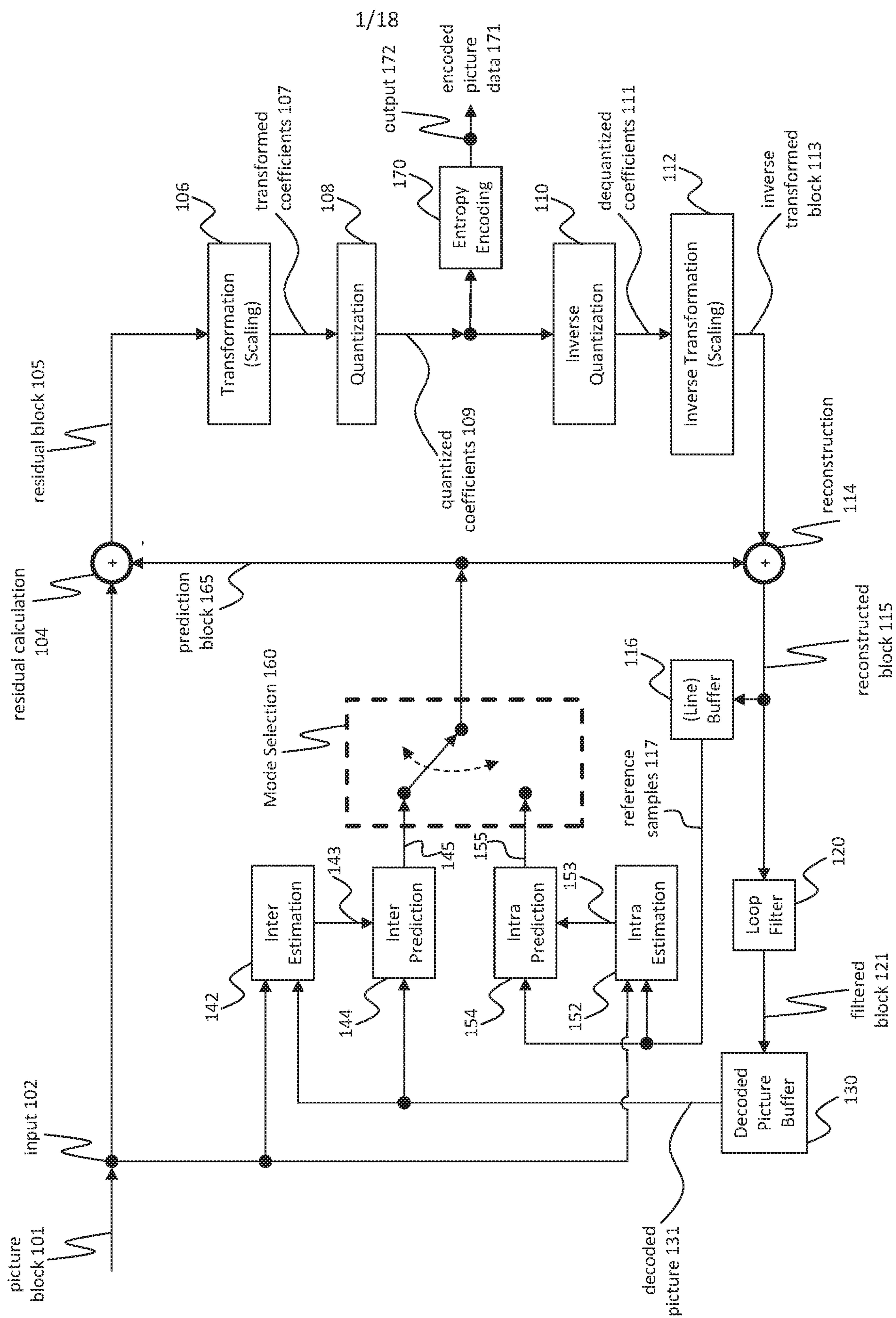


Fig. 1

Encoder 100

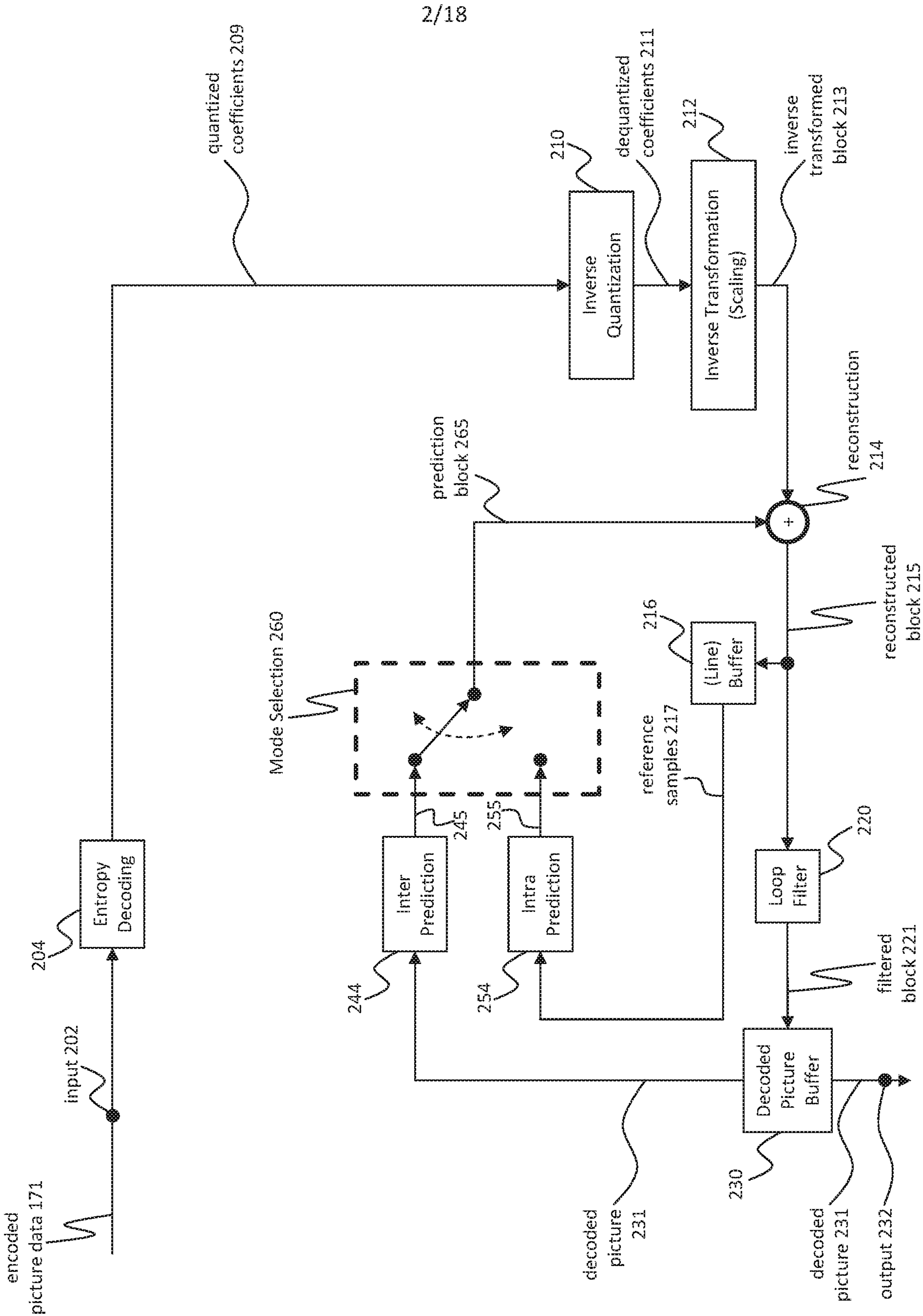


Fig. 2

Decoder 200

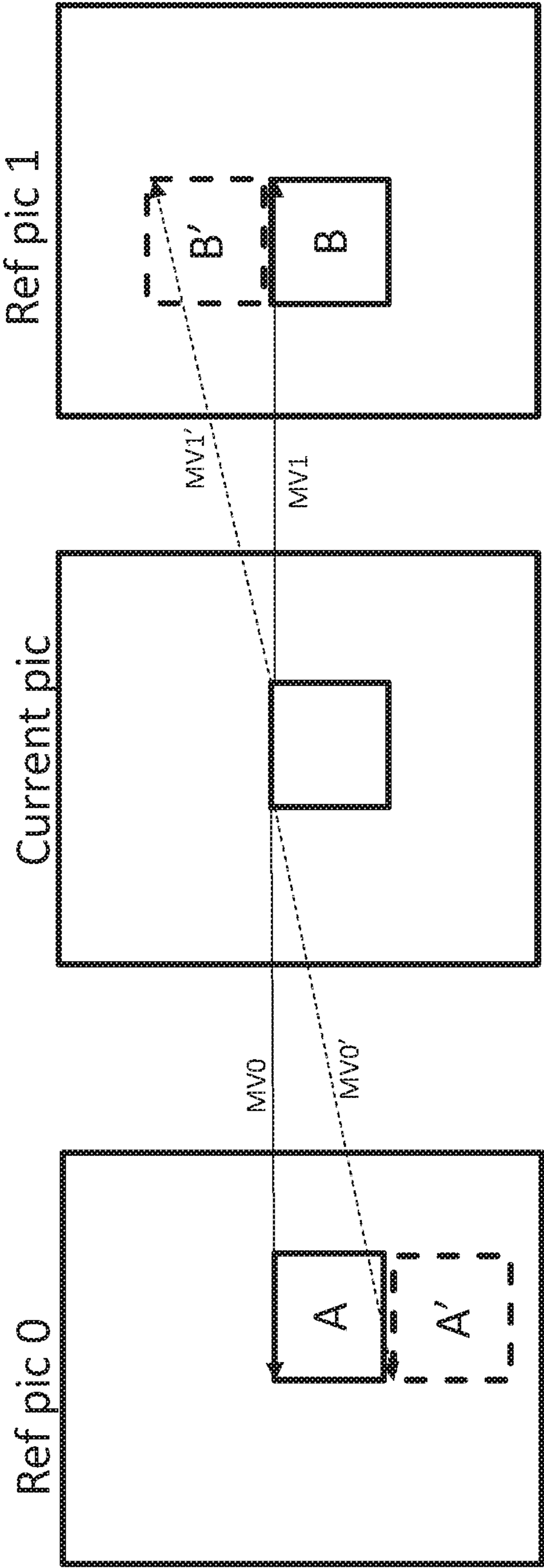


