ABSTRACT

A map generator 100 includes: a collector 65 that collects monitoring information in an environment; and a creator 67 that generates a map 2 for assisting autonomous driving of a mover 1 based on the monitoring information. The creator 67 obtains a hazardous area 3 that is included in the environment and to be avoided based on the monitoring information. The creator 67 generates the map 2 including geographical information 21 and the hazardous area 3.

FIG. 2