Fig. 3

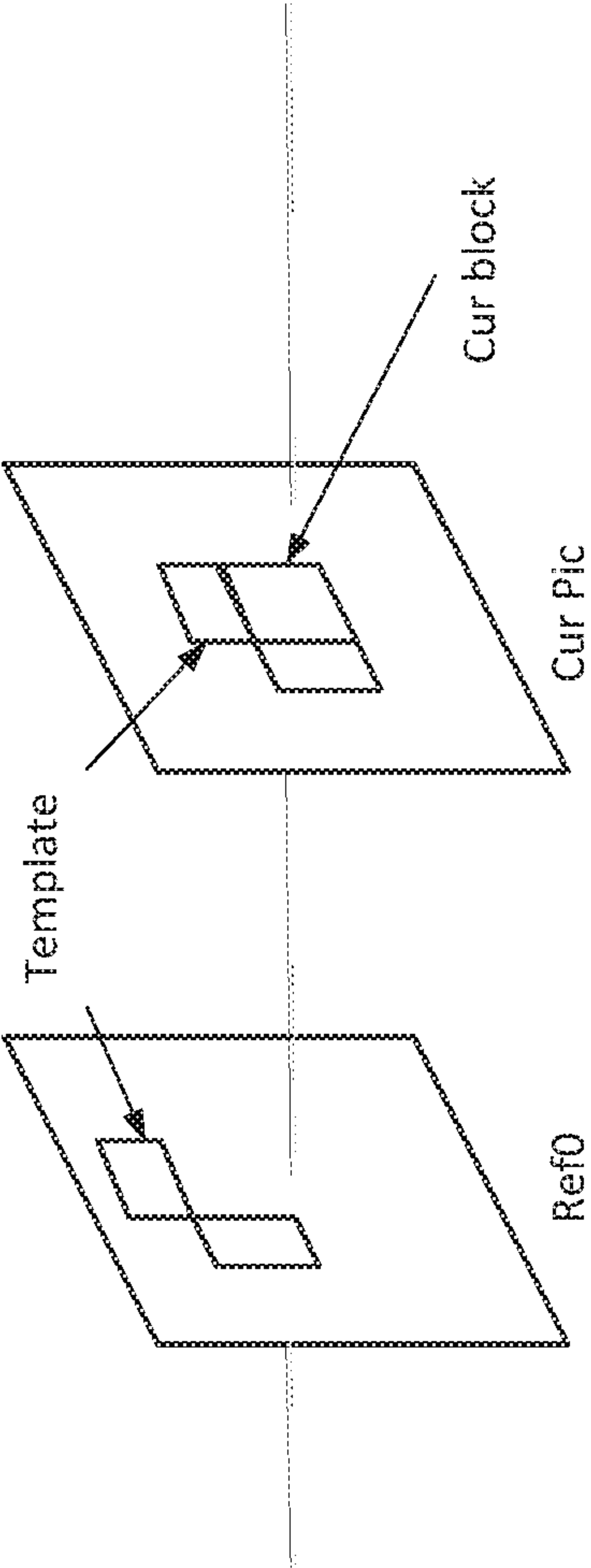


Fig. 4

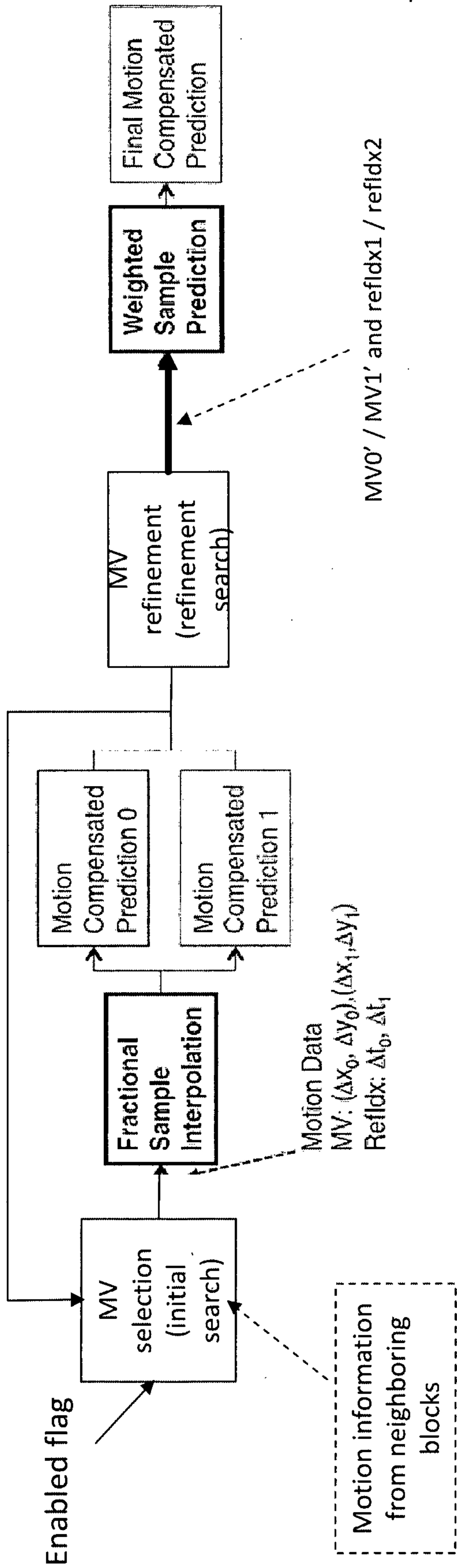


Fig. 5

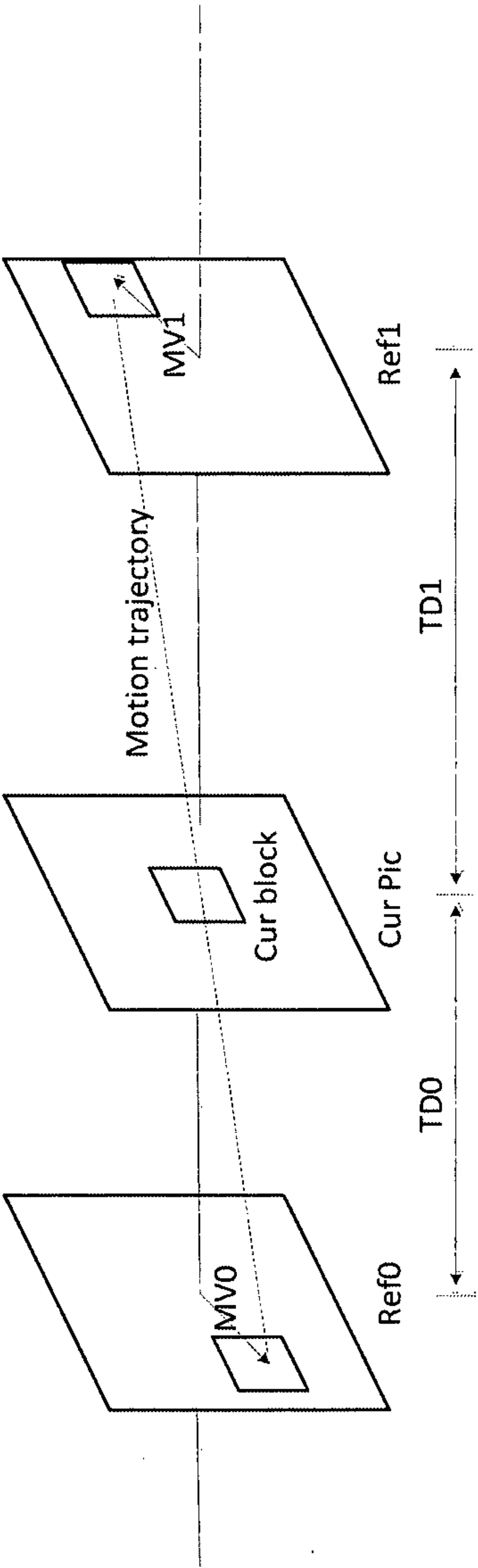


Fig. 6

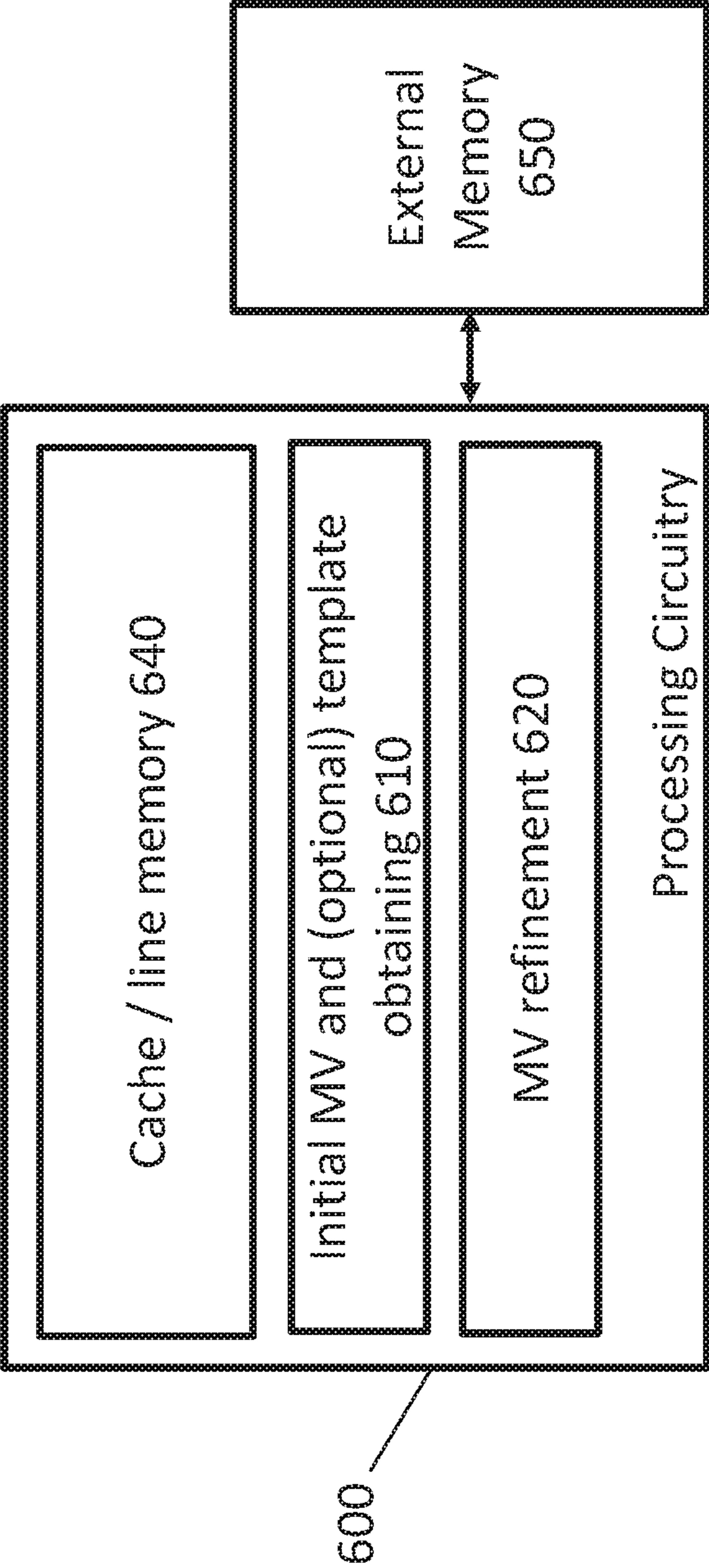


Fig. 7

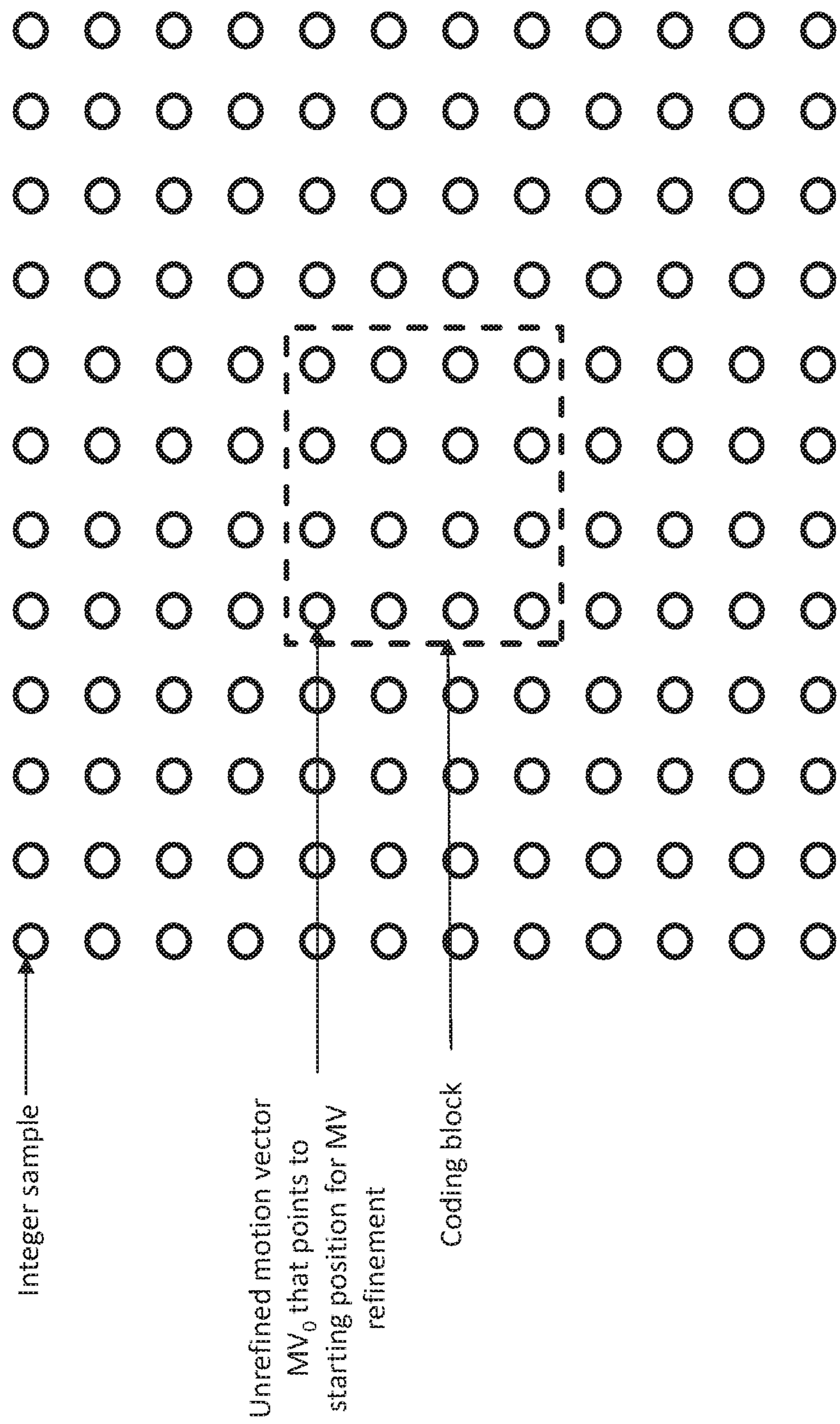


Fig. 8

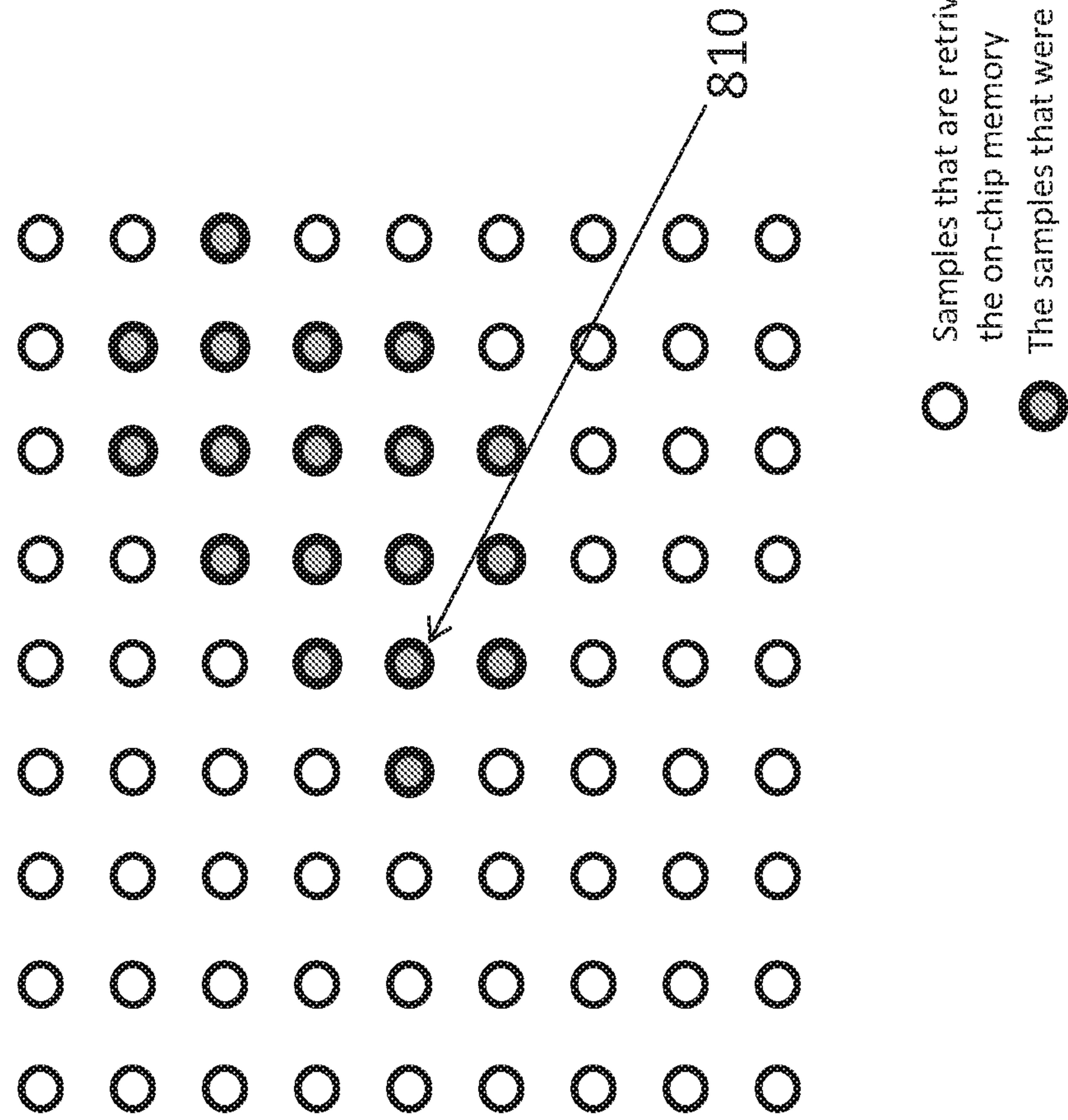


Fig. 9

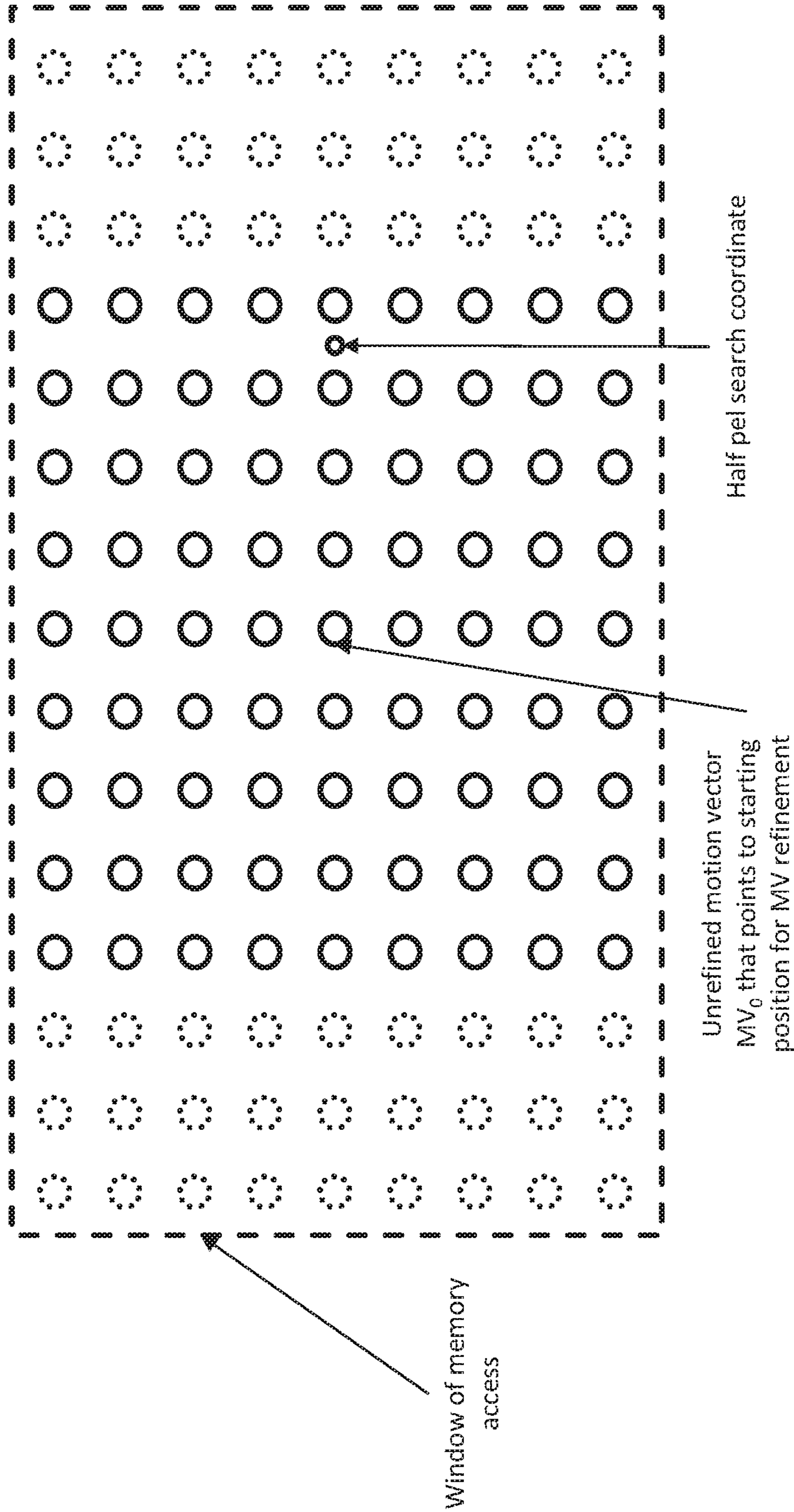


Fig. 10

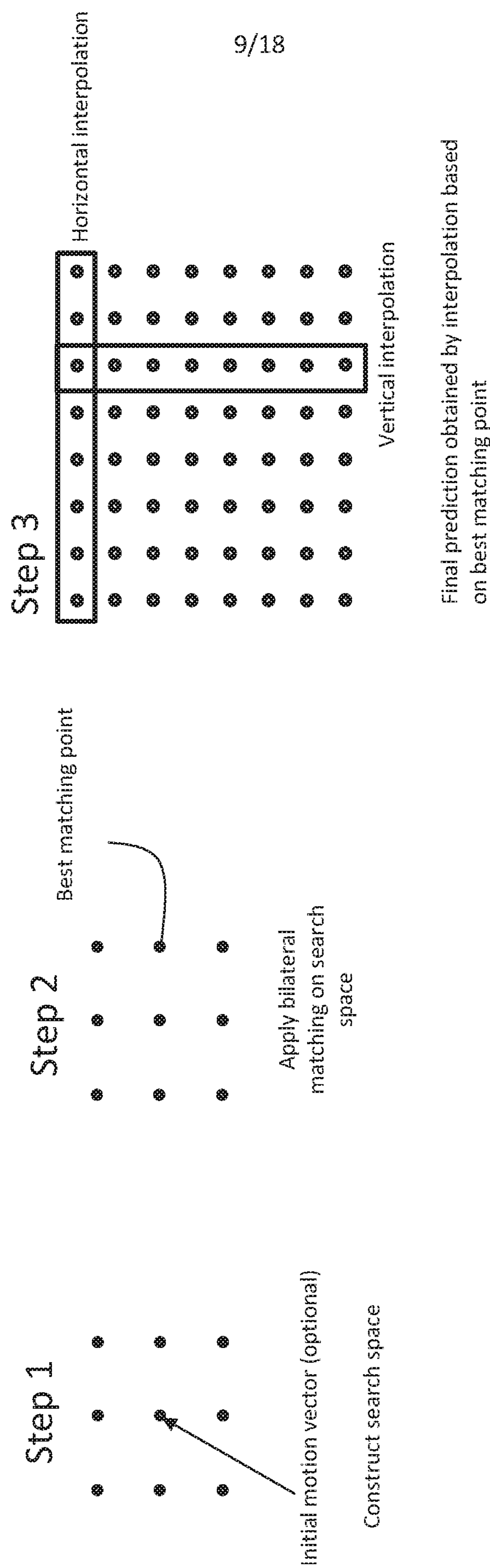


Fig. 11

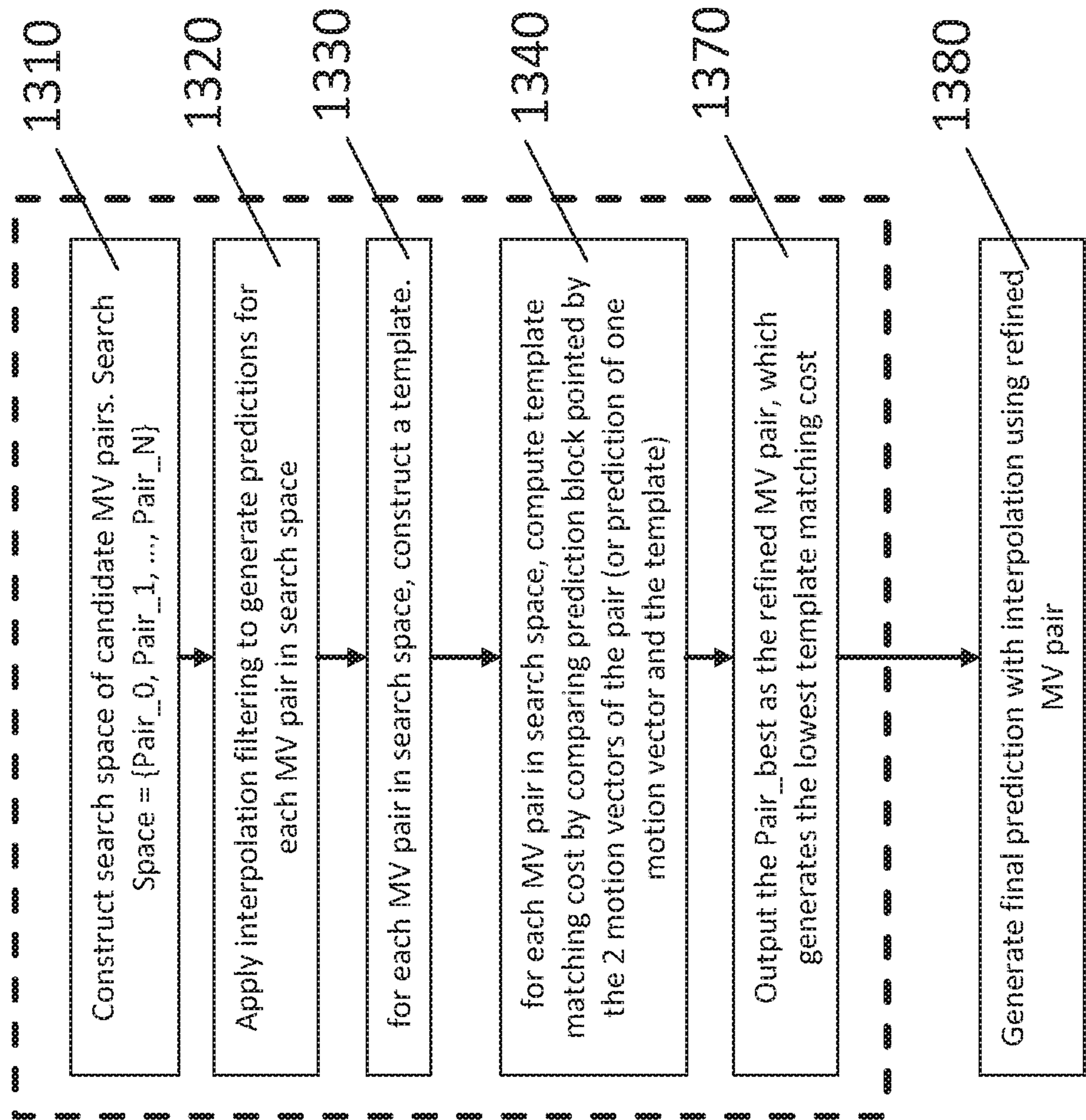
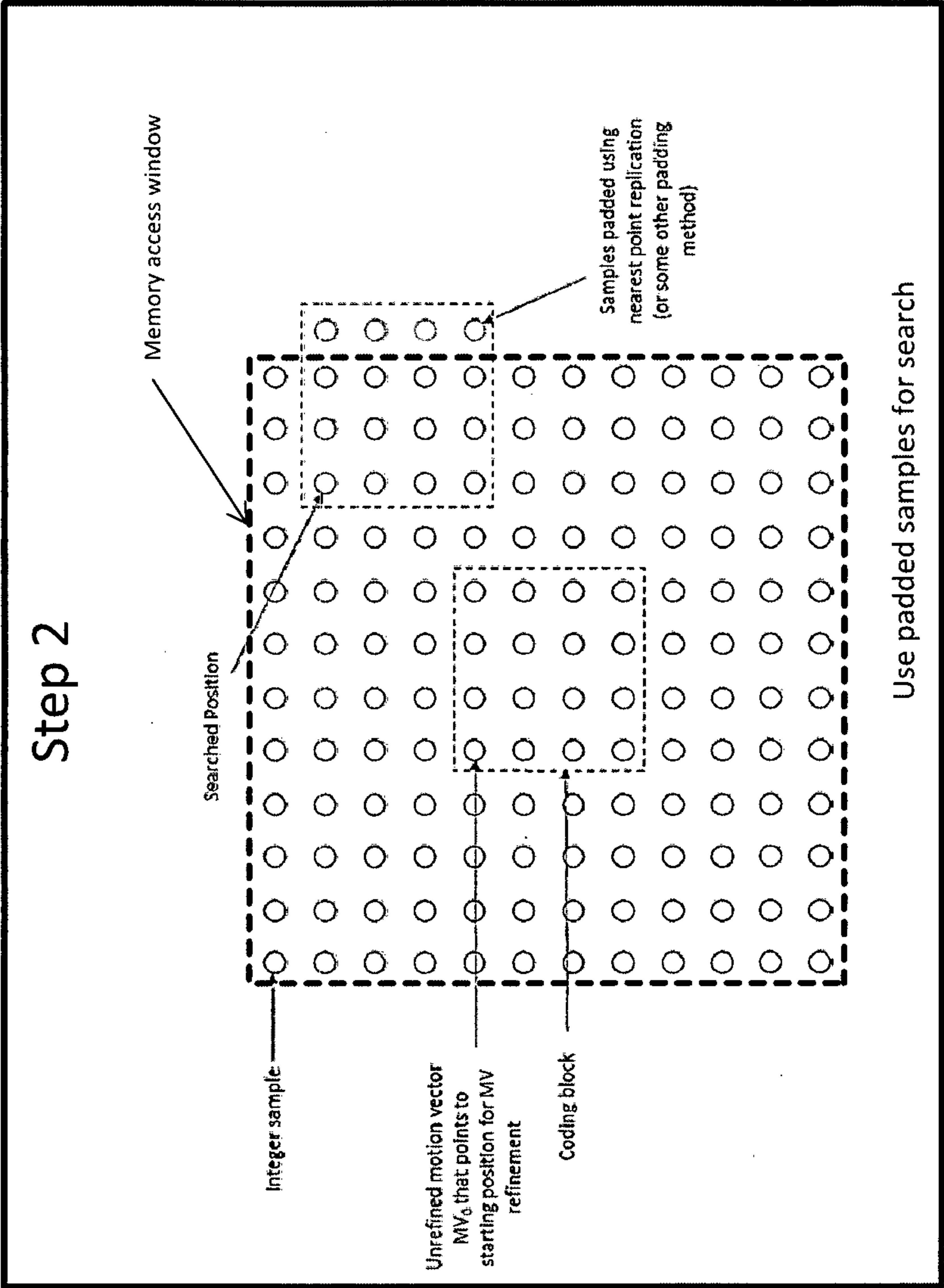
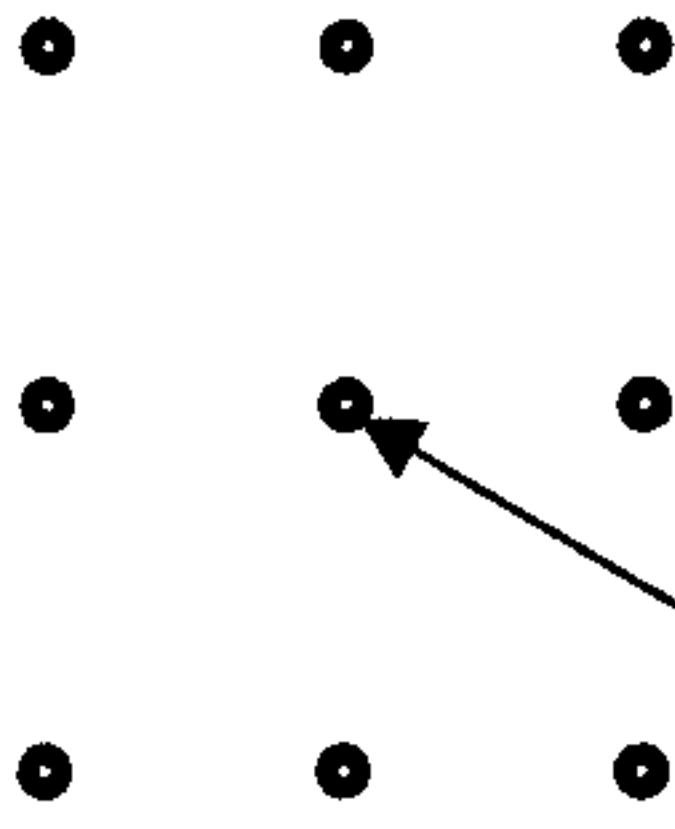


Fig. 12



Step 1



Initial (anchor) motion vector (optional)

Step 3



Best matching point

Apply bilateral matching or template matching

Step 4

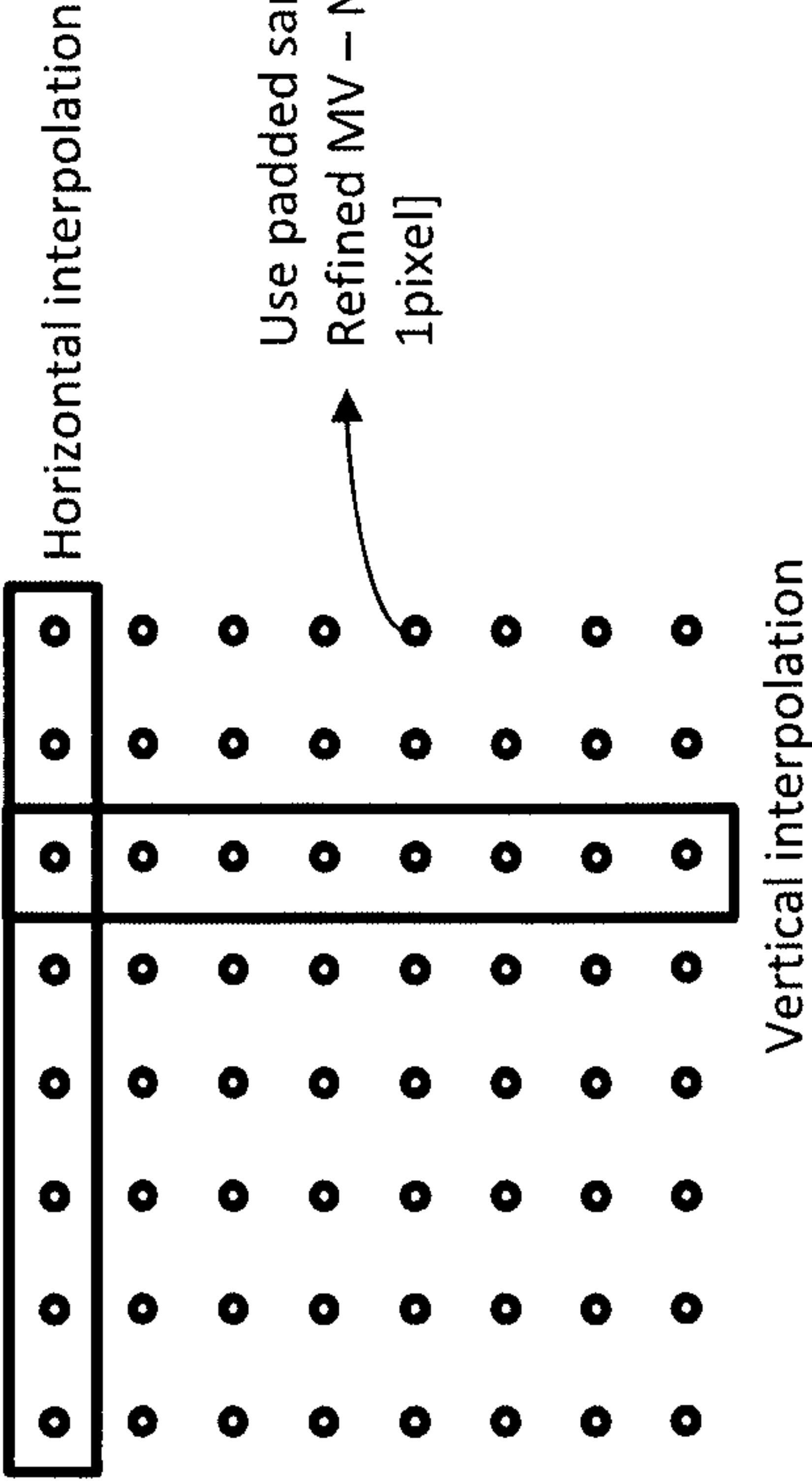


Fig. 13

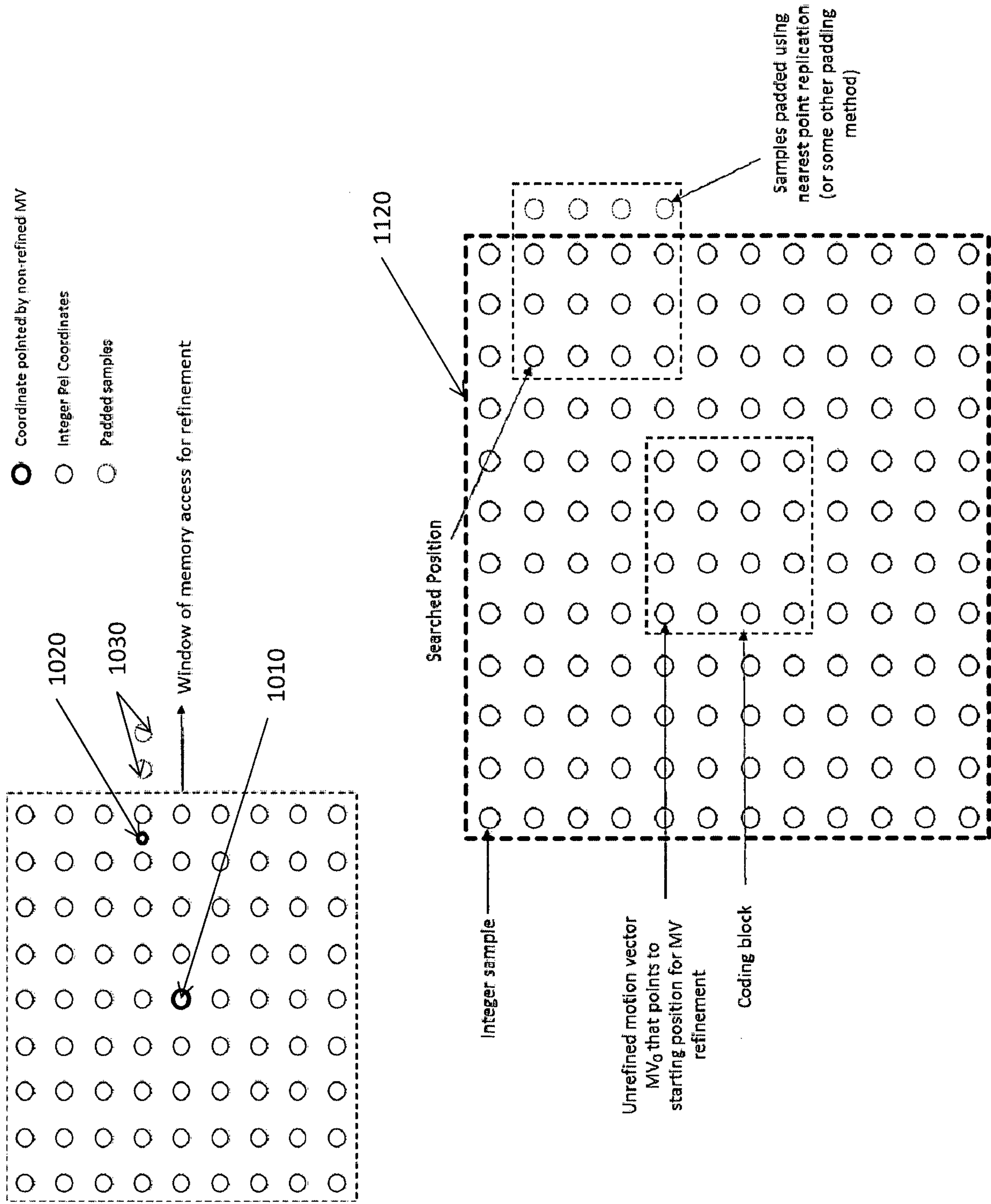


Fig. 14

Fig. 15

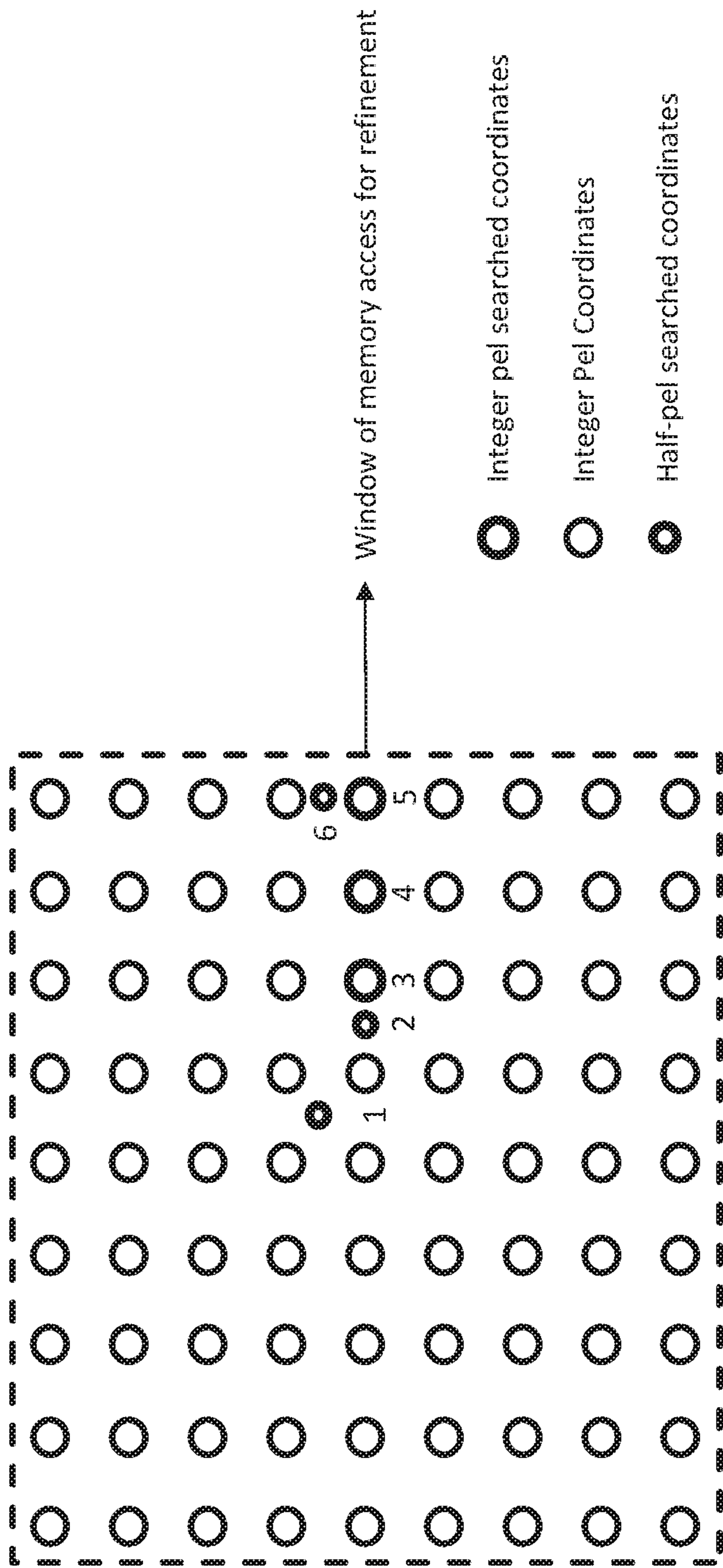


Fig. 16

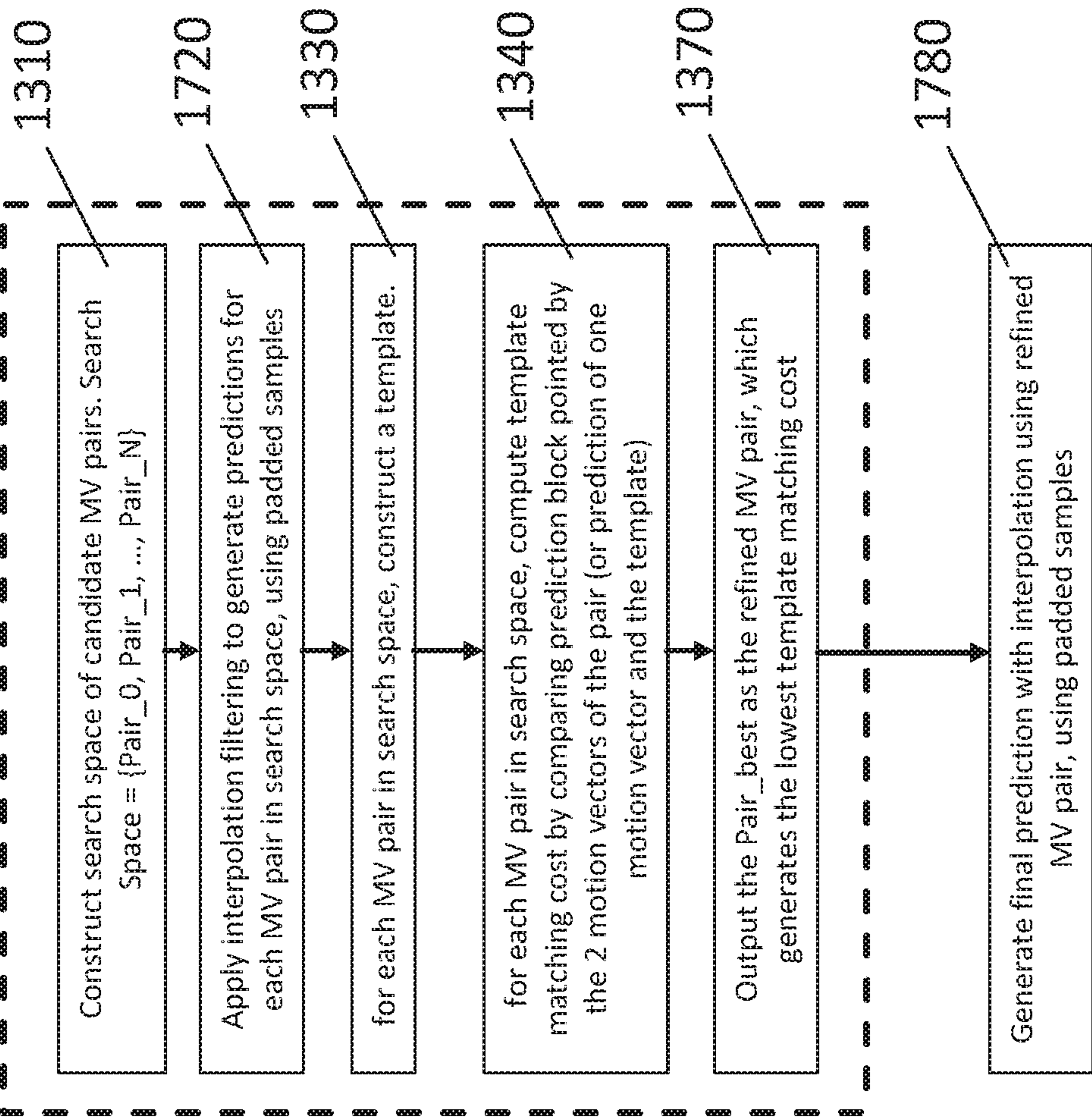


Fig. 17

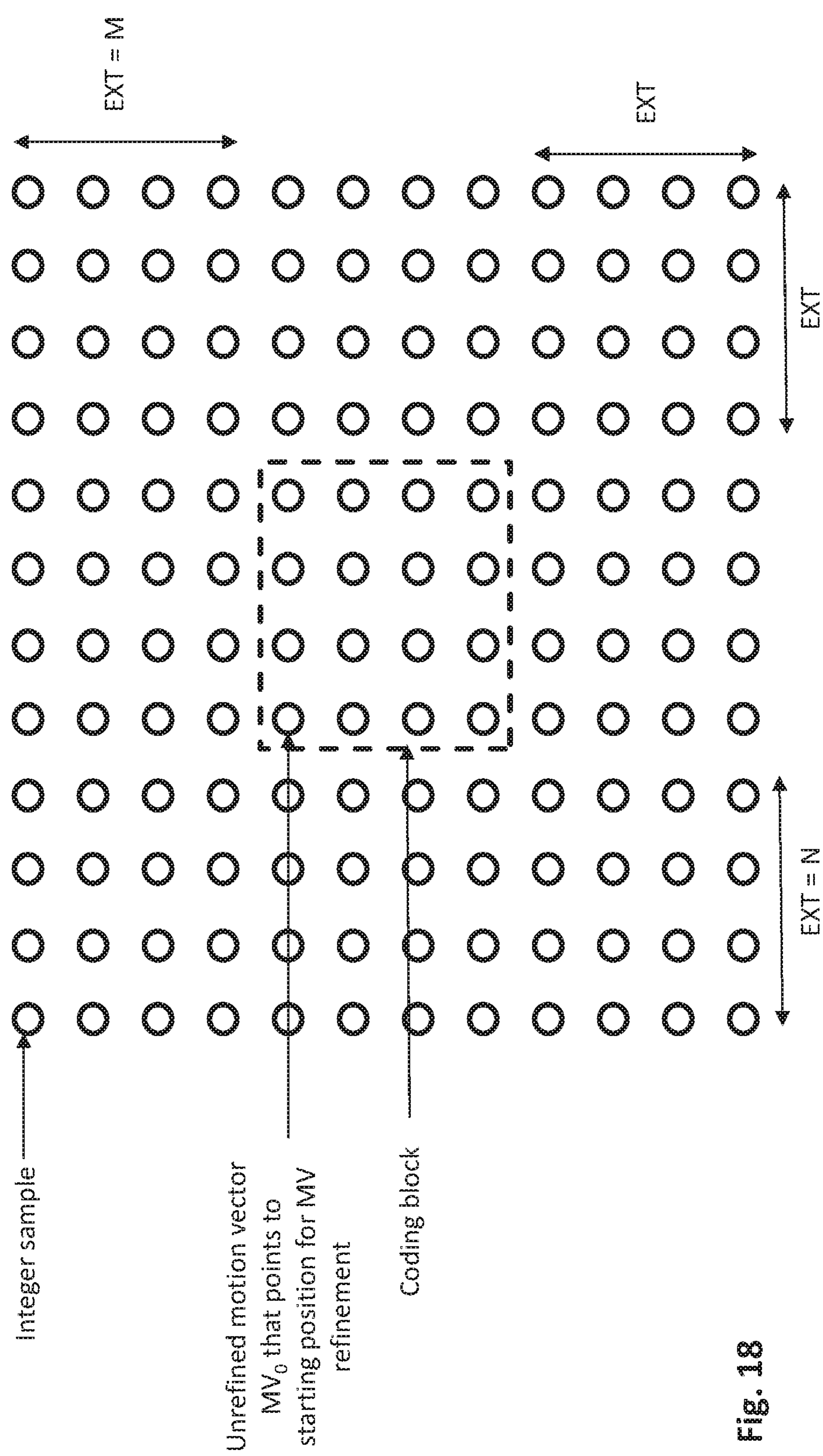


Fig. 18

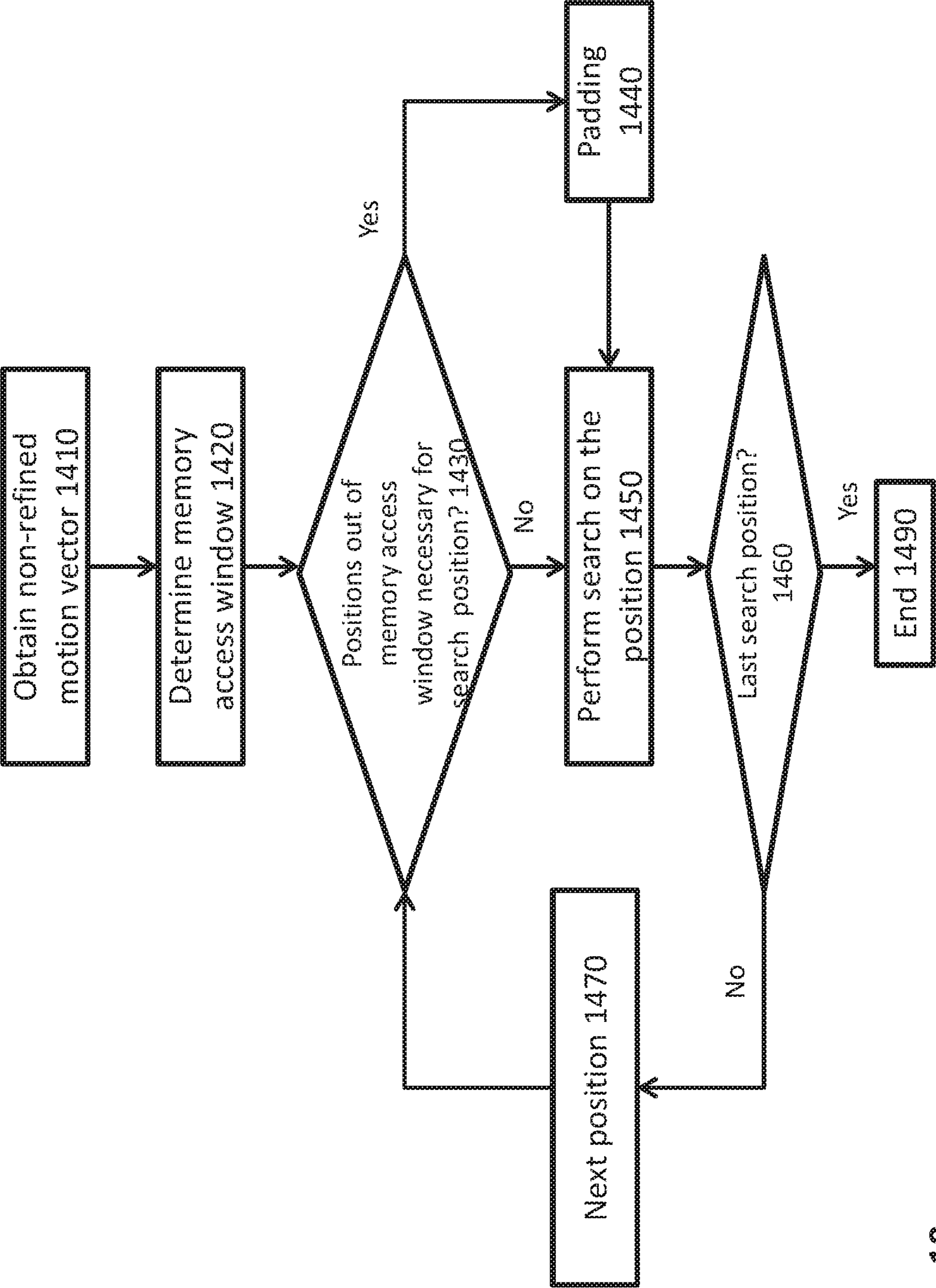


Fig. 19

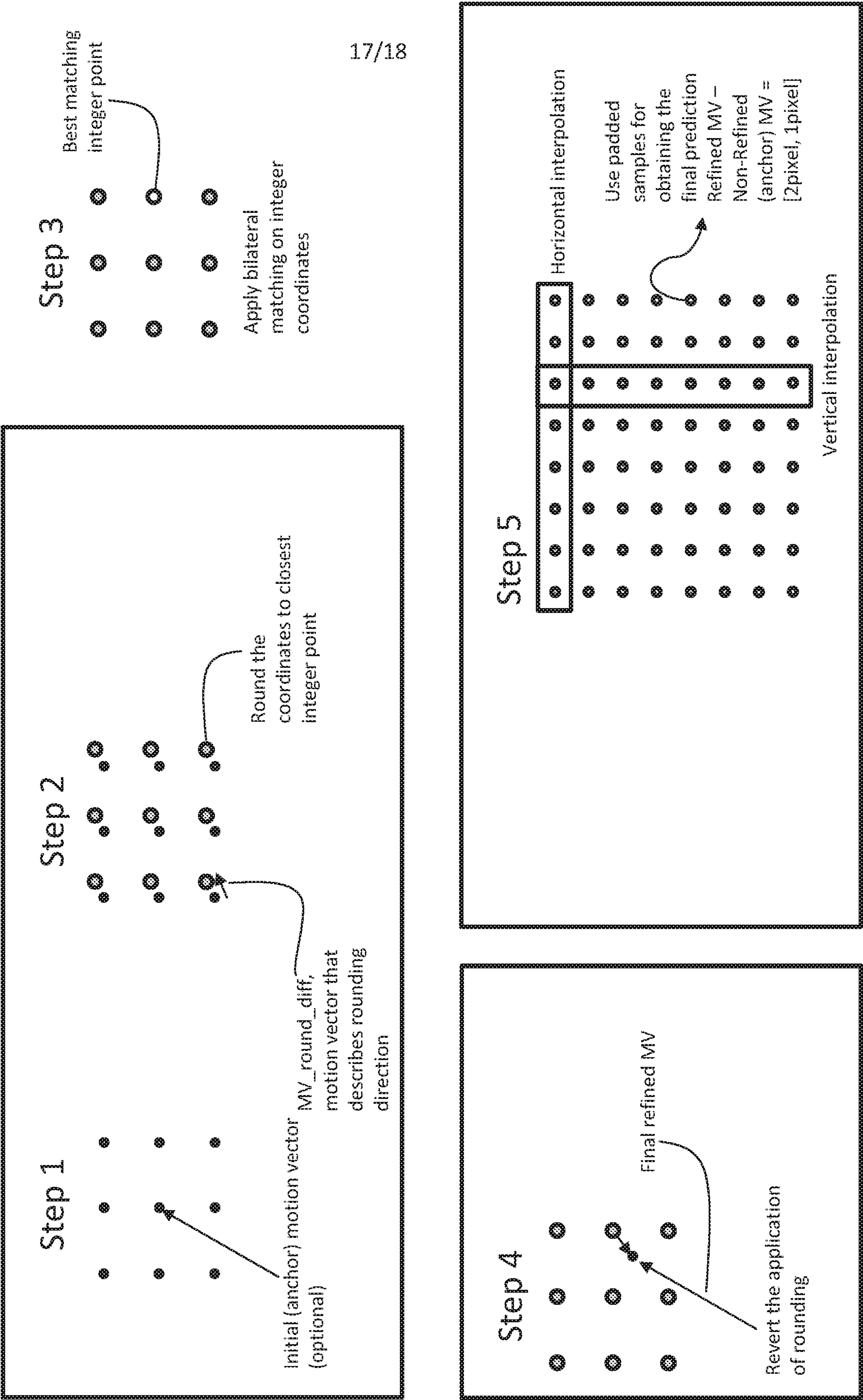


Fig. 20

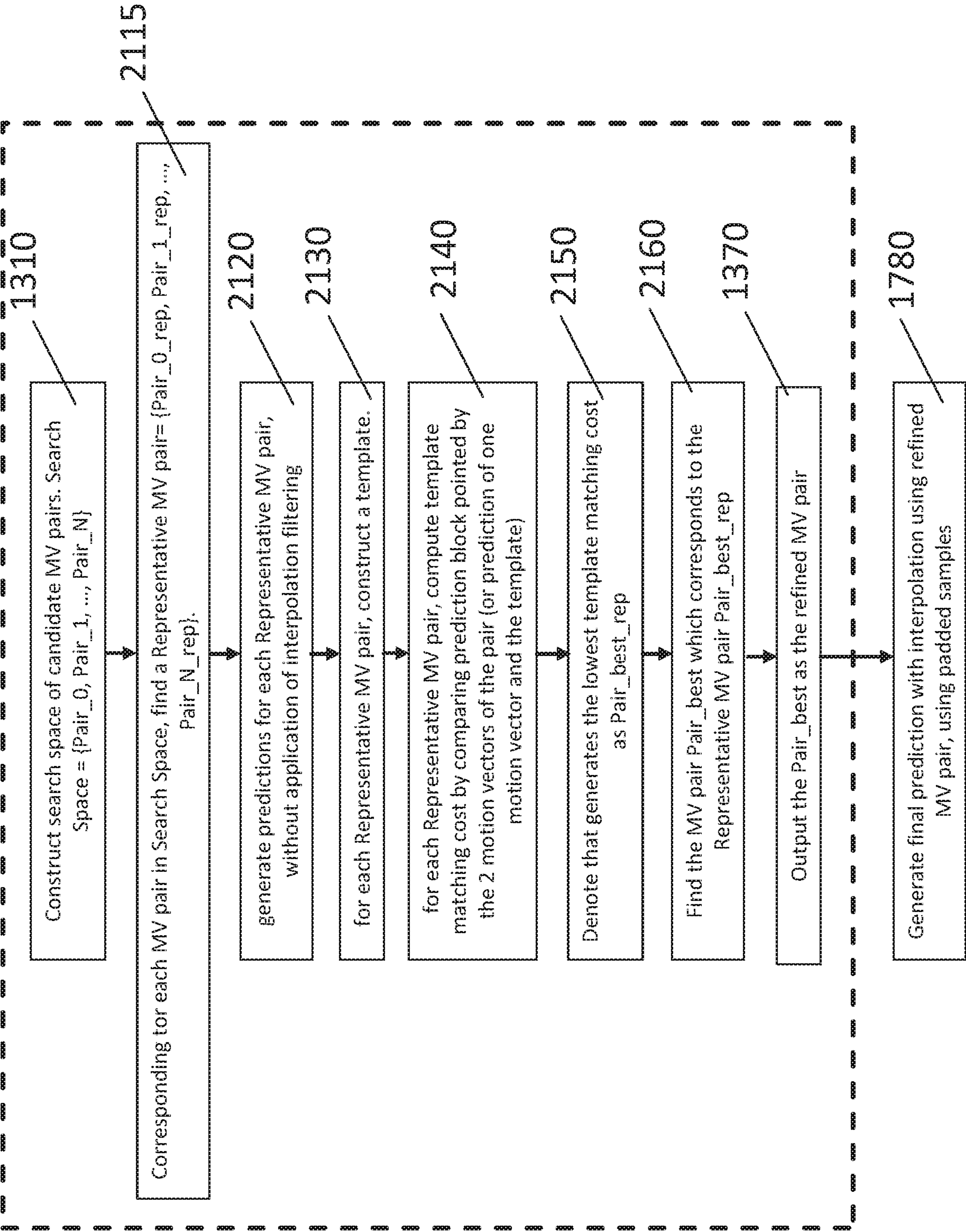


Fig. 21